#### FURUNO

# Installation Manual DOPPLER SPEED LOG Model DS-85

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## **SAFETY INSTRUCTIONS**

The installer must read the applicable safety instructions before attempting to operate or install the equipment.



Indicates a potentially hazardous situation which, if not avoided, could result in death or serious injury.



Indicates a potentially hazardous situation which, if not avoided, can result in minor or moderate injury.



Warning, Caution



**Prohibitive Action** 



**Mandatory Action** 

## **⚠ WARNING**



#### Do not open the equipment.

This equipment uses high voltage electricity which can shock, burn or cause serious injury. Only qualified personnel can work inside the equipment.



Turn off the power at the mains switchboard before beginning the installation.

Fire, electrical shock or serious injury can result if the power is left on or is applied while the equipment is being installed.



Do not install the equipment where it may get wet from rain or water splash.

Water can cause fire or electrical shock, or damage the equipment.

Careful consideration is required to avoid ingress of water through the transducer tank. The tank shall be strong enough to withstand the water pressure in fully loaded conditions in rough weathers. FURUNO Electric Co., Ltd. is not liable to any loss of ship and personnel which is caused by installation procedures.

## **⚠** CAUTION



Be sure to power each unit with proper voltage.

Connection of an improper power supply can cause fire or damage the equipment.



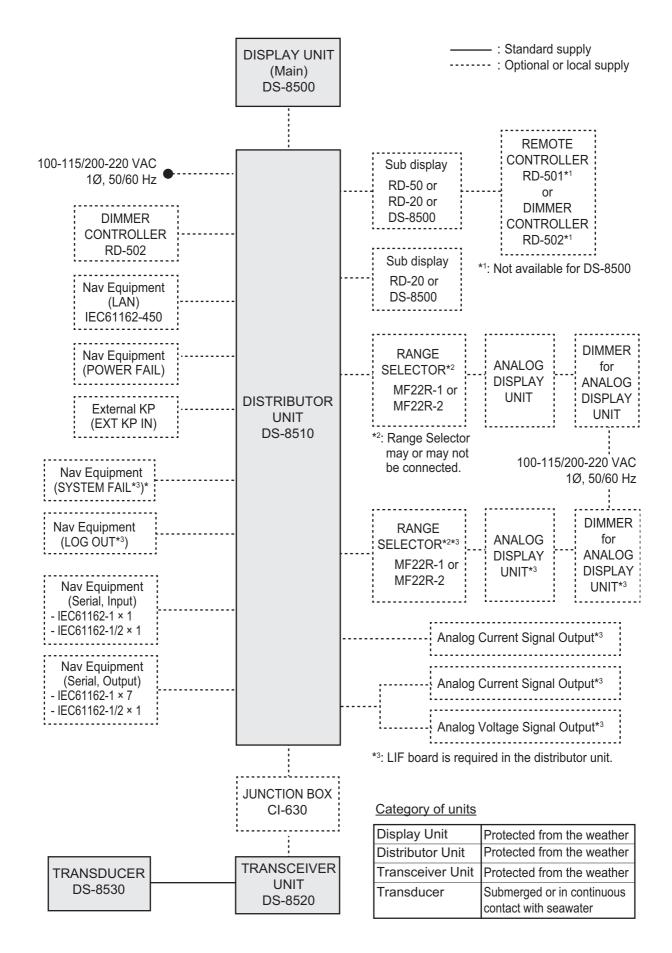
Ground the equipment to prevent electrical shock and mutual interference.



Observe the following safe compass distances to prevent interference to a magnetic compass:

	Standard	Steering
	compass	compass
Display Unit (DS-8500)	0.50 m	0.35 m
Distributor Unit (DS-8510)	2.30 m	1.45 m
Transceiver Unit (DS-8520)	1.95 m	1.25 m
Junction Box (CI-630)	2.00 m	1.15 m

## SYSTEM CONFIGURATION



## **EQUIPMENT LISTS**

## **Standard supply**

Name	Туре	Qty	Remarks
Display Unit	DS-8500	1	
Distributor Unit	DS-8510-1	1	For 100 VDC, no LIF board
	DS-8510-2	1	For 200 VDC, no LIF board
	DS-8510-1-LIF	1	For 100 VDC, w/LIF board
	DS-8510-2-LIF	1	For 200 VDC, w/LIF board
Transceiver Unit	DS-8520	1	
Transducer	DS-8530	1	10/20/30/40 m cable
Installation Materials	CP05-13701	1	For DS-8500
	CP65-01501	1	For DS-8510
	CP65-01401	1	For DS-8520
	CP65-01701	1	For DS-8530
Spare Parts	SP65-01101	1	For DS-8510
	SP65-01001	1	For DS-8520

## **Optional equipment**

Name	Туре		Remarks (*: degree of protection, **: See section 1.5.3)		
Display Unit	DS-8500	For sub displa	For sub display		
Remote Display	RD-50				
	RD-20				
Analog Indicator	FL-200S-1	Flush mount	Scale range: -10	to 30 kn	IP5X*
	FL-200S-1W		Scale range: -10 -2 to 6 kn (double		
	FL-200S-2		Scale range: -10	to 40 kn	
	FL-200S-3		Scale range: -10	to 20 kn	
	SL-200-1W	Bulkhead	Scale range: -10 -2 to 6 kn (double		IP56*
	SL-200-5W		Scale range: 30 to 6 to -2 kn (double	·	
	SL-200-1		Scale range: -10	to 30 kn	
	SL-200-2		Scale range: -10	to 40 kn	
	SL-200-3		Scale range: -10	to 20 kn	
	SL-200-4		Scale range: -10  KTS (double sca		
	SL-200-5		Scale range: 30		
Range Selector	MF-22R-1	Flush mount			
	MF-22R-2	Bulkhead	Bulkhead		
Dimmer	DS-F25	Flush mount	100-110 VAC	For	IP5X*
	DS-FE25		200-220 VAC	analog in-	
	DS-S25	Bulkhead	100-110 VAC	dicator	IP56*
	DS-SE25		200-220 VAC	7	
Dimmer Controller	RD-502	For remote operation			

		Remarks
Name	Туре	(*: degree of protection,
Name	rype	**: See section 1.5.3)
Remote	RD-501	For RD-50, RD-20
Controller	ו ווס-טא	FOI RD-50, RD-20
•	OL 020	
Junction Box	CI-630	
Transducer Tank	DS-781	Projection type, replaceable on deck
	DS-784	Flush type, replaceable on deck
	DS-786	Gate valve type, replaceable on sea
	DS-854	Ball valve type, replaceable on sea
Front Fixing Panel	OP24-35	For DS-8500
Waterproof Kit	OP05-139	For waterproof of DS-8500
Replacement Kit	OP05-140	For retrofit of display unit from DS-800 to DS-8500
F_Mount	OP05-141	For DS-8500
Cushion Kit		
Cable Protection	OP05-147	For Z-AWG25X4P-SB L050/100 (for DS-8500)
Kit		
Cable Assembly	OP05-146-1	For DS-8500,
		w/Z-AWG25X4P-SB L050 (5 m), gasket and cable tie.
	OP05-146-2	For DS-8500,
		w/Z-AWG25X4P-SB L100 (10 m), gasket and cable tie.
LIF Board Kit	OP65-3	For analog output
SC Lock	OP65-4	For TTYCSLA-4 cable or unspecified cable (applicable
		diameter φ14.5 to 16.5)
Installation	CP24-02900	LAN cable 10 m
Materials	CP24-02910	LAN cable 20 m
	CP24-02920	LAN cable 30 m
Spare Parts	SP65-01000 (BOX)	For DS-8510, DS-8520

## **NOTICE**

Do not apply paint, anti-corrosive sealant or contact spray to coating or plastic parts of the equipment.

Those items contain organic solvents that can damage coating and plastic parts, especially plastic connectors.

## 1.1 Display Unit

The display unit (main or sub) can be installed on a desktop, overhead, on the bulk-head or flush mounted in a console or panel.

#### 1.1.1 Installation considerations

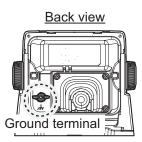
When selecting a mounting location for the display unit, keep the following in mind:

- · Keep the unit out of direct sunlight.
- The temperature and humidity of the mounting location should be moderate and stable.
- Locate the unit away from exhaust pipes and vents.
- The mounting location should be well ventilated.
- Mount the unit where shock and vibration are minimal.
- Keep the unit away from electromagnetic field-generating equipment such as motors and generators.
- For maintenance and checking purposes, leave sufficient space at the sides and rear of the unit and leave slack in cables. Refer to the outline drawings at the back of this manual.
- A magnetic compass will be affected if the display unit is too close to it. Observe the compass safe distances to prevent disturbance to the magnetic compass. Refer to the compass safety distances of the units on "SAFETY INSTRUCTIONS" page.
- For flush mounting in a panel, the mounting surface must be flat. Do not install the unit on an uneven surface.
- To avoid damage to the cabling when mounting the display unit, make sure the cabling is not excessively bent.

**Note:** The cabling to the display unit should be completed before mounting the unit. See section 2.3.2.

#### Grounding

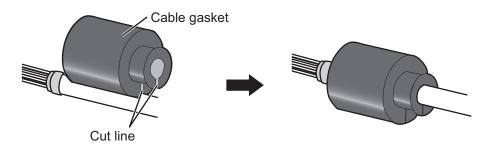
Ground the unit with the supplied ground wire referring to the figure to the right.



# 1.1.2 How to fit the cable gasket (When using the OP05-146-1 or OP05-146-2)

When using the cable assembly OP05-146-1 (5 m) or OP05-146-2 (10 m), its water-proofing capability can be increased by attaching the cable gasket attached to the cable assembly.

The cable gasket needs to be attached to the cable as shown below. The cut line must face downward to prevent the water intrusion to the unit.



Regarding how to connect the cabling to the Display and how to fit the cable gasket to the cable clamp, referring to section 2.3.2.

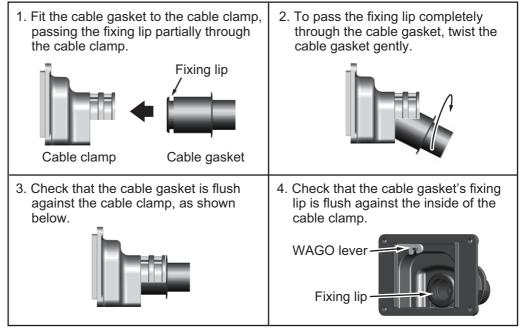
#### 1.1.3 How to fit the optional waterproofing kit (OP05-139)

The optional waterproofing kit (OP05-139) must be fitted at the same time as the cabling is connected to the display unit.

The waterproofing kit (OP05-139) contains the following items:

- Cover gasket (Type: 05-109-3504) ×1
- Cable gasket (Type: 05-109-3503) ×1
- 1. Unfasten the four screws on the rear cable clamp, then remove the cable clamp to reveal the WAGO connector.

2. Fit the cable gasket to the cable clamp, referring to the figure below.

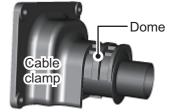


- 3. Pass the cabling through the cable gasket and cable clamp. **Note:** To maintain the IPX5 waterproof rating, the cable must be TTYCSLA-4 (or equivalent) with a diameter of  $\phi$ 14.4±0.4 mm.
- 4. Fit the cover gasket to the rear of the display unit. Make sure the cover gasket is placed inside the groove indicated in the figure below.



- 5. Connect the cabling to the display unit, referring to section 2.3.2.
- 6. Slide the cable clamp along the cable until the clamp is flush against the rear of the display unit.

**Note:** The cable clamp must be oriented with the dome-side up, to prevent water intrusion.



- 7. Fasten the four screws removed at step 1.
- 8. Secure the cabling to the cable clamp with cable ties (local supply) referring to the figure in section 2.3.2.

#### 1.1.4 How to install the display unit on a desktop or overhead

The display unit is shipped with the hanger.

- 1. Place the display unit on a firm, flat surface, then unfasten the two knobs on either side of the display unit to separate the display unit and hanger.
- 2. Drill four holes for the self-tapping screws ( $\phi 5 \times 20$ ) at the installation location.

3. Secure the hanger to the desktop or overhead with four self-tapping screws ( $\phi$ 5×20, installation material). The hanger should be oriented with the insertion slots facing forward. For mounting dimensions and required clearance, see the outline drawing at the back of this manual.



- 4. Referring to section 2.3.2, connect the cabling to the display unit.
- 5. Fit the display unit to the hanger and tighten the bolts on either side evenly. Adjust the angle of the display unit so that the screen can be viewed clearly.

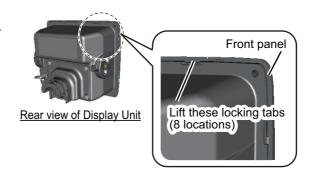
#### 1.1.5 How to flush mount the display unit

There are two methods for flush mounting the display unit, flush mounting the display unit directly to the installation location or with using the optional front fixing panel kit.

**Note:** For flush mounting in a panel, the mounting surface must be flat. Do not install the unit on an uneven surface.

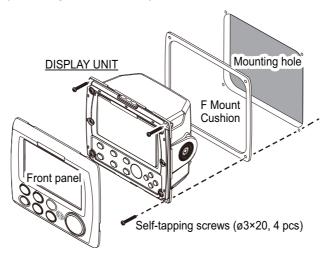
#### Flush mounting the display unit (unit only)

- 1. Cut a hole in the installation location, using the template at the back of this manual.
- 2. Drill four holes for the self-tapping screws ( $\phi 3 \times 20$ ).
- 3. Place the display unit on a firm, flat surface, then unfasten the two knobs on either side of the display unit to separate the display unit and a hanger. The hanger can be disposed.
- Gently lift the locking tabs at the rear of the front panel, then the remove the front panel. Be careful not to damage the locking tabs or the front panel.



5. Fit the supplied F Mount Cushion (20-032-1064) to the rear of the display unit or to the installation hole.

6. Run the cabling through the cutout, then, referring to section 2.3.2, connect the necessary cabling to the display unit.



- 7. Referring to the figure above, fit the display unit to the cutout, then use the supplied self-tapping screws ( $\phi 3 \times 20$ ) to secure the display unit to the flush mount panel.
- 8. Re-attach the front panel detached at step 4.

#### Flush mounting the display unit (with optional front fixing panel kit)

Use the optional kit (OP24-35), referring to the outline drawings at the back of this manual and the installation instructions (C42-01310) included with the optional kit.

#### 1.2 Distributor Unit

This unit can be installed on a bulkhead or on the floor. Install it referring to the outline drawing at the back of this manual for dimensions.

#### 1.2.1 Installation consideration

When selecting a mounting location for the distributor unit, keep the following in mind:

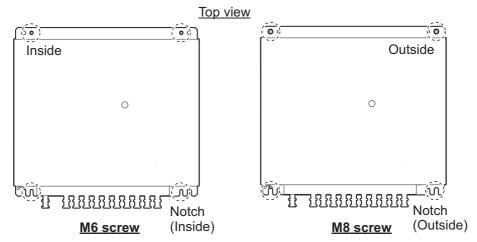
- Keep the distributor unit out of direct sunlight.
- The temperature and humidity should be moderate and stable.
- Locate the unit away from exhaust pipes and vents.
- The mounting location should be well ventilated.
- · Mount the unit where shock and vibration are minimal.
- Keep the unit away from electromagnetic field generating equipment such as motors and generators.
- For maintenance and checking purposes, leave sufficient space at the sides and rear of the unit and leave slack in cables. Refer to the outline drawing.
- A magnetic compass will be affected if the unit is placed too close to it. Observe the following compass safe distances to prevent disturbance to the magnetic compass, referring to "SAFETY INSTRUCTIONS" on page i.
- Avoid floor mounting the distributor unit in locations where there is water splash.
   Keep the cable entry away from water spray and splash. For a bulkhead installation, install the unit so that the cable entrance must face downward.

#### 1.2.2 Mounting

Use M6 (supplied) or M8 (local supplied) screws. Note that the size of mounting holes etc. differ according to the screw size.

**Note:** For bulkhead installations, the cable entry must face downward.

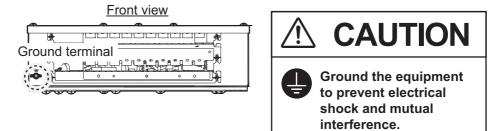
- 1. Make four pilot holes, referring to the outline drawing at the back of this manual.
- 2. Fit two self-tapping screws at the location for the bottom fixing holes. Leave approximately 5 mm of thread exposed. The mounting holes and notches differ according to the mounting screws.



- 3. Place the distributor unit on the two screws and fasten two self-tapping screws to the top fixing holes.
- 4. Fasten the two self-tapping screws at the bottom fixing holes tightly.

#### Grounding

Ground the unit with the supplied ground wire referring to the figure to the right.



### 1.3 Transceiver Unit

This unit can be installed on a bulkhead.

#### 1.3.1 Installation considerations

Keep in mind the following points when selecting a location.

 Locate the transceiver unit away from heat sources to prevent heat build up inside the cabinet.

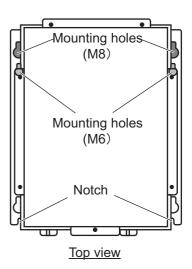
- Select a location where the vibration is minimal. When installing the transceiver unit in a location with a lot of vibration such as a bow thruster room, use a vibration isolator (shipyard supply).
- · Locate the equipment away from places subject to water splash and rain.
- Leave sufficient space at the sides and rear of the unit to facilitate maintenance.
- A magnetic compass will be affected if the processor unit is placed too close to the magnetic compass. Observe the compass safe distances in the "SAFETY INSTRUCTIONS" on page i to prevent interference to a magnetic compass.
- · For the mounting direction, the cable entry must face downward.
- Referring to the weight of this unit, indicated in the outline drawings at the back of this manual, reinforce the mounting location if necessary.

#### 1.3.2 How to install the transceiver unit

Use M6 (supplied) or M8 (local supplied) screws. Note that the size of mounting holes differ according to the screw size.

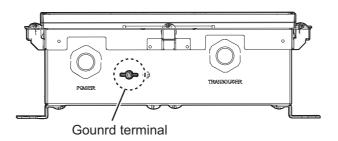
Note: For bulkhead installations, the cable entry must face downward.

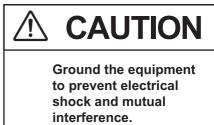
- 1. Make four pilot holes, referring to the outline drawing at the back of this manual.
- Fit two self-tapping screws at the location for the bottom fixing holes. Leave approximately 5 mm of thread exposed. The mounting holes and notches differ according to the mounting screws.
- 3. Place the transceiver unit on the two screws and fasten two self-tapping screws to the top fixing holes.
- 4. Fasten the two self-tapping screws at the bottom fixing holes tightly.



#### **Grounding**

Ground the unit with the supplied ground wire referring to the figure below.





#### 1.4 Transducer

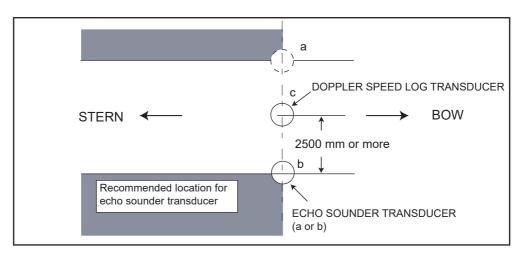
The performance of this equipment is directly dependent on the installation of the transducer. The installation of the transducer and the tank should be accomplished by a dockyard referring to the installation drawings at the back of this manual.

Also, the transducer DS-820 which is used for DS-80 is available. For installation of DS-820, see the installation manual (IME-72470) for DS-80.

#### 1.4.1 Installation considerations

To decide the location of the transducer, the following points should be taken into account.

 Locate the transducer DS-8530 at least 2.5 m from the transducer of an echo sounder.



Transducer, mounting location

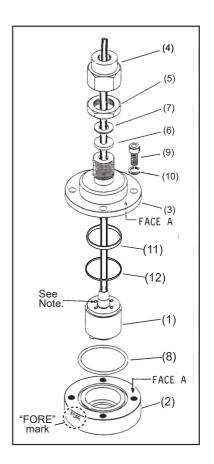
- Separate as far as possible from air bubble sources; e.g., side thruster and water disposal pipes.
- The Doppler speed log emits ultrasonic waves diagonally forward and backward, so the transducer should not be located on the same line of the Doppler speed log in the bow-stern direction.
- Install in close proximity to the keel, for uniform water flow.
   The closer the ship is to the keel line, the more the water flow at the bottom of the vessel creates an arrhythmic flow parallel to the keel, thus reducing errors in speed measurement.
- Generally, best performance is obtained by mounting on the bow; the stern side is influenced more easily by air bubbles and propeller cavitation.
- Never apply ordinary ship bottom paint to the transducer face. Whenever the ship
  is dry docked, the transducer face should be cleaned, removing marine life and foreign material.
- For DS-784 (flush type), DS-786 (gate valve type) or DS-854 (ball valve type) transducer tank, remove the hose clamp of the transducer.
   For DS-781 (projection type), the hose clamp is required even if it is removed temporarily under installation.
- Do not remove the metal pipe on the outside of the transducer. Please mount the transducer with the metal pipe attached to prevent reverberation.

 Refer to the procedure below for the location where the supplied liquid gasket TB1121 is applied. For DS-781 (projection type) bottom tank, there is no place to apply the liquid gasket.

#### 1.4.2 How to install the transducer

#### **DS-784 (Mounting of Flush Type Seachest)**

- Loosen lock nut (5) with a wrench (hex. size: 50 mm) and take off cap nut (4) from the flange (3) together with gasket (6) and flat washer (7).
   Note: It is necessary to remove the cap nut (4) completely from the cable.
- 2. Unscrew hex. socket head bolts (9) (M12×25, 4 pcs.) and spring washers (10) with a socket screw wrench (local supply, size: 10 mm). Separate the hull flange (2) from the flange (3). Handle O-ring (8) carefully to avoid scratching.
- 3. Align the "FORE" mark on the side of the hull flange (2) to face the fore direction, parallel with the fore-aft line of the ship (a 1 degree error margin is allowed), then weld the hull flange (2) to the hull plate.
- 4. Finish the outside hull plate with a grinder to ensure smooth water-flow.

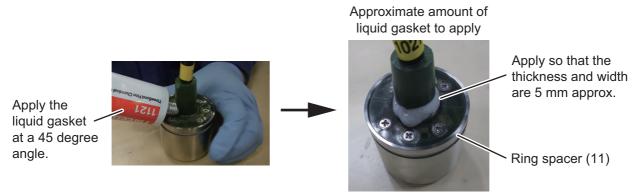


5. Remove the Jubilee clip located at the base of the transducer cable (see the figure below).



6. Attach the ring spacer (11) to the transducer (1).

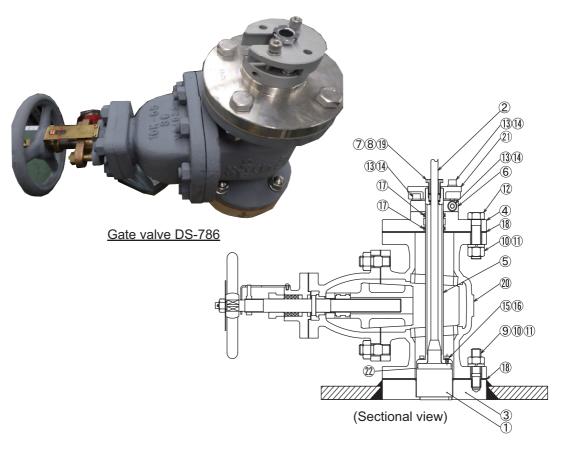
7. Apply the liquid gasket TB1121 to the top of the transducer (1) for waterproofing (see the figure below).



- 8. Apply "Kinoruster (Anti-crevice corrosive sealant)" to face A of the hull flange (2), O-ring groove on the hull flange (2), O-ring (8) and face A of the flange (3).
- 9. Fit O-ring (8) onto the O-ring groove.
- 10. Place transducer (1) into the hull flange (2) so that the alignment projection on the transducer face fits into the hollow side on the full flange (2).
- 11. Clean the full flange face with a clean cloth and fit the flange (3) on the full flange.
- 12. Tighten hex. socket bolts (9) and spring washers (10) with a socket screw wrench.
- 13. Fit the gasket (6) and flat washer (7) over the transducer flange and tighten cap nut (4) securely with a wrench (hex. size: 50 mm). Screw lock nut (5).
- 14. When running the transducer cable inside a conduit pipe, screw the pipe onto the cap nut (PS3/4) for watertightness.

**Note:** Never remove the four flat head screws on the transducer. These are sealing screws and are required to maintain watertightness.

#### **DS-786 (Mounting of Gate Valve Type Seachest)**



**Note:** The gate valve requires service space of 700 mm. For details, see the installation drawing at the back of this manual.

- 1. Unfasten M16 nut (3) and spring washer (11) from the assembled gate valve to remove the following five items.
  - 1) Gate valve (20)
  - 2) flange (3)
  - 3) Gasket 1 (18)
  - 4) Gasket 2 (18)
  - 5) Shaft assy.
- 2. Set the flange (3) to the mounting location.

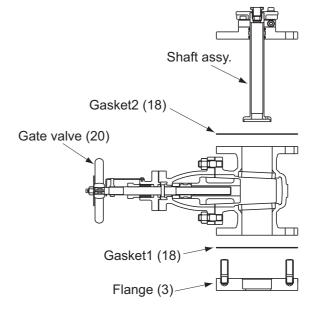
The "FORE-AFT" line on the spacer must be parallel with the ship's fore and aft line (within 1°). For horizontal direction, the

1°). For horizontal direction, the

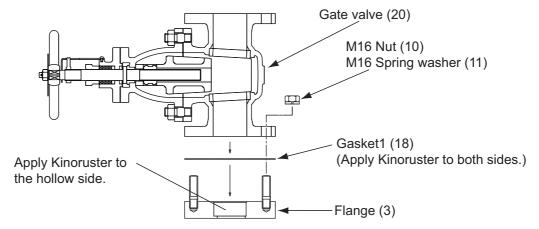
bottom of the spacer must be parallel with the ship's draft.

**Note:** Handle the top side of the flange (3) carefully to preserve the waterproofing.

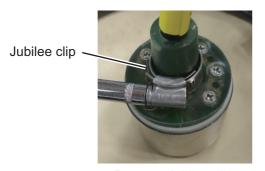
- 3. Weld the flange (3) to the ship's hull. The welding and doubling methods are left up to the shipyard.
- 4. Apply Kinoruster (supplied) to both sides of the gasket1 (18), and fit it to the flange (3).



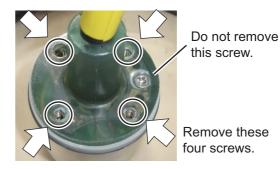
- 5. Apply Kinoruster (supplied) to the hollow side of the flange (3).
- 6. Clean the top and bottom of the gate valve (20), and put it on the gasket1 (18) set on the flange (3).
- 7. Fasten M16 nut (10) and M16 spring washer (11) loosely to the stud bolt of the flange (3).
- 8. Paint the gate valve (20) and the flange (3) the same color as ship's body. Paint only gray-colored areas; for other parts, seal with masking tape. Remove the tape when the paint dries.



- 9. Unfasten two sets of hex. bolt (13) and M8 spring washer (14) from the top side of the shaft to remove the fixing plate (21).
- 10. Remove the gland (19), gasket (7) and washer (8)(2 pcs.) from the shaft.
- 11. Remove Jubilee clip located at the base of the transducer (1) cable and M4 flathead Phillips screws at the top of the transducer (1).



Remove Jubilee clip



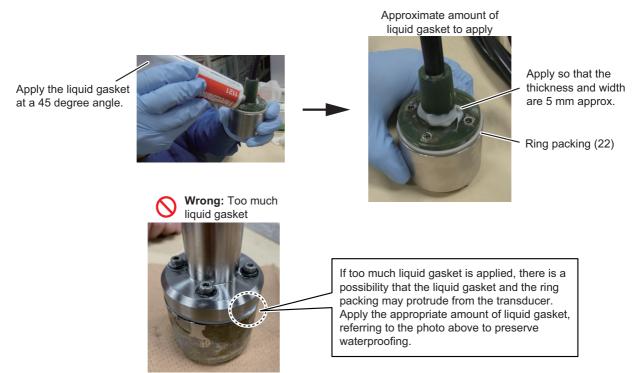
Remove flat-head Phillips screws

- 12. Pass the transducer cable through the shaft (5) from the flange side.
- 13. Attach the supplied four spacers (Type: 4×3 SPCC FEZN5-3CM) to the four screw holes where the M4 flat-head Phillips screws were removed in step 11.



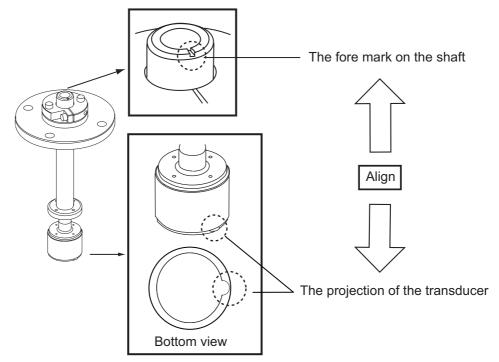
Attach the four spacers

14. Apply the liquid gasket TB1121 to the top side of the transducer (1) (see the figure below).



15. Check that the ring packing (22) is not twisted, then attach the shaft (5) to the transducer (1). Check that the fore mark on the shaft is aligned with the projection at the bottom of the transducer (1).

**Note:** If the liquid gasket or the ring packing (22) is protruding from the transducer, wipe off the liquid gasket and make sure that the ring packing (22) does not protrude.



16. Loosely fasten hex. bolts (15) with seal washers (16) to two diagonal locations (1 and 2).

**Note 1:** Do not tighten the bolts one at a time, but tighten them so that the tightening force at the two locations is equal.

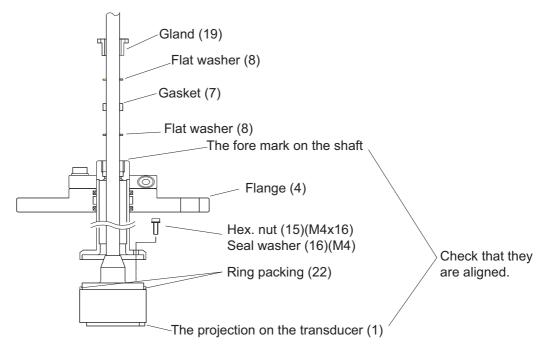
**Note 2:** Check that the liquid gasket does not overflow from the holes that have not been fastened with bolts. If it overflows, wipe off the liquid gasket.



- 17. Loosely fasten the remaining two locations (3 and 4) with hex. bolts (15) and seal washers (16).
- 18. Tighten the four hex. bolts (15) and seal washers (16) that were loosely fastened in steps 16 and 17 in the following order  $1 \rightarrow 2 \rightarrow 3 \rightarrow 4$  by two turns, torque 1.20 N•m.

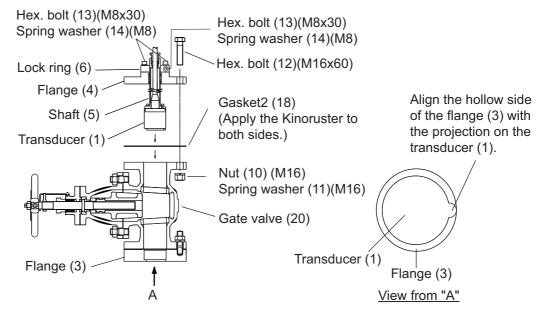
**Note:** If the liquid gasket or ring packing (22) is protruding from the transducer (1), loosen the bolts, wipe off the liquid gasket, and retighten the bolts while checking that the ring packing (22) is not protruding.

- 19. Pass the flat washer (8), gasket (7), washer (8), and the gland (19) onto the transducer cable.
- 20. Fasten the gland (19) to the top of the shaft (5).

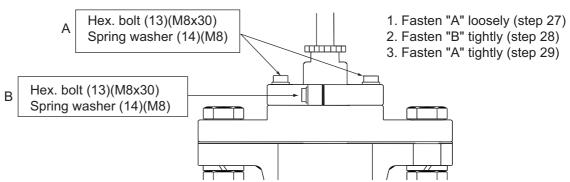


- 21. Apply Kinoruster to both sides of the gasket2 (18), and put it on the gate valve (20).
- 22. Put the shaft on the gasket2 (18), and align the hollow side on the flange (3) with the projection of the transducer (1).
- 23. Remove the M8 hex. bolt (13) and M8 spring washer (14) from the lock ring to free the shaft (5).
- 24. Use the M16 hex. bolt (12), M16 nut (10) and M16 spring washer (11) to fasten the flange (4) loosely.
- 25. Insert the shaft so the projection on the transducer (1) fits in the groove on the flange (3). Move the shaft up and down by hand to confirm that it moves smoothly.

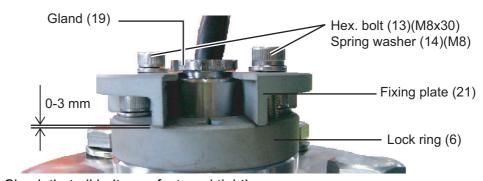
26. Tighten the M16 nut(8 pcs.) on the gate valve (20).



- 27. Loosely fasten two sets of M8 hex. bolt (13) and M8 spring washer (14) at the top side of the lock ring (6).
- 28. Tightly fasten the M8 hex. bolt (13) tightly and the M8 spring washer (14) at the lateral side of the lock ring.
- 29. Tighten two sets of M8 hex. bolt (13) and M8 spring washer (14) fastened at step 27.



30. Put the fixing plate (21) between the shaft (5) and gland (19). Fasten the plate with two sets of M8 hex. bolt (13) and M8 spring washer (14). Check the clearance between the fixing plate (21) and the lock ring (6). If the clearance is more than 3 mm, be sure to check that the hollow side of the flange (3) is aligned with the projection on the transducer (1).

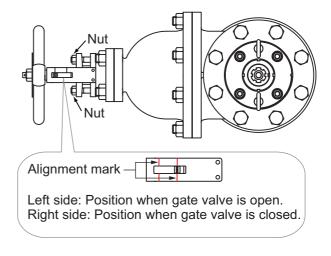


31. Check that all bolts are fastened tightly.

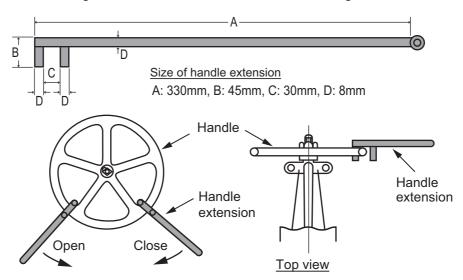
#### <How to open/close the gate valve>

- Loosen the two nuts fixing the gland gasket until the handle can be turned.
- 2. Operate the handle to open or close the gate valve.

When closing the gate valve; If additional tightening is necessary after turning the handle by hand, prepare separate handle extensions. Tighten again using the handle extension until the main handle can no longer be turned. For the



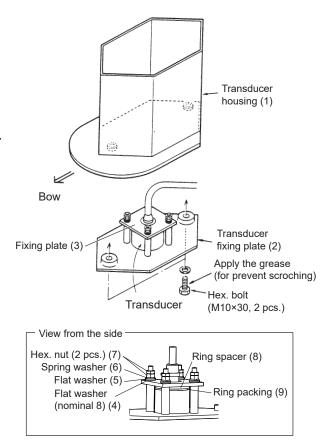
size and usage of the handle extension, refer to the figure below.



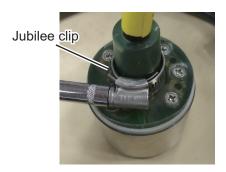
3. After opening or closing the gate valve, tighten the loosened nuts until the handle cannot be turned.

#### **DS-781 (Mounting of Projection Type Seachest)**

- 1. Weld doubling plate (local supply) to hull plate.
- 2. Remove the M10 bolts, and take out transducer fixing flange (2) from transducer housing (1).
- 3. Remove the flat washers (nominal 8) (4), flat washers (5), spring washers (6), hex nuts (7), and the fixing plate (3) that are temporarily attached to the transducer fixing flange (2).



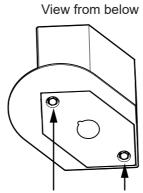
4. Remove the Jubilee clip located at the base of the transducer cable (see the figure below).



- 5. Attach the ring spacer (8) to the transducer.
- 6. Pass the cable through the hole in the fixing plate (3) and attach the fixing plate (3) to the top of the transducer.
- 7. Secure the transducer and the fixing plate (3) to the transducer fixing flange (2) with the flat washers (nominal 8) (4), flat washers (5), spring washers (6) and hex. nuts (7) removed in step 3.
- 8. Reattach the jubilee clip you removed in step 4 to the base of the transducer cable and tighten firmly to prevent water leakage.
- 9. Determine the projection distance, and cut transducer housing (1). The horizontal error should be within 1°.
- 10. Before beginning this step, remove the rubber gasket inside the thru-hull pipe to prevent it from melting. Cut a hole in the hull plate to pass the thru-hull pipe ( $\phi$ 36) through, and weld the thru-hull pipe to the hull plate.

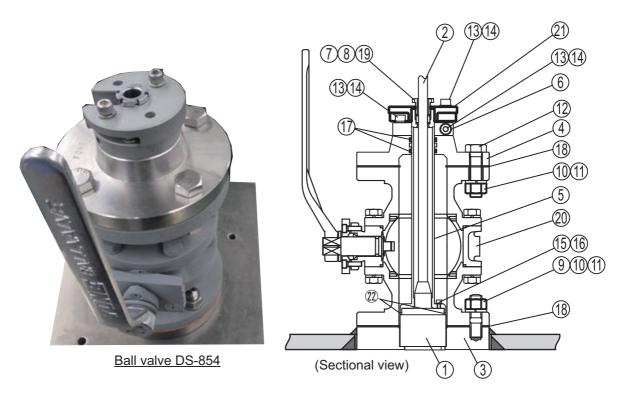
- 11. Weld the transducer housing (1) to the plate. Direction error from fore-aft line should be within 1°. At the stern side of the transducer housing (1), make drain holes (φ10-20).
- 12. Through the thru-hull pipe, pull up the transducer cable into the ship. Be careful not to jam the cable between the transducer fixing flange (2) and transducer housing (1). Next, using the two M10×30 bolts (grease applied) fasten the transducer fixing flange (2) to the transducer housing (1).
- 13. Fill the gap between the two hex. bolts and the transducer fixing flange (2) with marine sealant (local supply).

**Note:** Apply marine sealant so that the bottom of the transducer fixing flange (2) is flat.



Fill the gap with marine sealant (local supply).

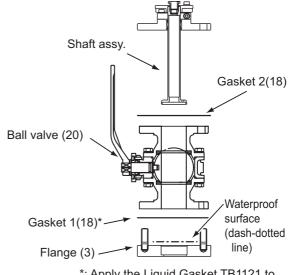
#### DS-854 (Ball valve, Transducer)



**Note 1:** The liquid gasket TB1121 for installation may not be supplied due to export regulations. If the liquid gasket TB1121 is not included in the installation materials, contact your dealer.

**Note 2:** The ball valve requires service space of 700 mm. For details, see the installation drawing at the back of this manual.

- 1. Unfasten M16 nut (10) and flat washer (11) from the assembled ball valve to remove the five items shown below.
  - Ball valve (20)
  - Flange (3)
  - Gasket 1(18)
  - Gasket 2(18)
  - · Shaft assy.



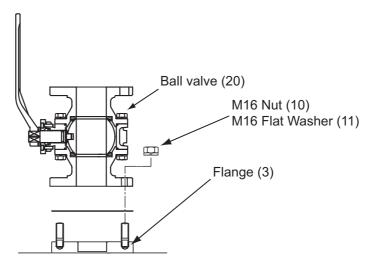
\*: Apply the Liquid Gasket TB1121 to both sides of the gasket1(18).

2. Set the flange (3) to the mounting location.

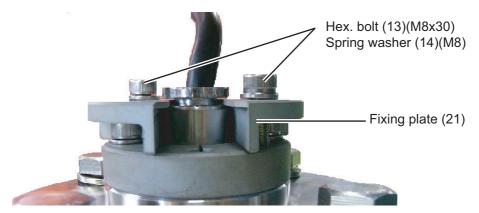
The "FORE-AFT" line on the spacer must be parallel with the ship's fore and aft line (within1). For horizontal direction, the bottom of the spacer must be parallel with the ship's draft.

**Note:** Do not paint the top side of the flange (3) and handle it carefully to preserve the waterproofing.

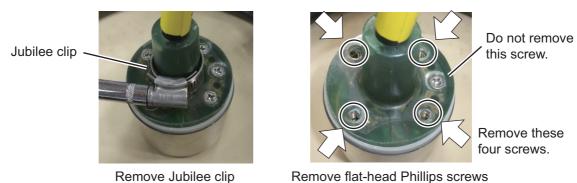
- 3. Weld the flange (3) to the ship's hull. The welding and doubling methods are left up to the shipyard.
- 4. Apply the liquid gasket TB1121 to both sides of the gasket1 (18), and put it on the flange (3) which is indicated as "dashed-dotted line" (mounting surface for the Gasket 1 (18)) in the figure at step 1 on page 1-19.
- 5. Clean the top and bottom of the ball valve (20), and put it on the gasket1 (18) set on the flange (3).
- 6. Fasten M16 nut (10) and M16 flat washer (11) loosely to the stud bolt of the flange (3) loosely.



7. Unfasten two sets of hex. bolt (13) and M8 spring washer (14) from the top side of the shaft to remove the fixing plate (21).



- 8. Remove the gland (19), gasket (7) and washer (8) (2 pcs.) from the shaft.
- 9. Remove the Jubilee clip located at the base of the transducer cable and four M4 flat-head Phillips screws at the top of the transducer (1).

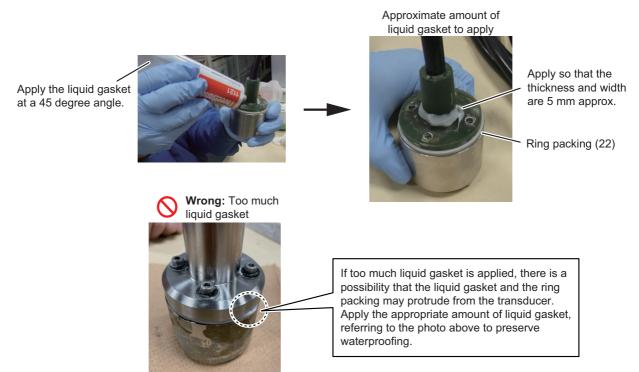


- 10. Pass the transducer cable through the shaft (5) from the flange side.
- 11. Attach the supplied four spacers (Type:4×3 SPCC FEZN5-3CM) to the four screw holes where M4 flat-head Phillips screws were removed in step 9.



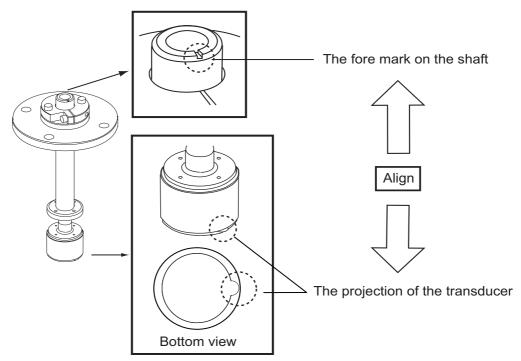
Attach the four spacers

12. Apply the liquid gasket TB1121 to the top side of the transducer (1) (see the figure below).



13. Check that the ring packing (22) is not twisted, then attach the shaft (5) to the transducer. Check that the fore mark on the shaft (5) is aligned with the projection at the bottom of the transducer (1).

**Note:** If the liquid gasket or ring packing (22) is protruding from the transducer (1), wipe off the liquid gasket and make sure that the ring packing (22) does not protrude.



14. Loosely fasten hex. bolts (15) with seal washers (16) to two diagonal locations (1 and 2).

**Note 1:** Do not tighten the bolts one at a time, but tighten them so that the tightening force at the two locations is equal.

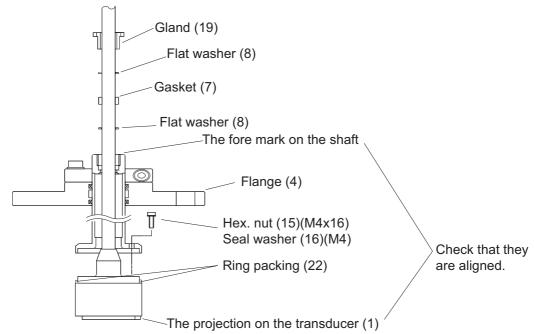
**Note 2:** Check that the liquid gasket does not overflow from the holes that have not been fastened with bolts. If it overflows, wipe off the liquid gasket.



- 15. Loosely fasten the remaining two locations (3 and 4) with hex. bolts (15) and seal washers (16).
- 16. Tighten the four hex. bolts (15) and seal washers (16) that were loosely fastened in steps 3 and 4 in the following order  $1 \rightarrow 2 \rightarrow 3 \rightarrow 4$  by two turns, torque 1.20 N•m.

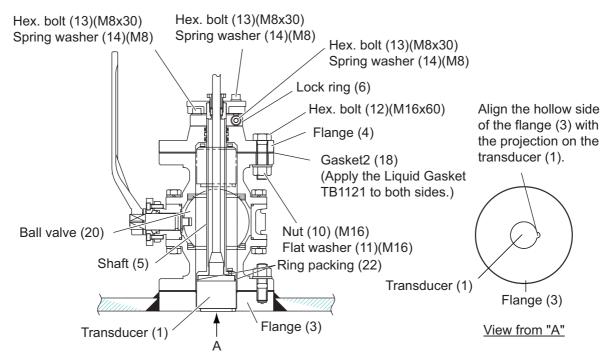
**Note:** If the liquid gasket or ring packing (22) is protruding from the transducer (1), loosen the bolts, wipe off the liquid gasket, and retighten the bolts while checking that the ring packing (22) is not protruding.

- 17. Pass the flat washer (8), gasket (7), washer (8), and the gland (19) onto the transducer cable.
- 18. Fasten the gland (19) to the top of the shaft (5).

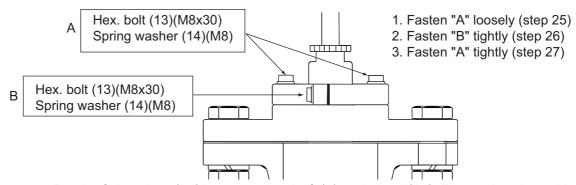


- 19. Apply the liquid gasket TB1121 to both sides of the gasket2 (18), and put it on the ball valve (20).
- 20. Put the shaft on the gasket2 (18), and align the hollow side on the flange (3) with the projection of the transducer (1).
- 21. Remove three M8 hex. bolts (13) and three M8 spring washers (14) from the lock ring (6) to free the shaft (5).
- 22. Fasten the flange (4) loosely with the M16 hex. bolt (12), M16 nut (10) and M16 flat washer (11).
- 23. Insert the shaft so the projection on the transducer (1) fits in the groove on the flange (3). Move the shaft up and down by hand to confirm that it moves smoothly.

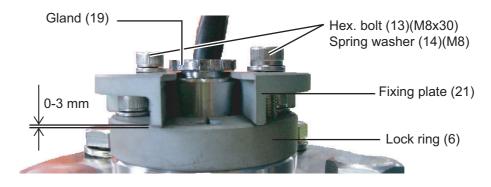
24. Tighten the M16 nut (8 pcs.) (10) on the ball valve (20).



- 25. Loosely fasten two sets of M8 hex. bolt (13) and M8 spring washer (14) at the top side of the lock ring (6).
- 26. Fasten the M8 hex. bolt (13) tightly and the M8 spring washer (14) at the lateral side of the lock ring (6) to fasten the shaft (5).
- 27. Fasten tightly two sets of M8 hex. bolt (13) and M8 spring washer (14) fastened at step 25.



28. Put the fixing plate (21) between the shaft (5) and gland (19). Fasten the plate with two sets of M8 hex. bolt (13) and M8 spring washer (14). Check the clearance between the fixing plate (21) and the lock ring (6). If the clearance is more than 3 mm, be sure to check that the hollow side of the flange (3) is aligned with the projection on the transducer (1).

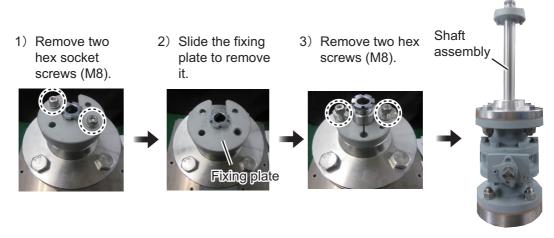


- 29. Check that all bolts are fastened tightly.
- 30. Paint the ball valve (20) and the flange (3) the same color as ship's body. Paint only gray-colored areas; for other parts, seal with masking tape. Remove the tape when the paint dries.

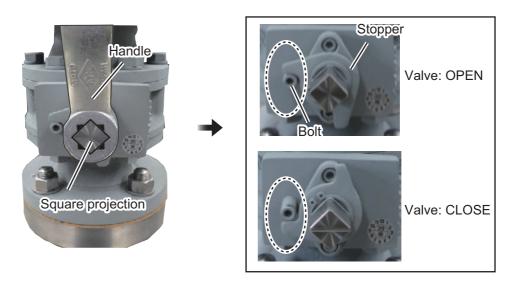
#### <How to open/close the ball valve>

To open/close the ball valve, attach the supplied handle to the square projection then change the stopper position.

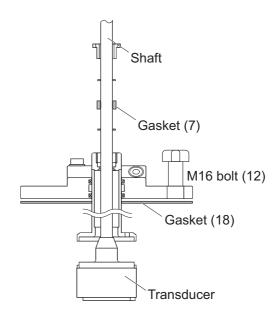
1. Remove the fixing plate as shown figure below then pull the shaft assembly up.



2. Attach the supplied handle to the square projection and then turn the handle 90° to change the stopper position.



3. After opening or closing the ball valve, tighten the removed nuts until the handle cannot be turned. Also, remove four bolts (M16) to remove the shaft and the transducer assembly. After removing the assemblies, replace the gaskets as shown in the figure to the right.



## 1.5 Option Unit

#### 1.5.1 Junction Box

The junction box forms a joint between the distribution box and the transceiver unit.

#### **Installation considerations**

- Keep the junction box away from noise-emitting electrical machinery, for example, electric generator, radio transmitter, TV, etc.
- Although the box is splash proof, do not install it in places of high humidity.
- Avoid installing the box where temperature varies greatly, since moisture may penetrate the box.

#### **Procedure**

Open the box cover, and fix the unit to a bulkhead, referring to the outline drawing at the back of this manual.

- 1. Select a mounting location, referring to the recommendations listed above.
- 2. Remove the cover of the junction box.
- 3. Fix the junction box from inside with the supplied self-tapping screws (5×25).
- 4. Attach the cover again.

#### 1.5.2 Range Selector

Change analog output to allow analog scales of -2 to 6 kn in addition to -10 to 30 kn.

#### **Installation considerations**

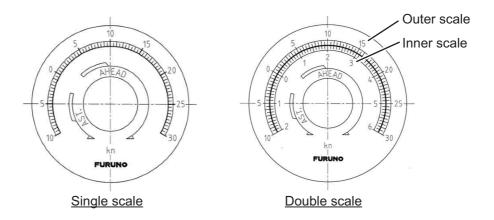
- The temperature and humidity of the mounting location should be moderate and stable.
- · Avoid locations near the air intake, dusty storage or where water splashing.
- · Mount the unit where shock and vibration are minimal.

#### 1.5.3 Analog Display Unit

The analog display units show the ship speed in the clockwise direction (For SL-200-5 and SL-200-5W, the ship speed in the counterclockwise direction).

There are two types of range scales according to the model of the analog display unit; single scale and double scale.

For double scale display units, there are scales on the outside and the inside. You can switch the scale between the scale on the outside and the inside with the range selector MF-2R-1 / 2. If the range selector is not connected, only the outer scale is valid.



#### **Installation considerations**

The analog indicator is an ammeter. An error may occur if a strong magnetic field exists nearby. Keep away from transformers and power supplies as much as possible. Avoid places subject to rain or seawater splashes and high temperatures or where there is high humidity and vibration.

#### 1.5.4 Remote Controller

For installation and cable connection of Remote Controller RD-501, see the operator's manual of the connected sub display (RD-20: OME-44540, RD-50: OME-44530) for your reference.

#### 1.5.5 Dimmer Controller

The dimmer controller has two types as below.

#### DS-F25/S25/FE25/SE25

These are used for externally controlling the illumination of the analog indicator. These power supply specifications (100-115 VAC or 200-220 VAC) vary depending on the type used.

#### **RD-502**

The RD-502 is used for controlling the illumination of the display unit DS-8500 and the sub display unit (option).

For the connection between RD-502 and RD20/RD-50, refer to the operator's manual of each remote display (RD-20: OME-44540, RD-50: OME-44530).

#### < Installation considerations >

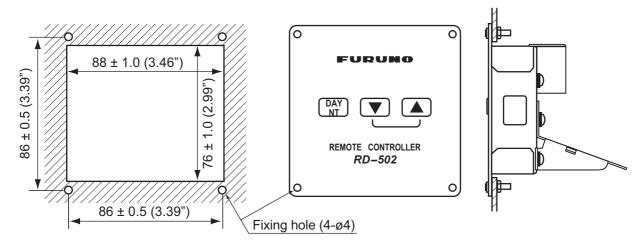
- The nominal viewing distance for the remote display is 1 m. Select a suitable mounting location considering that distance.
- · Locate the remote display away from exhaust pipes and vents.
- · Select an installation location that is well ventilated.
- · Locate the remote display where shock and vibration are minimal.
- Locate the remote display away from equipment which generates the electromagnetic fields like a motor or generator.
- Allow enough maintenance space at the sides and rear of the remote display and leave enough slack in cables to facilitate maintenance and servicing.
- Observe the compass safe distances (see page ii) to prevent interference to a magnetic compass.

#### <Procedure>

Only flush mounting is available.

**Note:** Make sure the cables are connected before installing the remote or dimmer controllers.

- 1. Make a cutout in the mounting location (88 mm (width) x 76 mm (height)).
- 2. Make four holes of  $\phi 4$  in the locations indicated in the illustration below.
- 3. Set the remote controller or dimmer controller to the cutout. Insert four binding head screws (M3x12) from the front side then fasten the unit with four sets of flat washers, spring washers and hexagonal nuts from the rear side.

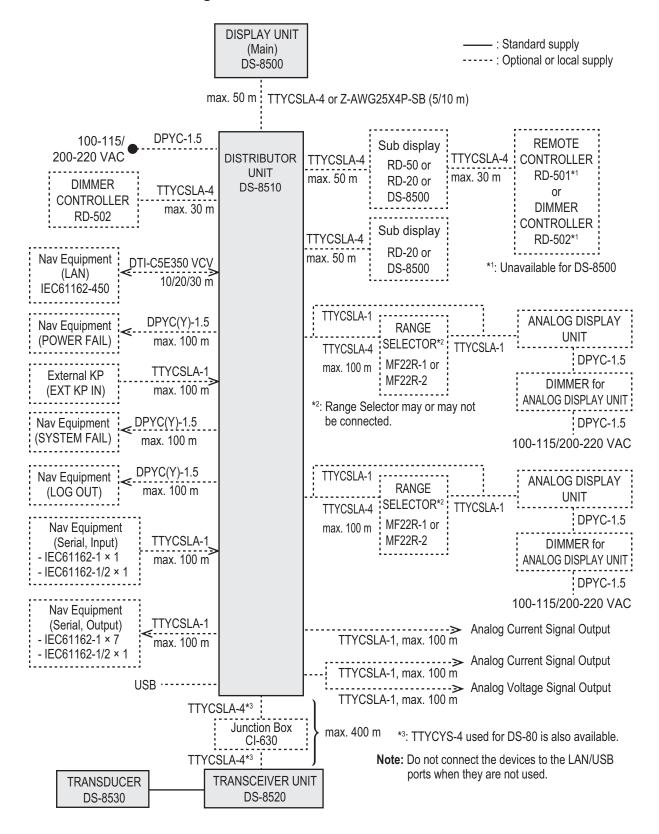


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## 2. WIRING

#### 2.1 Overview

#### **Standard wiring**



#### 2.2 Precautions for Cable Installation

To avoid noise and interference, lay cables between units as far away as possible from power cables and radio transmission signal cables.

When the cables run in parallel with power cables, separate them 400 mm at minimum.

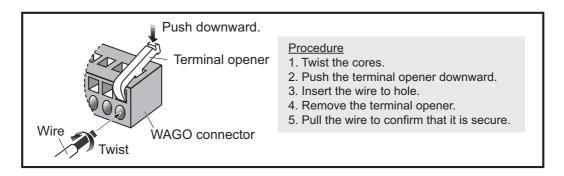
Run the transducer cables separate from other cables as much as possible.

Also, ground the equipment to prevent electrical shock and mutual interference.

#### 2.2.1 WAGO connection

For the display unit, the terminal opener is included inside the cable clamp on the back cover.

For the distributor unit, the two terminal openers are included inside the unit. Check that the size (large or small) of the opener is correct before use.

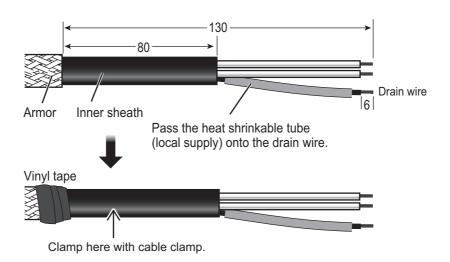


## 2.3 Display Unit

#### 2.3.1 How to fabricate the cables

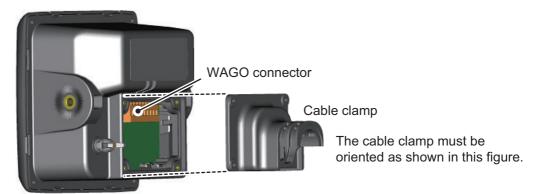
Using the supplied terminals on the inside of the DS-8500, fit the drain wire (or shield line) of each cable with a terminal, then attach the terminal to the inside of the DS-8500 (the same place it was situated originally).

#### TTYCSLA-4



#### 2.3.2 How to connect the cables

1. Unfasten the four screws on the rear cable clamp, then remove the cable clamp to reveal the WAGO connector.



- 2. Unplug the WAGO connector from the display unit.
- Pass the cable through the cable clamp.
   Note: To maintain the IPx5 waterproof rating, the cable must be TTYCSLA-4 (or equivalent) with a diameter of φ14.4±0.4 mm.
- 4. Referring to the interconnection diagram at the back of this manual, connect the display unit using the WAGO connector inside the unit.
- 5. Reattach the WAGO connector to the display unit.
- 6. Slide the cable clamp along the cable towards the display unit, then fasten the four screws which were removed at step 1. The cable clamp must be oriented as shown the figure above.
- 7. Secure the cable to the cable clamp with cable tie(s) (included). The location and number of cable tie(s) is different, depending on whether the cable assembly OP05-146-1, OP05-146-2, optional cable protection kit or waterproofing kit is installed. Refer to the figure below for the correct location and numbers.

When using the cable When using the cable (TTYCSLA-4) assembly OP05-146-1, OP05-146-2 or the cable Without using the With using the protection kit (OP05-147) waterproofing kit (OP05-139) waterproofing kit (OP05-139) With three cable ties With two cable ties With a single cable tie Cable clamp Cable clamp Cable clamp Cable tie Cable tie Cable tie Slot Slot Cable Cable gasket aasket Secure the cable gasket also Wind cable ties through the slots. Wind a cable tie outside of the with a cable tie. cable clamp.

Top view of cable clamp

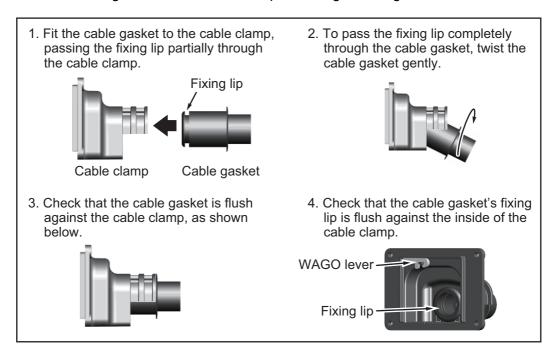
In cases where the WAGO connector is connected to the cable before the cable is passed through the cable clamp, the cable clamp can be adjusted to allow connection.

#### How to fit the optional waterproofing kit (OP05-139)

The optional waterproofing kit must be fitted at the same time as the cabling is connected to the display unit.

**Note:** To satisfy the requirements for IPX5 waterproof rating, the cable used must have a diameter of 14.4 mm (±0.4 mm).

- 1. Unfasten the four screws on the rear cable clamp, then remove the cable clamp to reveal the WAGO connector.
- 2. Fit the cable gasket to the cable clamp, referring to the figure below.



- 3. Pass the cabling through the cable gasket and cable clamp.
- 4. Fit the cover gasket (rubber seal) to the rear of the display unit. Make sure the rubber seal is placed inside the groove indicated in the figure below.



- 5. Connect the cabling to the display unit, referring to the interconnection diagram at the back of this manual.
- 6. Slide the cable clamp along the cable until the clamp is flush against the rear of the display unit.

**Note:** The cable clamp must be oriented with the dome facing upwards in order to retain it's waterproofing rating.

- 7. Fasten the four screws removed at step 1.
- 8. Secure the cables to the cable clamp with cable ties.

## 2.4 Distributor Unit

## 2.4.1 Required tools

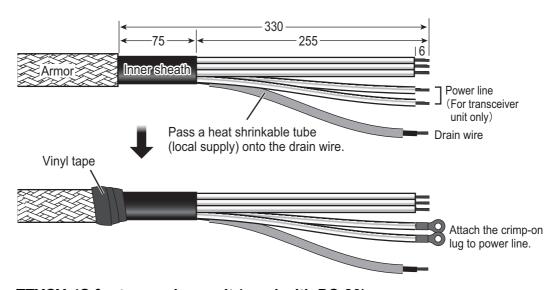
The following item should be prepared in advance for this installation locally.

Item	Qty	Remarks
Cable tie	61	Equivalent of Convex CV-150B (125 × 4.9 mm)

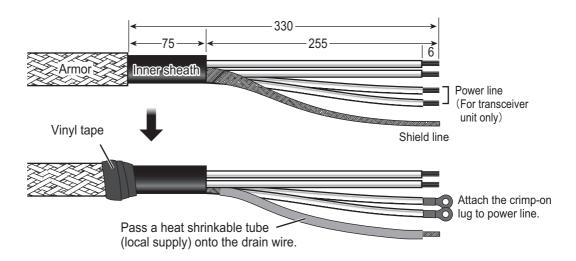
#### 2.4.2 How to fabricate the cables

**Note:** Make sure that the cover does not contact any connected cables when you close the cover.

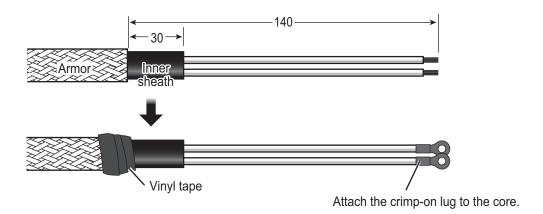
# TTYCSLA-4/-1 DPYC(Y)-1.5 for Navigation equipment and display unit. transceiver unit



#### TTYCY-4S for transceiver unit (used with DS-80)

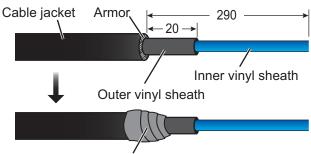


#### DPYC(Y)-1.5 for Ship's Mains



#### LAN cable DTI-C5E350 VCV

**Note:** This equipment only uses straight cables.



Wrap vinyl tape. (width: 20 mm)



Expose inner vinyl sheath.



Remove the inner vinyl sheath by approx. 25 mm. Be careful not to damage inner shield and cores.



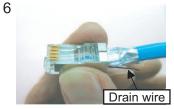
Fold back the shield, wrap it onto the inner vinyl sheath and cut it, leaving approx. 9 mm.



Fold back drain wire and cut it, leaving approx. 9 mm.



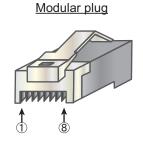
Straighten and flatten the cores in colored order and cut them, leaving approx. 11 mm.



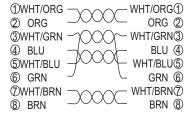
Insert the cable into the modular plug so that the folded part of the shield enters into the plug housing. The drain wire should be located on the tab side of the jack.



Using special crimping tool MPT5-8AS (PANDUIT CORP.), crimp the modular plug. Finally, check the plug visually.



[Straight cable]



#### 2.4.3 How to connect the cables

Some parts or wiring have been omitted from the illustrations for clarity.

**Note:** When closing the distributor unit, make sure that the connected cables do not contact the cover.

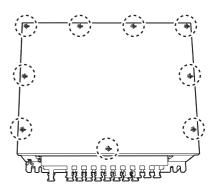
#### How to open/close the top cover

Unfasten nine screws to open the top cover.

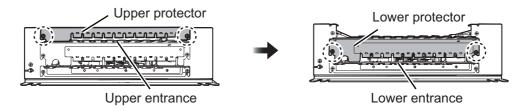
After the appropriate cable connections are completed, fasten nine screws to close the top cover.

## Cable entrance

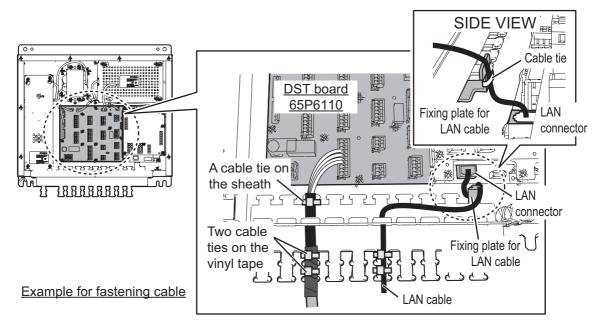
There are two layers at the cable entrance on the front side of the distributor unit, upper and lower entrances.



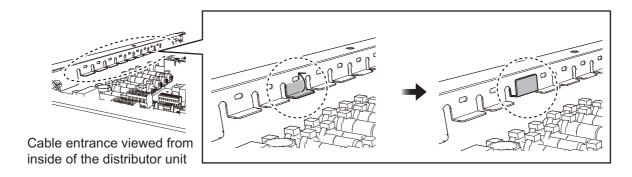
First, loosen two screws to remove the upper protector. The upper cable entrance appears. Then, loosen two screws to remove the lower protector. The lower cable entrance appears.



Set each cable on the cable entrance, referring to "Cable entrance" on page 2-8 then fasten the cable as follows with two cable ties which are supplied locally.



**Note:** If the cable is too thick for the protector to hold, bend the protector with a plier supplied locally.



Also, the lane for each cable is shown below, referring to the Wiring Label attached on the reverse side of the top cover.

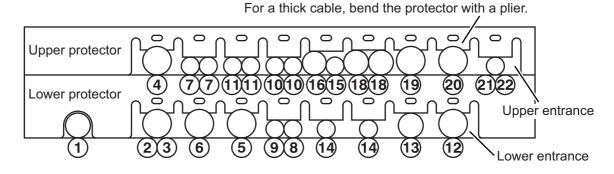
#### Cable connection (other than the power cable)

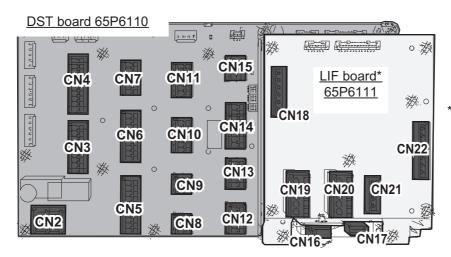
Connect the cables to the connectors on the DST board 65P6110 and the LIF board 65P6111 (option). The core lines of the cables should be connected to the connectors referring to the interconnection diagram at the back of this manual.

The type of cable to be connected and the cable location on the cable entrance are shown in the following figure and table.

The LIF board

#### Cable entrance





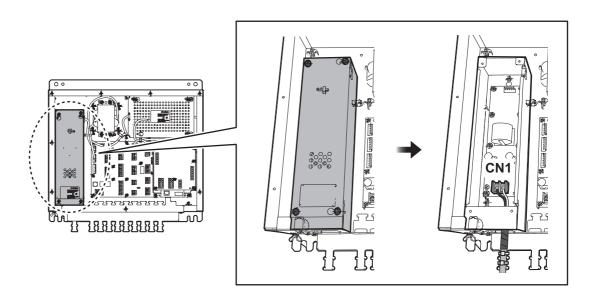
\*: If LIF board is not attached in distributor unit, the board is provided with the optional kit OP65-3.

**Connector location** 

No. of cable		Printed board		
entrance	Signal	Туре	Connector no.	Remarks
2	TRX POWER	65P6110 (DST)	CN2	Power to transceiver unit
3	TRX		CN3	Signal from trans- ceiver unit
4	SUB DISP1		CN4	
5	DISP		CN5	
6	SUB DISP2		CN6	
7	IEC61162OUT3		CN7	
8	IEC61162IN1		CN8	
9	IEC61162IN2		CN9	
10	IEC61162OUT1		CN10	
11	IEC61162OUT4		CN11	
12	DIMMER		CN12	
13	POWER FAIL		CN13	
14	IEC61162OUT2		CN14	
15	EXT KP IN		CN15	
16	LAN		CN16	
_	USB		CN17	
18	SYSTEM FAIL		CN18	
19	ANA DISP1	GEDG114	CN19	
20	ANA DISP2	65P6111 (LIF)	CN20	Option
21	ANA DISP3	(LII )	CN21	
22	ANA DISP4		CN22	

### **Connection of power cable**

Remove the four screws on the cable cover inside the distributor unit. Set the power cable from ship's Mains on the no.1 cable entrance, referring to the "Cable entrance" on page 2-8 and fasten the cable with two cable ties supplied locally. The core should be connected to CN1 terminal as follows.



## 2.5 Transceiver Unit

#### 2.5.1 How to fabricate the cables

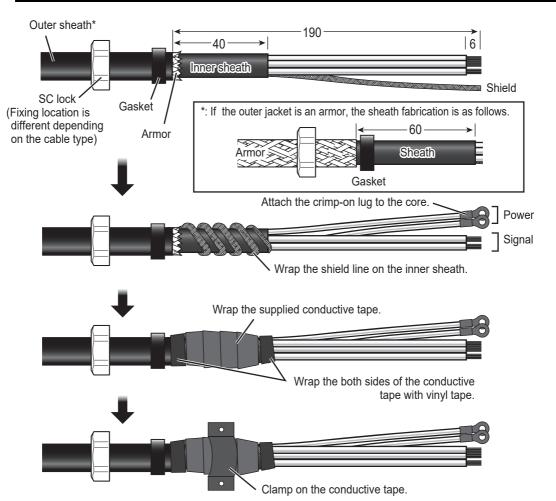
Attach the SC lock and the packing (pre-attached to the cable entry on the transceiver) to the cable before fabricating the cable. Please pay attention to the orientation of the SC lock and packing.

### Signal cable

The cables listed in the table below can be used for the transceiver unit.

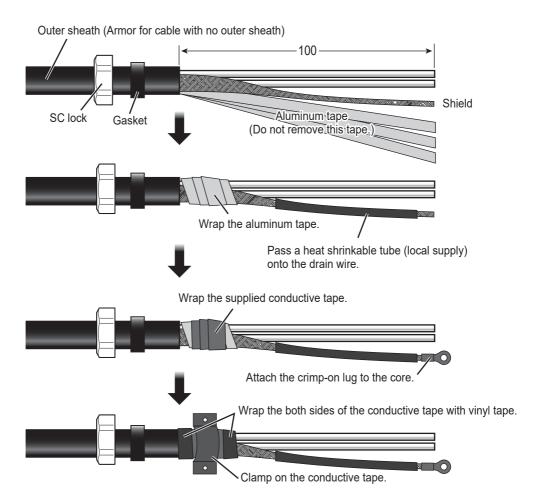
Depending on the used cable, the type of the SC lock and the fixing location on the cable are various, referring to the table below. The appropriate SC lock must be attached at the appropriate location on the cable.

Type of cable	Replacement to OP65-4	Fixing location on the cable	Remarks
TTYCYSLA-4	_	On the outer sheath	
TTYCSLA-4	Required	On the armor	No outer sheath
<ul><li>TTYCY-4S</li><li>TTYC-4S</li></ul>	_	On the inner	Cable for DS-80
Other cable \$\phi\$14.5 to 16.5?	Required	sheath	



When using the optional junction box, fabricate the cable as in the previous figures.

#### **Transducer cable**

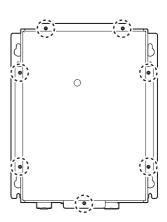


### 2.5.2 How to connect the cables

#### How to open/close the top cover

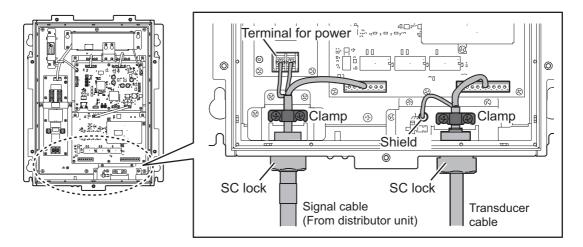
Unfasten seven screws to open the top cover.

After the appropriate cable connections are completed, fasten seven screws to close the top cover.



#### **Cable Connection**

Connect the signal cable and the transducer cable from the distributor unit as shown below. Refer to the interconnection diagram at the back of this manual for connection details.



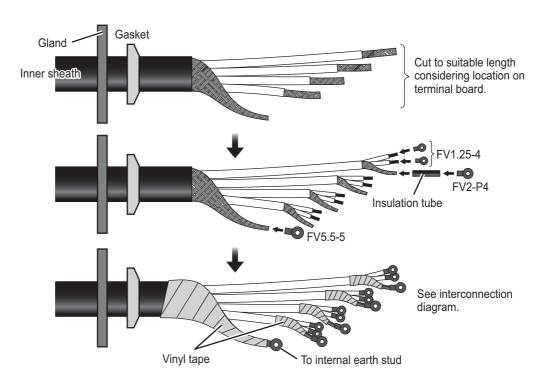
- Signal cable (from distributor unit): Connect the power and signal lines, and fix the cable on the conductive tape with the clamp in the transceiver unit. Then tighten the cable with the SC lock.
- Transducer cable: Connect the signal and shield lines, and fix the cable on the conductive tape with the clamp in the transceiver unit. Then tighten the cable with the SC lock.

## 2.6 Junction Box (option)

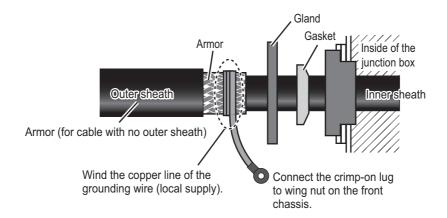
The transceiver unit cable is connected to the junction box with an extension cable. After making the connection, seal the cable gland with putty for watertightness.

#### 2.6.1 How to fabricate the cable

Before cable fabrication, attach the cable glands and gaskets which are attached at the cable entrance on the cable in advance. Please pay attention to the orientation of cable glands and gaskets on the cable.

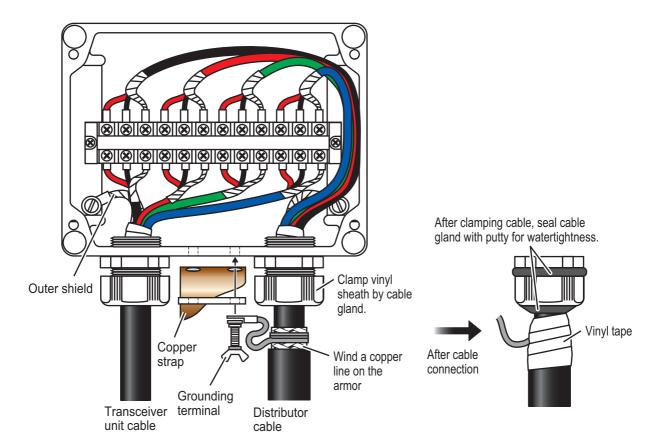


After tightening the inner sheath by the gland, wind a grounding wire on the armor as shown below. Then connect the grounding wire to the wing nut on the front of the chassis.



#### 2.6.2 How to connect the cables

For the cable connection details, see the interconnection diagram at the back of this manual. After cable connection, seal the gland with putty for watertightness as shown below.



## 2.7 Grounding

This equipment uses pulse signals which may cause interference to other electronic equipments It is strongly recommended to ground all cables referring to the guidelines below.

- Separate all units as far as possible from radio equipment.
- Do not run interconnection cables close to or near radio equipment or its cables.
- Run the cables in the shortest practical path.
- Ground all units with a copper strap or earth wire.
- To join copper straps, use solder cream for perfect contact.

## 3. ADJUSTMENTS

At the first start-up after installation, turn on the display unit with the power key. Open the protected menus to adjust the system. Follow the procedures in this chapter to complete the adjustment.

**Note 1:** Set the password at the first start-up. The password should be set by the administrator of the unit (e.g., the captain). The password requirements are as shown below.

- Length: 8 to 16 characters.
- Character type: Must use a combination of upper case, lower case and numeric.



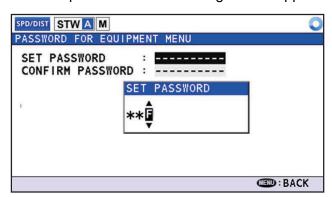
Power key

**Note 2:** If you leave your seat after password authentication to open the [EQUIPMENT] menu, your password may be changed by someone other than the administrator. Therefore, do not leave your seat after password authentication, or if you must leave, turn off the power to the DS-85 to cancel the authentication status.

#### Setting the user password

When you start the application for the first time, the user password should be set. Set the password with following procedure.

1. Turn the power on. The following screen appears.

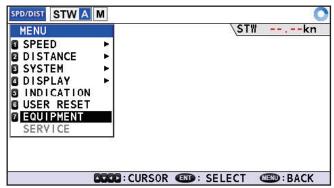


2. Enter the password with keypad, then enter the password once again for confirmation.

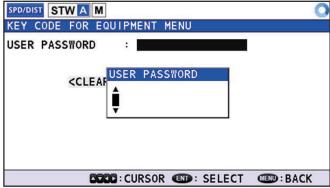
**Note:** The password requires eight letters or more, and capital/small alphabet, numerical characters. To change the restriction, contact your service technician.

#### Changing the user password

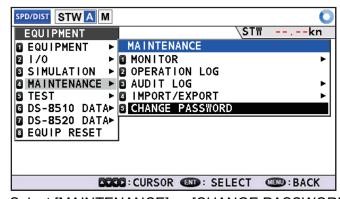
1. Press the **MENU/ESC** key to show the main menu.



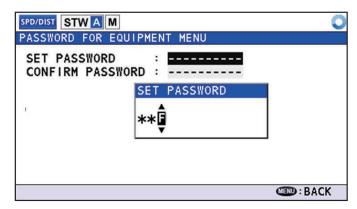
2. Select [EQUIPMENT] menu and press the **ENT** key. The user password entry window appears.



3. Enter the user password and press the **ENT** key. The [EQUIPMENT] menu appears.

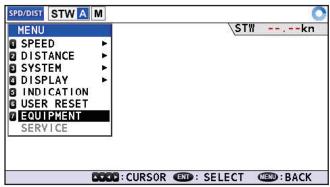


- 4. Select [MAINTENANCE] → [CHANGE PASSWORD] and press the **ENT** key.
- 5. Enter the new password to "SET PASSWORD" and "CONFIRM PASSWORD" in same strings.

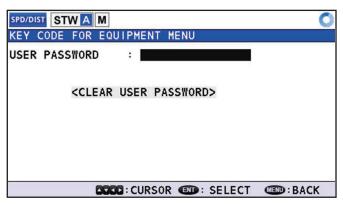


#### Reset the user password

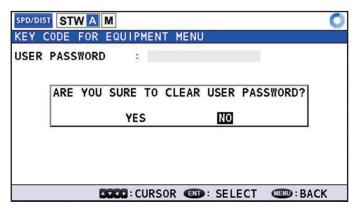
1. Press the **MENU/ESC** key to show the main menu.



2. Select [EQUIPMENT] menu and press the **ENT** key.



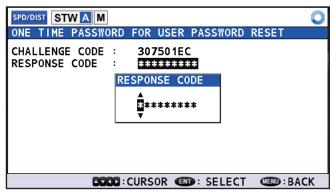
3. Select <CLEAR USER PASSWORD> and press the **ENT** key. The pop-up menu appears.



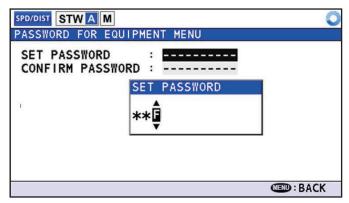
#### 3. ADJUSTMENTS

4. Select [YES] and press the ENT key.

The password reset menu appears. To change the password, the response code is required. Contact FURUNO service technician and request a response code by telling the challenge code displayed.



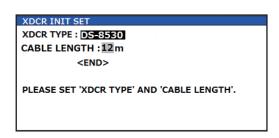
5. Enter the response code and press the **ENT** key. Password setting menu appears.



6. Set a new password using the same procedure as when you first started the DS-85 after installation.

#### <u>Transducer initial setting</u>

For the main display unit, the [XDCR INIT SET] display is shown when the power is turned on. After the above settings are completed, select [END] with the ▼ key and then press the ENT key. The confirmation message "ARE YOU SURE? (RESTART OK?)" is shown, and select [YES] then press the ENT key to complete the initial settings.



Once set the following items, this window is not shown at start up next time. To change the following settings, initialize this setting at the [TYPE CLEAR] menu (see page 3-7).

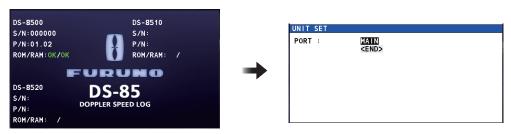
• [XDCR TYPE]: Set the type of the transducer, [DS-820] or [DS-8530] (default setting: [N/A]).

**Note:** If an incorrect setting is entered, STW (Speed Thru Water) is not displayed correctly and the transducer may overheat, causing malfunction.

[CABLE LENGTH]: Set the transducer cable length 1 to 40 m (default setting: 20 m)
 Note: Set the correct cable length to compensate for the correction of the transducer signal with cable length. If an incorrect setting is entered, the STW (Speed Thru Water) is not displayed correctly.

#### **Display unit initial setting**

For installations with a single DS-85, select [MAIN]. For vessels with more than one DS-85, you can share the brilliance setting across the networked DS-85s. Select [MAIN] for the main DS-85 unit, SUB units receive and use the setting from the MAIN unit. To show the **UNIT SET** window, press the **MENU** → **DISP** → **BRILL** keys in order during the start-up window below is shown. After selecting [MAIN] or [SUB], select [END] with the ▼ key and then press the **ENT** key. The confirmation message "ARE YOU SURE? (RESTART OK?)" is shown then select [YES] and press the **ENT** key.



[MENU]→[DISP]→[BRILL] key

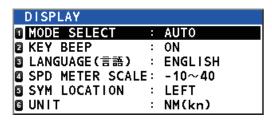
#### How to select the language for menu window

The default language for the menu window is English. To change the language to Japanese, set as follows.

1. Press the **MENU/ESC** key to open the main menu.



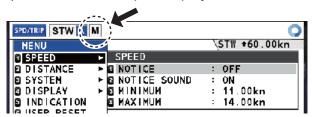
2. Select [DISPLAY] then press the **ENT** key.



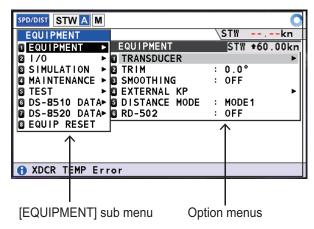
- 3. Select [LANGUAGE] then press the ENT key.
- 4. Select the appropriate language (English or Japanese) then ENT key.
- 5. Press the **DISP** key to close the menu window.

#### How to Open the [EQUIPMENT] menu for installation

**Note:** For "MAIN" display unit only, the installation menus are operative. Make sure that [M] (Main) is shown at the top of display.



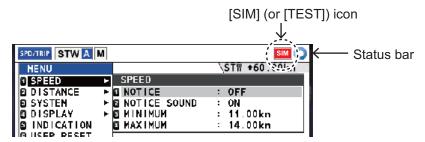
- 1. Press the **Power** key to turn on the unit.
- 2. Press the **MENU/ESC** key to open the main menu. The [SERVICE] menu is shown in gray and inoperative.
- 3. Select [EQUIPMENT]. The password input window for the [EQUPMENT] menu is shown.
- 4. Enter the password to open the sub menu. The [EQUIPMENT] menu has the eight sub menus shown in the figure below.



5. Press the **MENU/ESC** key to close the menu.

#### Status bar

The status bar is shown on every screen, and gives you a quick, at-a-glance view of the DS-85's current status. See the Operator's Manual (OME-72880) for this equipment. The two icons for service technician are shown below.



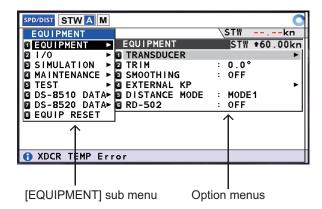
- [SIM] icon: Displays when the simulation mode is active (see section 3.3).
- [TEST] icon: Normal operation cannot be performed when the [TEST] icon is displayed. To return to normal operation, change the DIP switch settings as follows.

Unit	Printed Board	DIP switch	Setting
Distributor Unit	DST board 65P6110	SW3	OFF (all)
Transceiver Unit	MAIN board 65P6120	SW2	OFF (all)

## 3.1 [EQUIPMENT] sub menu

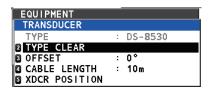
On the main menu, select [EQUIPMENT] →[EQUIPMENT] to open the [EQUIPMENT] sub menu.

**Note:** The [EQUIPMENT] menu requires password certification.



### 3.1.1 [TRANSDUCER] menu

On the [EQUIPMENT] sub menu, select [TRANSDUCER] to open the [TRANSDUCER] menu.



#### [TYPE]

Shows the type for the transducer which is set the transducer initial setting. See page 3-4 for the transducer initial setting.

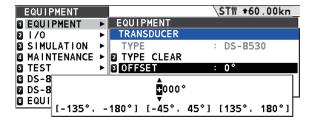
To change the type, execute [TYPE CLEAR] then set the transducer settings again.

#### **ITYPE CLEAR**

Select [YES] on the confirmation message to reset the default settings for the setup of the transducer.

#### [OFFSET]

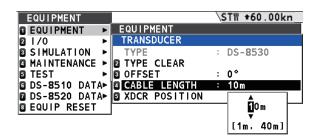
If the transducer is not installed parallel to the bow-stern keel line, correct the error in the equipment angle. Set the calibration angle for the transducer position (default: 0°). The setting range is -135° to -180°, -45° to 45° and 135° to 180°. Set the clockwise direction as + with viewing the transducer from above.



#### [CABLE LENGTH]

Shows the cable length of the transducer which is set at initial setting. See page 3-4 for the transducer initial setting. Make sure that the length is correct for calibration by the temperature sensor.

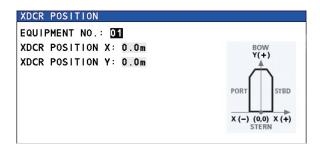
To change the cable length, execute [TYPE CLEAR] then set the transducer settings again. see page 3-7 for [TYPE CLEAR].



#### [XDCR POSITION]

Open the [XDCR POSITION] window to set the position for each transducer. The setting range for the number of the transducer is [01] to [99] (default: [01]).

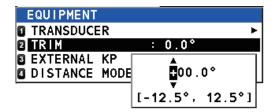
For each transducer, set the X-axis distance (between port (-) and starboard (+) from the center of ship) and Y-axis distance (between bow and stern).



## 3.1.2 [TRIM] menu

On the [EQUIPMENT] sub menu, select [TRIM] to set the correction for ship angle.

The setting range is -12.5° to 12.5° (default: 0°).

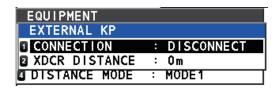


## 3.1.3 [EXTERNAL KP] menu

On the [EQUIPMENT] sub menu, select [EXTERNAL KP] to set up external KP.

#### [CONNECTION]

Select [CONNECT] when an external KP is connected, if not [DISCONNECT].



#### [XDCR DISTANCE]

Set the distance between the transducers that are connected to the external KP. This setting automatically adjusts the delay time for signal processing, based on the set distance. The setting range is 0 to 250 m (default: 0 m).

: 0.0°

MODE1 Mode2

### 3.1.4 [DISTANCE MODE] menu

On the [EQUIPMENT] sub menu, select [DISTANCE MODE].

Select the speed calculation mode to use when normal speed calculation is not available.

- [MODE1]: Distance is NOT added, pulse is NOT output (default).
- [MODE2]: Distance is added, pulse is output, using the ship's last calculated speed.

**EQUIPMENT** 

2 TRIM

**TRANSDUCER** 

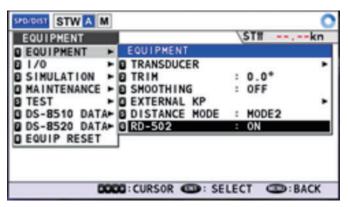
EXTERNAL KP

DISTANCE MODE

### 3.1.5 Dimmer unit setting

Follow the procedure below to set up the dimmer unit RD-502.

- 1. Press the **MENU/ESC** key to open the main menu.
- Select [EQUIPMENT], then press the ENT key.



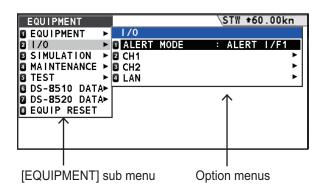
Select [RD-502], then press the ENT key. The options pop-up window shows.



- 4. Select [ON] or [OFF], then press the **ENT** key. [ON] allows remote operation from the RD-502, [OFF] disable operations from the RD-502.
- 5. Press the **DISP** key to close the menu.

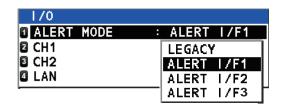
## 3.2 [I/O] sub menu

On the main menu, select [EQUIPMENT]  $\rightarrow$ [I/O] to open the [I/O] sub menu.



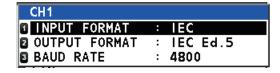
### 3.2.1 [ALERT MODE] menu

On the [I/O] sub menu, select [ALERT MODE] to set the alert mode, [LEGACY], [ALERT I/F1], [ALERT I/F2] and [ALERT I/F3](default: [ALERT I/F1]).



### 3.2.2 [CH1], [CH2] menu

On the [I/O] sub menu, select [CH1] (or [CH2]) to set each channel setting. These channels can be set for the following signals.



[CH1]: RD1, TD1

[CH2]: RD2, TD2 to TD8

#### [INPUT FORMAT]

Select the input format, [IEC] or [NMEA] (default: [IEC]).

#### **[OUTPUT FORMAT]**

Select the output format, [IEC Ed.1] to [IEC Ed.5] (default: [IEC Ed.5]).

#### [BAUD RATE]

Select the baud rate, [4800] bps or [38400] bps (default: [4800] bps).

Note: For [CH2], baud rate is fixed at [4800].

## 3.2.3 [LAN] menu

On the [I/O] sub menu, select [LAN] to set LAN setting.

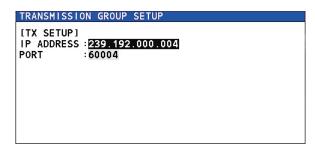


#### [FORMAT]

Select the format for LAN connection, [IEC Ed.4] or [IEC Ed.5] (default: [IEC Ed.5]).

#### **ITRANSMISSION GROUP SETUP1**

Open the [TRANSMISSION GROUP SETUP] window to set the IP address or port.



[IP ADDRESS]: Set the IP address, [000.000.000.000] to [255.255.255.255] (default: [239.192.000.004]).

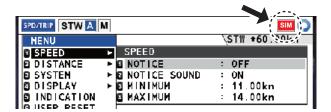
[PORT]: Set the port, [00000] to [65535] (default: [60004]).

Note: To comply with the IEC standards, the following conditions are required.

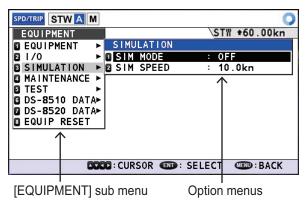
- [IP ADDRESS]: Set between [239.192.000.001] and [239.192.000.064].
- [PORT]: Set between [60001] and [60064]

## 3.3 [SIMULATION] sub menu

The simulation mode displays and outputs internally specified speed data. This mode can be used for simulation and to check output to external equipment. "SIM" appears on the screen when the simulation mode is active.



On the main menu, select [EQUIPMENT] →[SIMULATION] to open the [SIMULATION] sub menu.

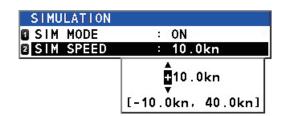


#### **SIM MODE**

Select [ON] to activate the simulation mode.

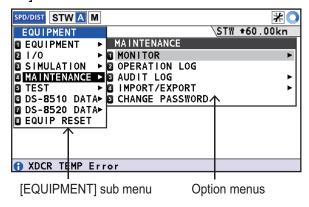
#### **SIM SPEED**

Select the speed to output from the transceiver unit in simulation mode. The setting range is [-10.0] to [40.0] kn (default: [+10.0] kn).



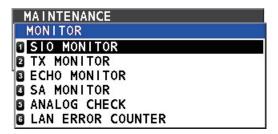
## 3.4 [MAINTENANCE] sub menu

On the main menu, select [EQUIPMENT] →[MAINTENANCE] to open the [MAINTENANCE] sub menu.



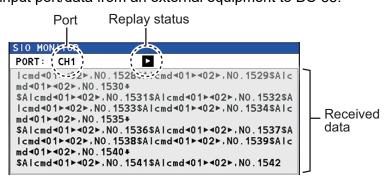
### 3.4.1 [MONITOR] menu

On the [MAINTENANCE] sub menu, select [MONITOR] to check the error status.



#### **[SIO MONITOR]**

Show the input port/data from an external equipment to DS-85.



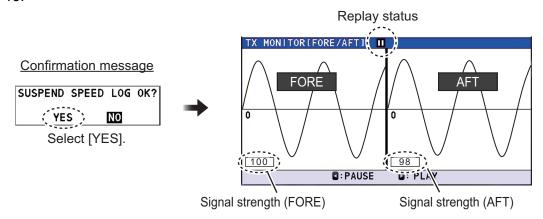
Note: The input data is shown in just one screen and it is not updated automatically.

- [Port]: Select the input port ([CH1] or [CH2]) when the replay status is "PAUSE".
- Replay status: means "PLAY", means "PAUSE"
- Received data: Shows the input data from the start in one screen. The latest data
  is shown the last row. If the data is full in one screen, the reply status becomes
  "PAUSE". Set the status to "PLAY" after "PAUSE", shows the data in one screen
  again.

#### [TX MONITOR]

Show the transmission wave for FORE and AFT. During displaying the transmission wave, the ship's speed is not calculated.

Select [TX MONITOR] then the confirmation massage appears. Select [YES] to show the [TX MONITOR]. To close the TX monitor, see "< MONITOR MENU >" on page 3-13.

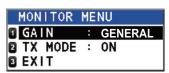


- Wave data for FORE and AFT: The left half is for FORE data, and the right half is for AFT data. The wave data for FORE and AFT are updated alternately every second.
- Replay status: means "PLAY", means "PAUSE". Press the ▶ key to start to update, and press the ◀ key to pause the update.

#### < MONITOR MENU >

The [MONITOR MENU] can set the gain setting or transmission mode.

- On the screen of [ECHO MONITOR] and [SA MONITOR] then press the MENU/ ESC key to show the [MONITOR MENU].
- Select [GAIN] or [TX MODE].

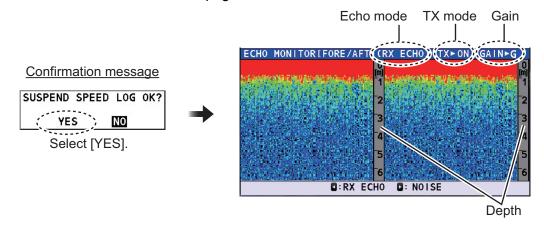


- [GAIN]: Set the gain level on each screen. The setting range is shown on the right-top of these screens as follows.
  - [GENERAL]: General use. [G] is shown on the screen.
  - [NOISE LEVEL]: For noise check. [N] is shown on the screen.
  - [INTERFERRENCE]: For interference check. [I] is shown on the screen.
- [TX MODE]: Set [OFF] to stop transmission.
- [EXIT]: Go back to [EQUIPMENT MENU].
- 3. After appropriate settings, select [EXIT] to go back to [EQUIPMENT MENU].

#### [ECHO MONITOR]

Show the color echo display according to the depth. During displaying the echo display, the ship's speed is not calculated.

Select [ECHO MONITOR] then the confirmation massage appears. Select [YES] to show the [ECHO MONITOR]. To close the Echo monitor, see "< MONITOR MENU >" on page 3-13.

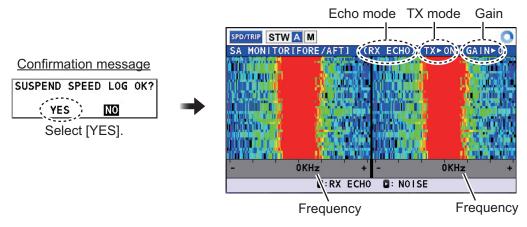


- Received echo data: The echo data is scrolled to the left and the latest data is shown at the right edge of each display screen. The display indicates echo strength in descending order of red>yellow>green>blue. The display changes with the echo mode as follows.
  - When the echo mode is [RX ECHO], the echo data on the transmitting side is displayed. The left half is data for FORE when transmitting on the FORE side, and the right half is data for AFT when transmitting on the AFT side.
  - When the echo mode is [NOISE], the echo data on the non-transmitting side is displayed. The left half is data for AFT when transmitting on the FORE side, and the right half is data for FORE when transmitting on the AFT side.
- Echo mode: Show the echo type. Press the ▶ key to show echo data for the speed calculating, and press the ◀ key to show the echo data for noise check.
- Depth: The vertical scale shows the depth according to the transducer setting.
- [TX]: The transmission mode which is set on the [MONITOR MENU] is shown. See "< MONITOR MENU >" on page 3-13 for details.
- [GAIN]: The gain level which is set on the [MONITOR MENU] is shown. See "< MONITOR MENU >" on page 3-13 for details.

#### [SA MONITOR]

Show the echo display to check the spectrogram for FORE and AFT. You can check the interference, noise, frequency or interval on this screen. During displaying the SA display, the ship's speed is not calculated.

Select [SA MONITOR] then the confirmation massage appears. Select [YES] to show the [SA MONITOR]. To close the SA monitor, see "< MONITOR MENU >" on page 3-13.

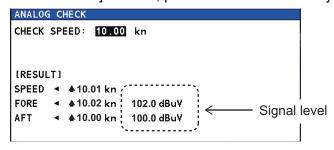


- Received echo data: The echo data is scrolled to the left and the latest data is shown at the right edge of each display screen. The display indicates echo strength in descending order of red>yellow>green>blue. The display changes with the echo mode as follows.
  - When the echo mode is [RX ECHO], the spectrogram on the transmitting side is displayed. The left half is spectrogram for FORE when transmitting on the FORE side, and the right half is spectrogram for AFT when transmitting on the AFT side.
  - When the echo mode is [NOISE], the spectrogram on the non-transmitting side
    is displayed. The left half is spectrogram for AFT when transmitting on the FORE
    side, and the right half is spectrogram for FORE when transmitting on the AFT
    side.
- Echo mode: Show the echo type. Press the ▶ key to show echo data for the speed calculating, and press the ◀ key to show the echo data for noise check.
- Frequency: The horizontal scale shows the frequency according to the transducer setting.
- [TX]: The transmission mode which is set on the [MONITOR MENU] is shown. See "< MONITOR MENU >" on page 3-13 for details.
- [GAIN]: The gain level which is set on the [MONITOR MENU] is shown.
   See "< MONITOR MENU >" on page 3-13 for details.

#### [ANALOG CHECK]

This screen is to check the analog circuit of the transceiver unit. For example, if you set 10 kn as ship's speed for test, check that 10 kn is displayed in the [RESULT]. If there is a discrepancy between this set value and the result, there may be a malfunction so contact your local dealer.

During displaying the [ANALOG CHECK] display, the ship's speed is not calculated. To go to the [MAINTENANCE] window, press the **MENU/ESC** key.



• [CHECK SPEED]: Set the ship's speed for test to check the analog circuit. The setting range is [-40.00] to [40.00] kn (default: [10.00] kn).

#### 3. ADJUSTMENTS

- [SPEED]: Show the ship's speed/direction which the transceiver unit outputs. This value is updated every second. The setting range is [↓ 99.99] to [↑ 99.99] kn. Ship direction is indicated as follows: [↑] means "Go forward" and [↓] means "Go backward".
- [FORE], [AFT]: Show the ship's speed/direction and signal level which the transducer of FORE (or AFT) outputs. When an analog circuit activates properly, the signal level is 35 to 40 dBuV. This value is updated every second. Ship direction is indicated as follows: [↑] means "Go forward" and [↓] means "Go afterward".

#### **[LAN ERROR COUNTER]**

This screen is to show the error status of LAN connection. To go [MAINTENANCE] window, press the **MENU/ESC** key.

- [UDP CHECKSUM ERROR]: Number of checksum errors in UDP headers.
- [INVALID HEADER]: Number of "UdPbC<NULL>" errors at the beginning of sentences.
- [INCORRECT TAG BLOCK]: Number of tag block structural errors.
- [TAG BLOCK CHECKSUM ERROR]: Number of checksum errors at the end of tag blocks.
- [TAG BLOCK SYNTAX ERROR]: Number of tag block format errors.
- [TAG BLOCK FRAMING ERROR]: Number of sentences with unexpected starts/ stops in the tag block.
- [INCORRECT SENTENCE]: Number of sentences in tag block with checksum errors or other errors.

## 3.4.2 [IMPORT/EXPORT] menu

Store and restore the settings if necessary. On the [MAINTENANCE] sub menu, select [IMPORT/EXPORT] menu. The USB flash memory should be connected before this menu is used.

#### **IEXPORT SETTING1**

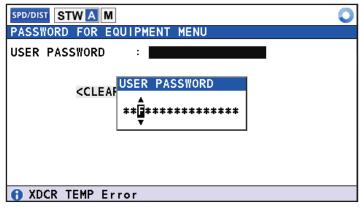
Store the setting of the equipment to the USB flash memory.

1. Connect an USB flash memory to the USB port.

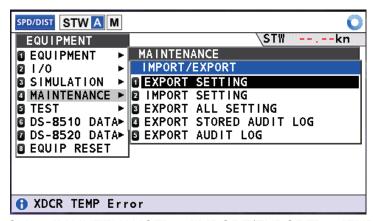
2. Press the **MENU/ESC** key to show the main menu.



3. Select the [EQUIPMENT] menu, then press the **ENT** key. The user password window appears.

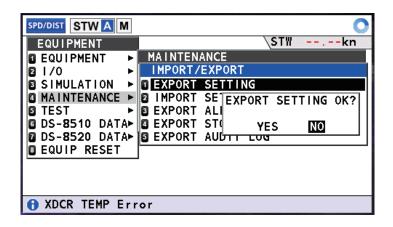


4. Enter the user password, then press the **ENT** key. The [EQUIPMENT] menu appears.



5. Select [MAINTENANCE]  $\rightarrow$  [IMPORT/EXPORT]  $\rightarrow$  [EXPORT SETTING], then press the **ENT** key.

The pop-up window appears.



#### 3. ADJUSTMENTS

Select [YES], then press the ENT key.
 The user backup data will be stored directly to the USB flash memory.
 Filename: root\(\frac{1}{2}\)DS-85 BACKUP USER.dat

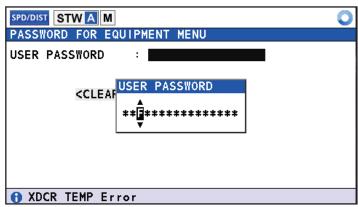
#### [IMPORT SETTING]

Restore the previously stored setting modes from the USB flash memory.

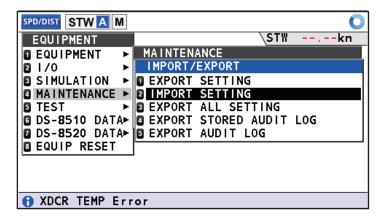
- Connect a USB flash memory with the stored user backup data to the USB port. (Filename: root\(\text{FIS-85\_BACKUP\_USER.dat}\))
- 2. Press the **MENU/ESC** key to show the main menu.



3. Select the [EQUIPMENT] menu, then press the **ENT** key. The user password window appears.

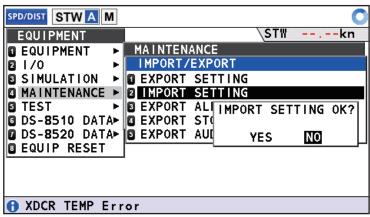


4. Enter the user password, then press the **ENT** key. The [EQUIPMENT] menu appears.



5. Select [MAINTENANCE]  $\rightarrow$  [IMPORT/EXPORT]  $\rightarrow$  [IMPORT SETTING], then press the **ENT** key.

The pop-up window appears.



Select [YES], then press the ENT key.The setting data is imported from the USB flash memory.

#### [EXPORT ALL SETTING]

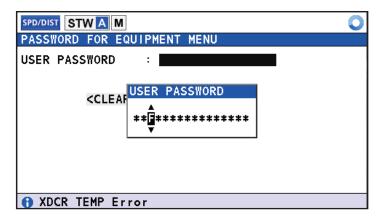
Stores all the settings including the service menu to the USB flash memory.

**Note:** To restore the settings, contact your service technician to import the backup data.

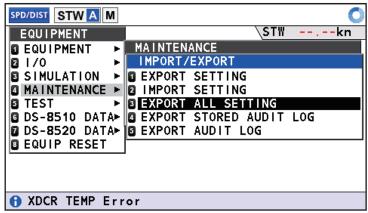
- 1. Connect the USB flash memory to the USB port.
- 2. Press the **MENU/ESC** key to show the main menu.



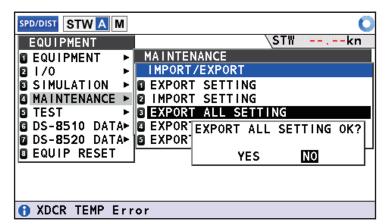
3. Select the [EQUIPMENT] menu, then press the **ENT** key. The user password window appears.



4. Enter the password, then press the **ENT** key. The [EQUIPMENT] menu appears.



 Select [MAINTENANCE] → [IMPORT/EXPORT] → [EXPORT ALL SETTING], then press the ENT key. The pop-up window appears.



Select [YES], then press the ENT key.
 The complete backup data is exported to the USB flash memory.
 Filename: root\(\frac{1}{2}\)DS-85\_BACKUP.dat

#### **[EXPORT STORED AUDIT LOG]**

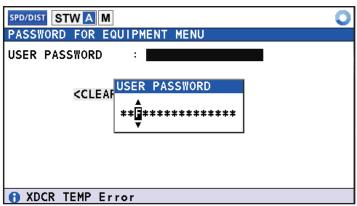
Exports the manually stored audit log to the USB flash memory.

**Note:** Refer to subsection 3.4.3 for how to store the audit log.

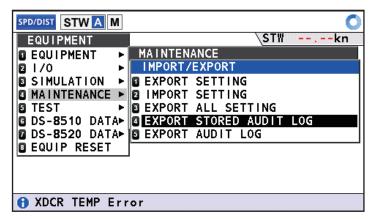
- 1. Connect an USB flash memory to the USB port.
- 2. Press the **MENU/ESC** key to show the main menu.



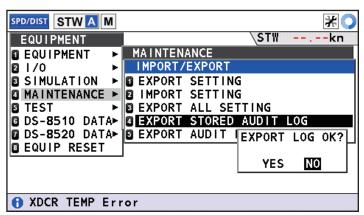
3. Select the [EQUIPMENT] menu, then press the **ENT** key. The user password window appears.



4. Enter the password, then press the **ENT** key. The [EQUIPMENT] menu appears.



 Select [MAINTENANCE] → [IMPORT/EXPORT] → [EXPORT STORED AUDIT LOG], then press the ENT key.
 The pop-up window appears.



6. Select [YES], then press the **ENT** key.

The stored audit log data is exported to the USB flash memory. Filename when date and time are entered: root\(\frac{1}{2}\)YYYMMDD\(\frac{1}{2}\)DIT\_-STORED\_YYYYMMDD hhmmss.log (YMDhms: Date\(\frac{1}{2}\)Time) Filename when date and time are not entered: root\(\frac{1}{2}\)HNO-DATE\(\frac{1}{2}\)DS-85\_AUDIT\_-STORED\_ssssssssss.log (s: Operating time (seconds))

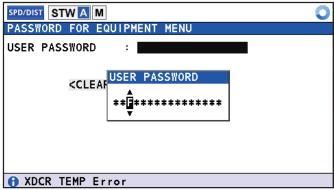
#### **[EXPORT AUDIT LOG1**

Exports the audit log to the USB flash memory.

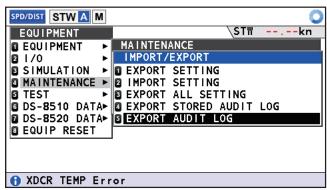
- Connect an USB flash memory to the USB port.
- 2. Press the **MENU/ESC** key to show the main menu.



3. Select the [EQUIPMENT] menu, then press the **ENT** key. The user password window appears.

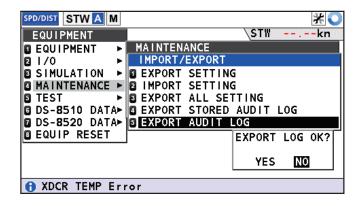


4. Enter the password, then press the **ENT** key. The [EQUIPMENT] menu appears.



5. Select [MAINTENANCE]  $\rightarrow$  [IMPORT/EXPORT]  $\rightarrow$  [EXPORT AUDIT LOG], then press the **ENT** key.

The pop-up window appears.



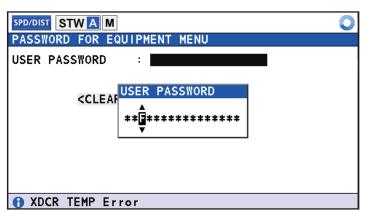
### 3.4.3 [STORE AUDIT LOG] menu

Stored the audit logs saved in the DS-85 to a specific area of internal memory of the DS-85.

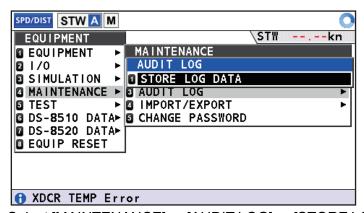
1. Press the **MENU/ESC** key to show the main menu.



2. Select the [EQUIPMENT] menu, then press the **ENT** key. The user password window appears.



3. Enter the password, then press the **ENT** key. The [EQUIPMENT] menu appears.

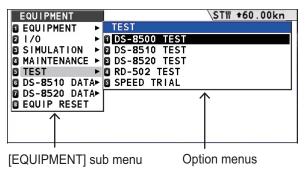


 Select [MAINTENANCE] → [AUDIT LOG] → [STORE LOG DATA], then press the ENT key.

The recent audit log is stored to a specific area of internal memory of the DS-85.

## 3.5 [TEST] menu

On the main menu, select [EQUIPMENT] →[TEST] to open the option menus of [TEST] sub menu.



## 3.5.1 [DS-8500 TEST] menu

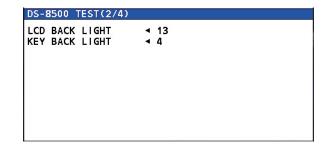
The test result of Display Unit DS-8500, the equipment information, ROM/RAM test or serial port test etc., is shown on this menu. The test result has four pages.

#### [DS-8500 TEST (1/4)]: page 1



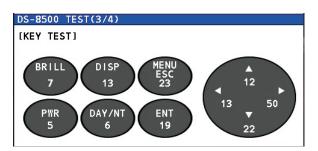
Item	Meaning	Range
[SERIAL NO.]	Serial number of display unit	[000000] to [999999]
[STATER VERSION]	Starter version of display unit	[6550302-01.01] to [6550302-99.99]
[BOOT VERSION]	<ul> <li>Upper: Booter version used for start-up of display unit.</li> <li>Lower: Booter version not used (back-up) for start-up of display unit</li> </ul>	[6550303-01.01] to [6550303-99.99]
[APPLICATION VERSION]	Application version of display unit	[6550304-01.01] to [6550304-99.99]
[ROM/RAM]	Result of ROM test/Result of RAM test	[OK] or [NG]
[PORT]	Result of serial port	[OK] or blank
[LCD TOTAL TIME]	Total operation hours of LCD.	[0] to [999999] (h)
[12 VOLT]	Voltage value of display unit	[0.0] to [99.9] (V)
► key	Go to page 2 of the [DS-8500 TEST].	
MENU/ESC key	Go back to [EQUIPMENT] sub menu.	

## [DS-8500 TEST (2/4)]: page 2



ltem	Meaning	Range
[LCD BACK LIGHT]	Automatic brilliance test of LCD is started. The brilliance is changed according to the displayed value.	[0] to [17] (First value: [17])
[KEY BACK LIGHT]	Brilliance of key back light	[0] to [17] (default: [0])
<b>▶</b> key	Go to page 3 of the [DS-8500 TEST].	
MENU/ESC key	Go back to [EQUIPMENT] sub menu.	

# [DS-8500 TEST (3/4)]: page 3



Each key is shown in gray. The color changes to red when the corresponding key is pressed, then changes to blue color when the key is released.

The number of times the key has been tested is shown under each key name.

Press the ▶ key three times to show the fourth page of [DS-8500 TEST]. You can also to press the **MENU/ESC** key three times to return the [TEST] sub menu.



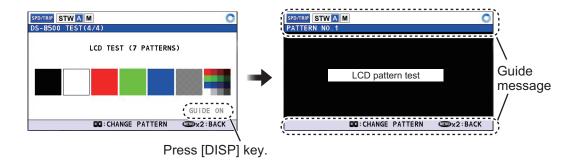
Number of times for key check

#### [DS-8500 TEST (4/4)]: page 4

By pressing the ▶ key, switch the selection of the display color type; Black→White→Red→Green→Blue→Gray→Multi (◀ key: reverse sequence).

To check the guide message display, press the **DISP** key.

# 3. ADJUSTMENTS



# 3.5.2 DS-8510 TEST

The test result of distributor unit DS-8510, the equipment information, ROM/RAM test etc., is shown on this menu. The test result has three pages.

# [DS-8510 TEST (1/3)]: page 1

CERIAL NO	4004 5450 0040
SERIAL NO.	1234-5678-9012
STARTER VERSION	<ul><li>XXXXXXXX-01.01 (20XX1213)</li></ul>
BOOT VERSION	▼ XXXXXXX-01.01 (20XX1213)
	XXXXXXX-01.01 (20XX1213)
APPLICATION VERSION	▼ XXXXXXXX-01.01 (20XX1213)
	XXXXXXX-01.01 (20XX1213)
DST VERSION	<b>◀</b> 1
LIF VERSION	<b>▼</b> 1
ROM / RAM	◆ OK/OK

Item	Meaning	Range
[SERIAL NO.]	Serial number of distributor unit	[0000-0000-0000] to [9999-9999-9999]
[STARTER VERSION]	Starter version of distributor unit	[6550306-01.01] to [6550306-99.99]
[BOOT VERSION]	<ul> <li>Upper: Booter version used for start-up of the distributor unit.</li> <li>Lower: Booter version not used (backup) for start-up of the distributor unit.</li> </ul>	[6550307-01.01] to [6550307-99.99]
[APPLICATION VERSION]	<ul> <li>Upper: Application version used for start-up of the distributor unit.</li> <li>Lower: Application version not used (backup) for start-up of the distributor unit.</li> </ul>	[6550308-01.01] to [6550308-99.99]
[DST VERSION]	DIST board version	[0] to [E], [-] (NG)
[LIF VERSION]	LIF board version	[0] to [E]
[ROM/RAM]	Result of ROM test/Result of RAM test	[OK] or [NG]
<b>▶</b> key	Go to page 2 of the [DS-8510 TEST].	
MENU/ESC key	Go back to [TEST] sub menu.	

# [DS-8510 TEST (2/3)]: page 2

DS-8510 TEST(2/3)	
IP ADDRESS	<b>◀</b> 172. 031. 016. 123
SUBNET MASK	<b>◄</b> 255. 255. 000. 000
GATEWAY	◀ 172. 031. 001. 001
MAC ADDRESS	■ 00 : D0 : 1D : 3E : 99 : 2F
DIPSW	◀ S3:0000 S4:0000
TOTAL TIME	◀ 21h
FAN RPM	◀ 4500 rpm
INTERNAL TEMPERATURE	◀ 30 . 1 °C
5 YOLT	◀ 5.0V
12 VOLT	◀ 12. 2V

Item	Meaning	Range
[IP ADDRESS]	IP address of distributor unit	[000.000.000.000] to
		[255.255.255.255]
[SUBNET MASK]	Subnet mask of distributor unit	[000.000.000.000] to
		[255.255.255.255]
[GATEWAY]	Gateway of distributor unit	[000.000.000] to
		[255.255.255.255]
[MAC ADDRESS]	MAC address of distributor unit	[00:00:00:00:00] to
		[FF:FF:FF:FF:FF]
[DIPSW]	Status DISPSW of distributor unit	S3: [0000] to [1111]
		S4: [0000] to [1111]
[TOTAL TIME]	Total time for operation of distributor unit	[0] to [999999]
[FAN RPM]	Revolution of FAN	
[INTERNAL	Temperature for board of distributor unit	[-99.9] to [999.9] (°C)
TEMPERATURE]		
[5 VOLT]	Voltage of 5 V for distributor unit	[0.0] to [99.9]
[12 VOLT]	Voltage of 12 V for distributor unit	[0.0] to [99.9]
<b>▶</b> key	Go to page 3 of the [DS-8510 TEST].	
MENU/ESC key	Go back to [TEST] sub menu.	

# [DS-8510 TEST (3/3)]: page 3

[\$10]		[USB]		
CH1		USB R/W	•	
CH2				
DS-8520	→ OK			
MAIN				
SUB1				
SUB2				
RD-502	d OK			

Item	Meaning	Range
[SIO]: SIO communication test		
[CH1]	Result of CH1 communication test	[OK] or blank
[CH2]	Result of CH2 communication test	[OK] or blank
[DS-8520]	Result of transceiver unit communication	[OK] or blank
[MAIN]	Result of MAIN communication	[OK] or blank
[SUB1]	Result of SUB1 communication	[OK] or blank
[SUB2]	Result of SUB2 communication	[OK] or blank
[RD-502]	Result of RD-502 communication	[OK] or blank
[USB]: USB communication test		
[USB R/W]	Check if reading or writing to USB	[OK] or blank
MENU/ESC key	Go back to [TEST] sub menu.	

# 3.5.3 DS-8520 TEST

The test result of Transceiver Unit DS-8520, the equipment information, ROM/RAM test results or serial port test result etc., is shown on this menu. The test result has three pages.

# [DS-8520 TEST (1/3)]: page 1

DS-8520 TEST(1/3)	
SERIAL NO. STARTER VERSION BOOT VERSION  APPLICATION VERSION FPGA VERSION MAIN VERSION TRX VERSION TRX VERSION ROM / RAM BUBBLE	<ul> <li>■ 345678</li> <li>■ XXXXXXX-01.01 (20XX1213)</li> <li>■ XXXXXXX-01.01 (20XX1213)</li> <li>■ XXXXXXX-01.01 (20XX1213)</li> <li>■ XXXXXXX-01.01 (20XX1213)</li> <li>■ A</li> <li>■ B</li> <li>■ 0K/0K</li> <li>■ 123</li> </ul>

ltem	Meaning	Range
[SERIAL NO.]	Serial number of transceiver unit	[000000] to [999999]
[STARTER VERSION]	Starter version of transceiver unit	[6550311-01.01] to [6550311-99.99]
[BOOT VERSION]	<ul> <li>Upper: Booter version used for start-up of the transceiv- er unit .</li> <li>Lower: Booter version not used (backup) for start-up of the transceiver unit</li> </ul>	[6550312-01.01] to [6550312-99.99]
[APPLICATION VERSION]	Application version of transceiver unit.	[6550313-01.01] to [6550313-99.99]
[FPGA VERSION]	FPGA version	[6550314-01.01] to [6550314-99.99]
[MAIN VERSION]	Main board version	[0] to [E], [–] (NG)
[TRX VERSION]	TRX board version	[0] to [E], [–] (NG)
[ROM/RAM]	Result of ROM test/Result of RAM test	[OK] or [NG]
[BUBBLE]	Value of bubble effects ([5] or less ideally)	[0] to [255]
<b>▶</b> key	Go to page 2 of the [DS-8520 TEST].	
MENU/ESC key	Go back to [TEST] sub menu.	

# [DS-8520 TEST (2/3)]: page 2

IP ADDRESS	◀ 192 . 168 . 200 . 001
SUBNET MASK	◀ 255 . 255 . 255 . 000
GATEWAY	■ 000 . 000 . 000 . 000
MAC ADDRESS	◆ FF : FF : FF : FF : FF : FF
DIPSW	4 S2:0001 S3:0000 S5:0000
TOTAL DIST	◆ 0.04NM

Item	Meaning	Range
[IP ADDRESS]	IP address of transceiver unit	[000.000.000.000] to [255.255.255.255]

ltem	Meaning	Range
[SUBNET MASK]	Subnet mask of transceiver unit	[000.000.000] to
		[255.255.255.255]
[GATEWAY]	Gateway of transceiver unit	[000.000.000] to
		[255.255.255.255]
[MAC ADDRESS]	MAC address of transceiver unit	[00:00:00:00:00] to
		[FF:FF:FF:FF:FF]
[DIPSW]	Status DIP switch of transceiver unit	S2: [0000] to [1111]
		S3: [0000] to [1111]
		S5: [0000] to [1111]
[TOTAL DIST]	Total distance	[0.00] to [999999.99]
<b>▶</b> key	Go to page 3 of the [DS-8520 TEST].	
MENU/ESC key	Go back to [TEST] sub menu.	

# [DS-8520 TEST (3/3)]: page 3

```
DS-8520 TEST(3/3)

XDCR TEMPERATURE

TRX TEMPERATURE

$\frac{4}{25}.5V$

$\frac{5}{0V}$

12 YOLT

$\frac{4}{25}.5V$

$\frac{12}{1VA}/11.9VD$

$\frac{25}{40}$

FAN RPM

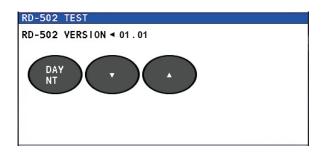
$\frac{4}{4803} \text{rpm}

NOISE LEVEL ( FORE / AFT ) $\frac{4}{32}.14/ $\frac{4}{32}.22kn
```

ltem	Meaning	Range
[XDCR TEMPERATURE]	Temperature of Transducer	[-99.9] to [999.9]
		([]: circuit error, or no
		connection to transducer)
[TRX TEMPERATURE]	Temperature of TRX board	[-99.9] to [999.9]
	on Transducer	
[PWR TEMP]	Temperature of PWR board	[-99.9] to [999.9]
	for transceiver unit	
[B VOLT]	B voltage of transceiver unit	[0.0] to [99.9]
[5 VOLT]	Voltage of 5 V for transceiv-	[0.0] to [99.9]
	er unit	
[12 VOLT]	Voltage of 12 V for trans-	[0.0] to [99.9]
	ceiver unit	
[24 VOLT]	Voltage of 24 V for trans-	[0.0] to [99.9]
	ceiver unit	
[FAN RPM]	Revolution of FAN	[0] to [999999]
[NOISE LEVEL (FORE/	Noise level of FORE/AFT	[-20] to [120.0]
AFT)]	transducer	
[SPEED (FORE/AFT)]	Measured ship's speed	[-99.99] to [99.99]
	(FORE/AFT)	
MENU/ESC key	Go back to [TEST] sub menu	

# 3.5.4 RD-502 TEST

Check the connection between DS-85 and the optional Dimmer RD-502.

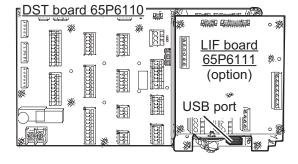


Item	Meaning
[RD-502 VERSION]	Version of RD-502
DAY/NT key	By pressing <b>DAY/NT</b> key of RD-502, changed figure color red $\rightarrow$ blue $\rightarrow$ red
<b>▼</b> key	By pressing ▼ key of RD-502, changed figure color red → blue → red
▲ key	By pressing $\blacktriangle$ key of RD-502, changed figure color red $\to$ blue $\to$ red
MENU/ESC key	Go back to [TEST] sub menu.

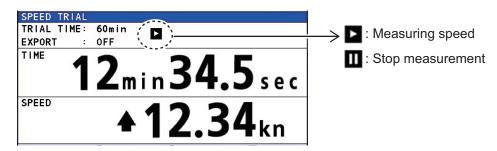
# 3.5.5 SPEED TRIAL

Show the average ship's speed for the specified period. Set the trial time then press the ▶ key to start the trial. To stop the trial test, press the ◀ key. If a USB flash memory is connected to the distributor unit, the distributor unit outputs the trial result.

**Note:** To output the results to a USB flash memory, connect a USB to the



USB port in the distributor unit (shown the in figure above-right).



Item	Meaning	Range
[TRIAL TIME]	Trial time (min)	[10] to [60]
[EXPORT]	Set [ON] to export the measurement result to an USB device.	[ON] or [OFF]
[TIME]	Elapsed time from trial start	[00 min 00.0 sec] to [60 min 00.0 sec]

ltem	Meaning	Range
[SPEED] or [SPEED (AVERAGE)]	[SPEED]: Ship's speed at that moment during measurement [SPEED (AVERAGE)]: Average ship's speed during measurement  The unit of measurement can be changed in the [UNIT] menu (Main menu→[DISPLAY]→[UNIT]).	[\$\frac{99.999}{99.999}]
<b>⋖</b> key	Stop measurement	
<b>▶</b> key	Start measurement	
MENU/ESC key	Go back to [TEST] sub menu.	

Use this menu as follows:

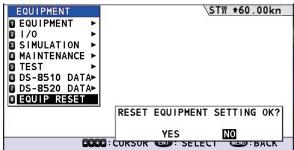
- 1. Set a longer time at [TRIAL TIME].
- 2. Set [ON] at [EXPORT].
- 3. Press ▶ key to start ship's speed measurement. If a USB device is connected to the distributor unit, exporting measurement result to a USB device begins.
- 4. Press ◀ key to stop ship's speed measurement. Record the average ship's speed shown. If a USB device is connected to the distributor unit, exporting is stopped.

# 3.6 [DS-8510 DATA]/[DS-8520 DATA] sub menu

These menus are for service technician only. Contact your local dealer for details.

# 3.7 [EQUIP RESET] sub menu

This menu can reset the all [EQUIPMENT] menu settings. On the main menu, select [EQUIPMENT] →[EQUIP RESET] to show the confirmation message below.



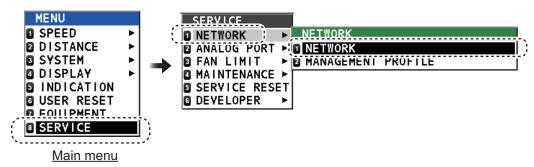
Select [YES] on the confirmation message to reset all settings of the [EQUIPMENT] menu.

# 3.8 How to Set SFI

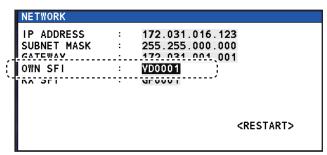
Open the [SERVICE] menu then set own SFI.

1. Select the [SERVICE] menu on the main menu. To open the [SERVICE] menu, a password is required. For the password, ask our service technician.

Select [NETWORK] → [NETWORK] to show the [NETWORK] window.



Move the cursor the item for [OWN SFI] on the [NETWORK] window.



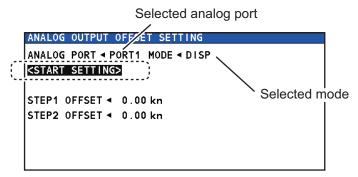
- 4. Set the SFI number for this equipment. SFI numbers contain six characters, two letters and four digits. The setting range is [AA0001] to [ZZ9998].
- 5. After setting, press the **ENT** key. The confirmation message "PLEASE RESTART IN ORDER TO UPDATE SETTING." appears.
- 6. Select [RESTART] to update the SFI.

# 3.9 How to Offset for Analog Port

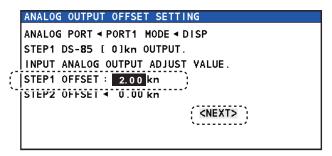
Set the offset value for the analog output port.

- 1. Select the [SERVICE] menu on the main menu. To open the [SERVICE] menu, a password is required. For the password, ask our service technician.
- Select [ANALOG PORT] and then set the analog port ([PORT1] to [PORT4)] to set
- 3. Select [MODE] and then select the type of analog port.
  - [DISCONNECT]: For no connection to analog port (default).
  - [DISP1]: For analog display unit of range to 30 kn
  - [DISP2]: For analog display unit of range to 40 kn
  - [DISP3]: For analog display unit of range to 20 kn
  - [CUR]: For analog current signal (4 to 20 mA). The corresponding ship speed is -10 to 30 kn.
  - [VOLT]: For analog voltage signal (-3.3 to 10 V). The corresponding ship speed is -10 to 30 kn.
- 4. Select the analog port to offset then the setting window appears. The offset setting window to be set depends on the analog port.
  - [DISP]: Set for PORT1 to PORT4.
  - [CURRENT]: Set for PORT3 to PORT4.
  - [VOLTAGE]: Set for PORT4 only.

5. Select [START SETTING] to show the confirmation message "START SETTING OK?". Then select [YES] to start setting. To stop setting, press the **MENU** key to go back to the [SERVICE] menu.

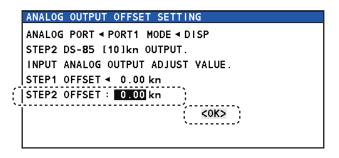


6. Set the offset value in the [STEP1 OFFSET] field so that the needle of the analog display unit will be "**0** kn", and click [NEXT]. The setting range is -4.9 to 4.9 kn. To stop setting, press the **MENU** key to go back to the [SERVICE] menu. For example, when the analog display unit indicates 2 kn, set "2" (kn) on this window so that the analog display unit indicates 0 kn.



7. Set the offset value in the [STEP2 OFFSET] field so that the needle of the analog display unit will be "10 kn", and click [OK] to complete setting. The setting range is -4.9 to 4.9 kn. To stop setting, press the **MENU** key to go back to the [SERVICE] menu.

For example, when the analog display unit indicates 9 kn, set "-1" (kn) on this window so that the analog display unit indicates 10 kn.



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# **APPX. 1 JIS CABLE GUIDE**

Cables listed in the manual are usually shown as Japanese Industrial Standard (JIS). Use the following guide to locate an equivalent cable locally.

JIS cable names may have up to 6 alphabetical characters, followed by a dash and a numerical value (example: DPYC-2.5).

For core types D and T, the numerical designation indicates the *cross-sectional Area (mm²)* of the core wire(s) in the cable.

For core types M and TT, the numerical designation indicates the *number of core wires* in the cable.

1. Core Type

2. Insulation Type

3. Sheath Type

D: Double core power line

P: Ethylene Propylene Rubber Y: PV

Y: PVC (Vinyl)

T: Triple core power line

M: Multi core

C: Steel

TT: Twisted pair communications (1Q=quad cable)

4. Armor Type

5. Sheath Type

6. Shielding Type
SLA: All cores in one shield, plastic tape w/aluminum tape

Y: Anticorrosive vinyl sheath

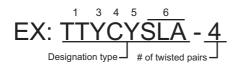
-SLA: Individually shielded cores, plastic tape w/aluminum tape

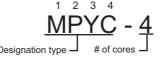












The following reference table lists gives the measurements of JIS cables commonly used with Furuno products:

Core Cable		Cable			Co	ore	Cable	
Туре	Area	Diameter	Diameter	L	Туре	Area	Diameter	Diameter
DPYC-1.5	1.5mm <sup>2</sup>	1.56mm	11.7mm		TTYCSLA-1	0.75mm <sup>2</sup>	1.11mm	9.4mm
DPYC-2.5	2.5mm <sup>2</sup>	2.01mm	12.8mm		TTYCSLA-1T	$0.75 \text{mm}^2$	1.11mm	10.1mm
DPYC-4	4.0mm <sup>2</sup>	2.55mm	13.9mm		TTYCSLA-1Q	$0.75 \text{mm}^2$	1.11mm	10.8mm
DPYC-6	6.0mm <sup>2</sup>	3.12mm	15.2mm		TTYCSLA-4	$0.75 \text{mm}^2$	1.11mm	15.7mm
DPYC-10	10.0mm <sup>2</sup>	4.05mm	17.1mm		TTYCY-1	$0.75 \text{mm}^2$	1.11mm	11.0mm
DPYCY-1.5	1.5mm <sup>2</sup>	1.56mm	13.7mm		TTYCY-1T	$0.75 \text{mm}^2$	1.11mm	11.7mm
DPYCY-2.5	2.5mm <sup>2</sup>	2.01mm	14.8mm		TTYCY-1Q	$0.75 \text{mm}^2$	1.11mm	12.6mm
DPYCY-4	4.0mm <sup>2</sup>	2.55mm	15.9mm		TTYCY-4	$0.75 \text{mm}^2$	1.11mm	17.7mm
MPYC-2	1.0mm <sup>2</sup>	1.29mm	10.0mm		TTYCY-4SLA	$0.75 \text{mm}^2$	1.11mm	19.5mm
MPYC-4	1.0mm <sup>2</sup>	1.29mm	11.2mm		TTYCYSLA-1	$0.75 \text{mm}^2$	1.11mm	11.2mm
MPYC-7	1.0mm <sup>2</sup>	1.29mm	13.2mm		TTYCYSLA-4	$0.75 \text{mm}^2$	1.11mm	17.9mm
MPYC-12	1.0mm <sup>2</sup>	1.29mm	16.8mm		TTPYCSLA-1	$0.75 mm^2$	1.11mm	9.2mm
TPYC-1.5	1.5mm <sup>2</sup>	1.56mm	12.5mm		TTPYCSLA-1T	$0.75 \text{mm}^2$	1.11mm	9.8mm
TPYC-2.5	2.5mm <sup>2</sup>	2.01mm	13.5mm		TTPYCSLA-1Q	$0.75 \text{mm}^2$	1.11mm	10.5mm
TPYC-4	4.0mm <sup>2</sup>	2.55mm	14.7mm		TTPYCSLA-4	$0.75 \text{mm}^2$	1.11mm	15.3mm
TPYCY-1.5	1.5mm <sup>2</sup>	1.56mm	14.5mm					
TPYCY-2.5	2.5mm <sup>2</sup>	2.01mm	15.5mm					
TPYCY-4	4.0mm <sup>2</sup>	2.55mm	16.9mm					

# **APPX. 2 DIGITAL INTERFACE**

# Priority for input data/sentences

Sentence (Priority)	Contents
GNS>GGA>RMC>GLL	Position
VTG>RMC	Speed over ground
VTG>RMC	Course over ground
ZDA	Date

# Priority for ports

LAN > Serial (CH1) > Serial (CH2)

# **Digital Interface**

Input sentences: ACN, GGA, RMC, VTG, ZDA

• Output sentences: ALC, ALF, ALR, POS, VBW, VHW, VLW

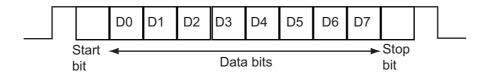
• Transmission interval: 1 s for VBW, VHW, VLW

#### Data transmission

Data is transmitted in serial asynchronous form in accordance with the standard referenced in 2.1 of IEC 61162-1/2. The first bit is a start bit and is followed by data bits, least-significant-bit as illustrated below.

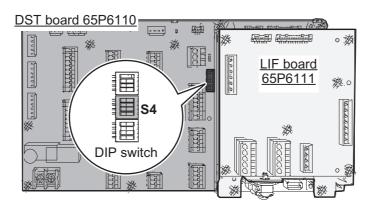
The following parameters are used: Baud rate: 38400 bps/4800 bps Data bits: 8 (D7 = 0), parity none

Stop bits: 1



#### · Data digit

The ship's speed data (VBW, VHW) has two digits after the decimal point (default setting). To change digit after the decimal point, set S4 of the DIP switch to ON on the DST board of the distributor unit.



# Sentence description

#### Input sentences

#### **ACN - Alert command**

- 1. Time (No use)
- 2. Manufacturer mnemonic code (3 characters, null)
- 3. Alert Identifier (000 9999999)
- 4. Alert Instance (0 999999, null)
- 5. Alert command (A,Q,O,S)

A=acknowledge

Q=request/repeat information

O=responsibility transfer

S=silence

Sentence status flag(C) (fixed)

# GGA - Global Positioning System (GPS) fix data

\$\*\*GGA,hhmmss.ss,llll.ll,a,yyyyy,yy,a,x,xx,x.x,x.x,M,x.x,M,x.x,xxxx\*hh<CR><LF>
 1 2 3 4 5 6 7 8 9 10 11 12 13 14

- 1. UTC of position (No use)
- 2. Latitude (No use)
- 3. N/S (No use)
- 4. Longitude (No use)
- 5. E/W (No use)
- 6. GPS quality indicator (1 to 5)
- 7. Number of satllite in use (No use)
- 8. Horizontal dilution of precision (No use)
- 9. Antenna altitude (No use)
- 10. Unit (No use)
- 11. Geoidal separation (No use)
- 12. Unit (No use)
- 13. Age of differential GPS data (No use)
- 14. Differential reference station ID (No use)

#### RMC - Recommended minimum specific GNSS data

- 1. UTC of position fix (No use)
- 2. Status (A=data valid)
- 3. Latitude (No use)
- 4. N/S (No use)
- 5. Longitude (No use)
- 6. E/W (No use)
- 7. Speed over ground, knots (0.00 999.99)
- 8. Course over ground, degrees true (0.00 359.99)
- 9. Date (No use)
- 10. Magnetic variation, degrees (No use)
- 11. E/W (No use)
- 12. Mode indicator (A=Autonomous mode D=Differential mode F=Float RTK P=Precise R=Real time kinematic)
- 13. Navigational status indication (S=Safe)

## VTG - Course over ground and ground speed

\$\*\*VTG,x.x,T,x.x,M,x.x,N,x.x,K,a\*hh <CR><LF>
1 2 3 4 5 6 7 8 9

- 1. Course over ground, degrees True (0.00 to 359.99)
- 2. T=True (fixed)
- 3. Course over ground, degrees Magnetic (No use)
- 4. M=Magnetic (fixed)
- 5. Speed over ground, knots (0.00 to 999.99)
- 6. N=Knots (fixed)
- 7. Speed over ground (0.00 to 999.99)
- 8. K=km/h (fixed)
- 9. Mode indicator (A=Autonomous, D=Differential P=Precise)

#### **ZDA - Time and date**

\$--ZDA,hhmmss.ss,xx,xx,xxx,xxx,xx\*hh<CR><LF>

1 2 3 4 5 6

- 1. UTC (000000 to 235959.99)
- 2. Day (01 to 31, UTC)
- 3. Month (01 to 12, UTC)
- 4. Year (0000 to 9999, UTC)
- 5. Local zone, hours (No use)
- 6. Local zone, minutes (No use)

# **Output sentences**

# ALC - Cyclic alert list

\$\*\*ALC,xx,xx,xx, aaa,x.x,x.x,x.x,'''''\*hh<CR><LF>
1 2 3 4 5 6 7 8 9

- 1. Total number of sentences this message (01 to 99)
- 2. Sentence number (01 to 99)
- 3. Sequential message identifier (00 to 99)
- 4. Number of alert entries (0 to 3)
- 5. Manufacturer mnemonic code (FEC)
- 6. Alert identifier (211000 to 211999)
- 7. Alert instance (1 to 2, null)
- 8. Revision counter (1 to 99)
- 9. Additional alert entries (same as #5 to #8)

#### **ALF - Alert sentence**

\$\*\*ALF,x,x,x,hhmmss.ss,a,a,a,aaa,x.x,x.x,x.x,x,c--c\*hh<CR><LF>

123 4 567 8 9 10 11 12 13

- 1. Total number of ALF sentences this message (1, 2)
- 2. Sentence number (1, 2)
- 3. Sequential message identifier (0 to 9)
- 4. Time of last change (hhmmss.ss, hh: 00 to 23, mm: 00 to 59, ss.ss: 00.00 to 59.99, null)
- 5. Alert category (B=Alert category B, null when #2 is 2)
- 6. Alert priority (C=Caution, null when #2 is 2)
- 7. Alert state (A=ACked, N=Normal state, null when #2 is 2)
- 8. Manufacturer mnemonic code (FEC)
- 9. Alert identifier (211000 to 211999)
- 10. Alert instance (1 to 2, null)
- 11. Revision counter (1 to 99)
- 12. Escalation counter (0 to 9)
- 13. Alert text (max. 16 characters)

#### **ALR - Set Alarm State**

- 1. Time of alarm condition change, UTC (hhmmss.ss, hh: 00 to 23, mm: 00 to 59, ss.ss: 00.00 to 59.99, null)
- 2. Unique alarm number (identifier) at alarm source (000 to 999, null when no alarm)
- 3. Alarm condition (A=threshold exceeded, V=not exceeded)
- 4. Alarm acknowledge state (A=acknowledged, V=not acknowledged)
- 5. Alarm description text (alphanumeric)

# POS - Device position and ship dimensions report or configuration command

\$\*\*POS,cc,xx,a,x.x,x.x,x.x,a,x.x,x.x,a\*hh <CR><LF>

- 1 2 3 4 5 6 7 8 9 10
- Equipment Identification (VD)
   Equipment number (01 to 99)
- 3. Position validity flag (A=Valid)
- 4. Position X-coordinate (-999.9 to 999.9)
- 5. Position Y-coordinate (0.0 to 999.9)
- 6. Position Z-coordinate (null)
- 7. Ship's width/length (V=Invalid)
- 8. Ship's width (null)
- 9. Ship's length (null)
- 10. Sentences status flag (R=Sentence is status report of current settings)

# VBW - Dual ground/water speed

\*\*VBW, x. x, x. x, A, x. x, A \* hh < CR > < LF >

1 2 3 4 5 6 7 8 9 10

- 1. Longitudinal water speed, knots (-999.9 to 999.9 (or -999.99 to 999.99), null)
- 2. Transverse water speed, knots (null)
- 3. Status: water speed (A=Data valid V=Data invalid)
- 4. Longitudinal ground speed, knots (null)
- 5. Transverse ground speed, knots (null)
- 6. Status: ground speed (V=Data invalid)
- 7. Stern transverse water speed, knots (null)
- 8. Status: stern water speed (V=Data invalid)
- 9. Stern transverse ground speed, knots (null)
- 10. Status: stern ground speed (V=Data invalid)

#### VHW - Water speed and heading

\$\*\*VHW,x.x,T,x.x,M,x.x,N,x.x,K\*hh <CR><LF>

1 2 3 4 5 6 7 8

- 1. Heading, degrees True (null)
- 2. T=True (fixed)
- 3. Heading, degrees Magnetic (null)
- 4. M=Magnetic (fixed)
- 5. Speed, knots (-999.9 to 999.9 (or -999.99 to 999.99), null)
- 6. N=Knots (fixed)
- 7. Speed, km/hr (-999.9 to 999.9 (or -999.99 to 999.99), null)
- 8. K=km/hr (fixed)

# VLW - Dual ground/water distance

\$\*\*VLW,x.x,N,x.x,N,x.x,N,x.x,N\*hh<CR><LF>
 1 2 3 4 5 6 7 8

- 1. Total cumulative water distance (0.00 to 2147483.65, null)
- 2. N=Nautical miles
- 3. Water distance since reset (0.00 to 2147483.65, null)
- 4. N=Nautical miles
- 5. Total cumulative ground distance (null)
- 6. N=Nautical miles
- 7. Ground distance since reset (null)
- 8. N=Nautical miles

# APPX. 3 CALIBRATION

For an accurate display of speed, a speed trial test to find the difference between your actual speed and the speed calculated by the equipment is necessary. Since DS-85 can measure only the speed against water, calibration is performed using round trip data in the same sea area to minimize the effect of tidal currents.

**Note:** To obtain accurate offset values, it is recommended to conduct the test using similar conditions and speeds to a regular voyage.

# Calibration from the speed trial

Calibration values can be calculated by comparing the doppler speed log with DGPS or other similar speed measuring devices.

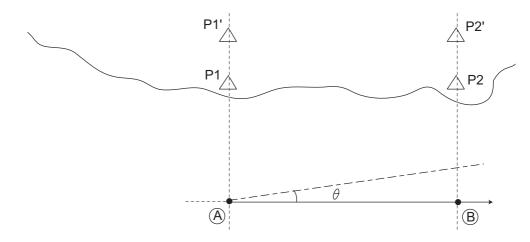
# 1) Calibration from the speed trial

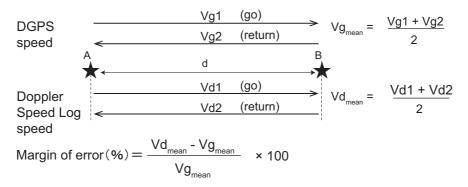
Speed trial result conducted using a GPS milepost may differ depending on the shipyard'smeasurement methods, as shown below:

- a) The ship's speed is calculated based on the time traveled.
- b) The ship's fore/aft (Y-axis) speed is calculated based on the time traveled.
- c) Calculation is based on a one-mile course, traveled three times.
- d) Calculation is based on the time traveled over a predetermined time.

Offset calculation for the above methods is described below.

a) Calculate the ship's speed with the measured total time of trip distance Vectors are combined to calculate the ship speed. The DS-85 can only measure the speed of the ship bow and stern, so errors may occur depending on the sea conditions. Steer the ship at a steady speed for 10 minutes or longer on the test course (EG: A to B in the figure). The ship's speed data is collected as VBW fore/aft speed (taken immediately after switching to water-based speed) data.Calculate the error with the average speed, from the GPS mile post meter and the speed data which DS-85 outputs, then enter the correction value so that the error are eliminated.





Where; d: distance run (NM), Vg1, Vg2: GPS measured speed (kn), Vd1, Vd2: doppler speed log measured speed (kn).

By conducting the same test using different speed conditions, you can obtain varied sampling data. Use the average values to calculate a calibration value and allow a 2% margin of error.

**Note 1:** For how to enter the speed calculation, see SPEED CAL menu (main menu $\rightarrow$  [SYSTEM] $\rightarrow$ [SPEED CAL]) in the operator's manual.

**Note 2:** To measure the average trial speed, use the speed trial function (see section 3.5.5).

- b) The ship's fore/aft (Y-axis) speed is calculated based on the time traveled.

  This method uses the fore/aft (Y-axis) speed as the GPS milepost. The calculation is made by the **VBW speed** (taken immediately after switching to water-based speed).
- c) <u>Calculation is based on a one-mile course, traveled three times.</u> Calculation is done with the same method as a).
- d) Calculation is based on the time traveled over a predetermined time. Calculation is done with the same method as a).
- 2) How to use survey poles as a milepost

Calculation is done using b) from method 1).

		≡   	E		Sea Note																			
	# C 1	Diall. role.	Aft:	Shipyard Data	Wind (m/s)																			
മ	3	Ξ,		Shipya	Course (deg)																	igneture:	name:	i
TEST SHEET FOR DOPPLER SPEED LOG					Depth (m)																	Owner's Signeture:	Company name:	; ;
OPPLER S	<u>.</u> <del>.</del>	Jul.			Calibration (%)																			
T FOR DO		omps lengm.	Shipyard:	Doppler Speed Log	*1 Error (%)																			
ST SHEE				Doppler S	Speed (kn)																		(%) nnt x =	
Ë					Tracking Mode																			
	Serial No.:	Tlace.	Hull No.:	DGPS	Rev. (rpm) Speed (kn)																	DS Speed (NM) - DGPS (NM)	DGPS (NM)	
				Engine																				
				En	Load (%)			,															Error = -	
	Type:	Dale.	Ship's Name:		RUN No.	- 1	Mean	-	Mean		Mean	-	Mean	<b>'</b>	Mean		Mean	-	Mean		Mean			

# APPX. 4 NETWORK AND SECURITY CONFIGURATION SETTINGS

This equipment has been provided with the least functionalities and services, accordingly security hardening is NOT necessary. The menu items, recommended settings, and defaults settings related to security functions are shown in the table below.

Security data	Menu	Recommended settings	Default settings
Adjust brightness settings remotely	[EQUIPMENT] → [EQUIPMENT] → [RD- 502]	Use as default settings. Set to ON only when the brightness is adjusted remotely.	OFF
Transmission group settings		Use as default settings.	[IP ADDRESS]: 239.192.000.004 [PORT]: 60004
Network settings	[SERVICE] → [NETWORK] → [NETWORK]	Use as default settings.	[IP ADDRESS]: 172.031.016.123 [SUBNET MASK]: 255.255.000.000 [GATEWAY]: 172.031.001.001
		Use as default settings.  Note: The SFI is not used by other devices.	[OWN SFI] VD0001
		Set the SFI of external devices connected to this equipment via LAN.	[RX SFI] GP0001
RMS settings	[SERVICE] → [NETWORK] → [MANAGEMENT PROFILE]	Use as default settings. Set to ON only when you are doing remote monitoring.	[MANAGEMENT PROFILE]: OFF
Audit log output	[SERVICE] → [NETWORK] → [AUDIT LOG]	Use as default settings.	[DESTINATION IP ADDRESS]: 239.192.000.254
Update settings	[SERVICE] → [MAINTENANCE] → [SOFTWARE UPDATE]	Set to ON only when updating.	[USB] [LAN]
Password policy settings	$ \begin{array}{l} [SERVICE] \to \\ [SECURITY] \to \\ [PASSWORD] \to \\ [LENGTH] \end{array} $	Use as default settings.	8
	[SERVICE] → [SECURITY] → [PASSWORD] → [CHARACTER TYPES]	Use as default settings.	[UPPER CASE]: Yes [LOWER CASE]: Yes [NUMBERS]: Yes

# PACKING LIST

DS-8500/-HK A-1

NAME		OUTLINE	DESCRIPTION/CODE No.	G, TA
ユニット リ	NIT			
指示器		172		
DIODI AV UNIT		146	DS-8500-*	1
DISPLAY UNIT		146 133.4O	000-037-351-00 **	ŀ
工事材料 [	NSTALLA	TION MATERIALS		
工事材料		~~		
			CP05-13701	1
INSTALLATION MATERIALS			001-443-270-00	ŀ

コード番号末尾の[\*\*]は、選択品の代表コードを表します。 CODE NUMBER ENDING WITH "\*\*\*" INDICATES THE CODE NUMBER OF REPRESENTATIVE MATERIAL.

(略図の寸法は、参考値です。 DIMENSIONS IN DRAWING FOR REFERENCE ONLY.)

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C7288-Z01-A

#### PACKING LIST DS-8510-1-\*/-1-\*-HK, DS-8510-2-\*/-2-\*-HK

A-2

				/ \ _
NAME		OUTLINE	DESCRIPTION/CODE No.	Q' TY
ユニット	UNIT			
分配器				1
DISTRIBUTOR UNIT		[130	DS-8510-*	1
DISTRIBUTOR UNIT		400 440	000-037-392-00 **	+
予備品	SPARE PA	RTS	000 007 002 00 1	
予備品				
			SP65-01101	1
SPARE PARTS			001-569-930-00	7
工事材料	INSTALLA	TION MATERIALS	001-569-930-00	-
工事材料	11101111111	TON MOTESTINES		T
			CP65-01501	1
INSTALLATION MATERIALS				1
			001-569-940-00	<u> T</u>
図書	DOCUMENT	•		
取扱説明書		210	[	1
OPERATOR'S MANUAL			0M*-72880-*	1
OPERATOR S MANUAL		297	000-197-137-1* **	+
装備要領書		210	000 107 107 17 44	†
			IM*-72880-*	1
INSTALLATION MANUAL		297		1
		**	000-197-139-1* **	<u> T                                   </u>

コード番号末尾の[\*\*]は、選択品の代表コードを表します。 CODE NUMBER ENDING WITH "\*\*\*" INDICATES THE CODE NUMBER OF REPRESENTATIVE MATERIAL

(略図の寸法は、参考値です。 DIMENSIONS IN DRAWING FOR REFERENCE ONLY.)

C7288-Z02-A

	K		DECODED TO USODE A	Т
N A M	UNIT	OUTLINE	DESCRIPTION/CODE No.	L
送受信機 TRANSCEIVER UNIT	orr.	1122	DS-8520-* 000-037-358-00 **	Ī
予備品	SPARE PAR	TS		_
予備品 SPARE PARTS		$\Diamond$	SP65-01001 001-569-860-00	Ī
工事材料	INSTALLAT	ION MATERIALS		_
工事材料 INSTALLATION MATER	IALS		CP65-01401 001-569-870-00	

DS-8530-*				A-4
NAME		OUTLINE	DESCRIPTION/CODE No.	Q' TY
ユニット	UNIT	•		
送受波器		0	DS-8530-*	1
TRANSDUCER UNIT		L=10/20/30/40M	000-044-834-00 **	
工事材料	INSTALLA	TION MATERIALS		
工事材料 INSTALLATION MATERIALS			CP65-01701	1
			001-679-450-00	
図書	DOCUMENT	•		
装備要領		210	C72-02401-*	1
INSTALLATION INSTRUCTION	INS	297	000-202-068-1*	

コード番号末尾の[\*\*]は、選択品の代表コードを表します。 CODE NUMBER ENDING WITH "\*\*" INDICATES THE CODE NUMBER OF REPRESENTATIVE MATERIAL.

(略図の寸法は、参考値です。 DIMENSIONS IN DRAWING FOR REFERENCE ONLY.)

ュード番号末尾の[\*\*]は、選択品の代表ュードを表します。 CODE NUMBER ENDING WITH "\*\*" INDICATES THE CODE NUMBER OF REPRESENTATIVE MATERIAL

(略図の寸法は、参考値です。 DIMENSIONS IN DRAWING FOR REFERENCE ONLY.)

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						,,,
	URUI	<b>10</b> [	CODE NO.	001-443-270-00	)	05ES-X-9406 -0
			TYPE	CP05-13701		1/1
I	事材料表					
INST	ALLATION MATERIALS					
番号 NO.	名 称 NAME	略 図 OUTLINE		名/規格 CRIPTIONS	数量 0' TY	用途/備考 REMARKS
1	F_MOUNT CUSHION F MOUNT CUSHION	144	20-032-1064-1		1	
	1 Jacobi Countries		CODE NO.	100-357-181-10		
2	+†^* \$95" 249" 191	20	3X20 SUS304		4	
	SELF-TAPPING SCREW	(f) mmmp 1 φ 3	CODE NO.	000-163-884-10	-	
3	+トラスタッヒ'ンネシ' 1シュ SFLF-TAPPING SCREW	20 20 1 φ5	20		4	
	OLLI TAITING SONEN	, mm	CODE NO.	000-162-608-10		
4	コンヘ" ックス	150	CV-150B		2	
4	CABLE TIE		CODE	CODE		

						A-
FURUNO			CODE NO. 001-569-940-00			65AE-X-9401 -0
			TYPE	CP65-01501		1/1
I	事材料表					
INST	ALLATION MATERIALS					
番号 NO.	名 称 NAME	略 図 OUTLINE		型名/規格 DESCRIPTIONS		用途/備考 REMARKS
1	+トラスタッセ゛ンネシ゛ 1シュ SELF-TAPPING SCREW	20 100000 p 6	6X20 SUSC	304 000-162-613-10	4	
2	圧着端子 CRIMP-ON LUG	7 (2)	FV2-M4 K	000-162-613-10	4	

(略図の寸法は、参考値です。 DIMENSIONS IN DRAWING FOR REFERENCE ONLY.)

FURUNO ELECTRIC CO . , LTD.

C4490-M06-A

(略國の寸法は、参考値です。 DIMENSIONS IN DRAWING FOR REFERENCE ONLY.)

FURUNO ELECTRIC CO . , LTD.

C7288-M01-A

A-7 FURUNO 
 CODE NO.
 001-569-870-00
 65AE-X-9402-1

 TYPE
 CP65-01401
 1/1
 工事材料表 INSTALLATION MATERIALS 番号 名 称 NO. NAME +トラスタッピンネジ 1シュ 略 図 OUTLINE 用途/備考 REMARKS 20 20 φ 6 6X20 SUS304 1 SELF-TAPPING SCREW CODE NO. 000-162-613-10 圧着端子 16 FV1. 25-3 (LF) RED K 2 CRIMP-ON LUG CODE NO. 000-166-756-11 圧着端子 7 (2) 3 CRIMP-ON LUG FV2-M4 K CODE NO. 000-157-229-11 導電性テーブ L= 100 NO. 1245 \*20MM\* × 100 CODE NO. 000-100-183-20 4 COPPER TAPE

			TYPE	S	65AE-X-9301-0 1/ BOX NO. P					
SHIP	NO.	SPARE PARTS LIST FOR			U S	E		SETS PER VESSEL		
	Г.,			DWG. NO.		QUANTITY			NRKS/CODE NO.	
ITEM NO.	PA	ME OF RT	OUTLINE	OR Type No.	PER SET	PER VES	SPARE			
1	E1-X FUSE TUBE	GLASS TYPE	20 1) \$\phi\$ \$\phi\$ 5	FGMB-A 250V 1A PBF	. 1	1	1	000-	157-496-10	
2	E1-X GLASS FUSE	TUBE	<del>~ 20  </del> φ 5	FGMB-A 250V 2A PBF	. 2	2	2		157-497-10	
								000	707 10	

(略國の寸法は、参考値です。 DIMENSIONS IN DRAWING FOR REFERENCE ONLY.)

(略関の寸法は、参考値です。 DIMENSIONS IN DRAWING FOR REFERENCE ONLY.)

FURUNO ELECTRIC CO . , LTD. C7288-M02-B

A-10

	U	R	CODE NO. 001-569-860-00						AE-X-9302-0	1/1	
			TYPE	TYPE SP65-01001							
SHIP NO. SPARE PARTS LIST FOR				U	S	Е			SETS PER VESSEL		
<u> </u>		ME OF		DWG. NO.		QUANTITY			REMARKS/CODE NO.		
ITEM No.	PA	ME OF RT	OUTLINE	OR Type No.		WORKING PER PER SPAI SET VES		SPARE			
1	E1-X GLASS FUSE	TUBE	20 1 \$\phi \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \	FGMB-A 250V 2A PBF	2		2	2	000-	157-497-10	
									000	107 407 10	
				-	-	$\frac{1}{1}$					=
					_	4					
				1		1					
					-	1					
	NAME	. 1 .	FURUNO ELECTRIC C		DWG			I	2-A		1/1

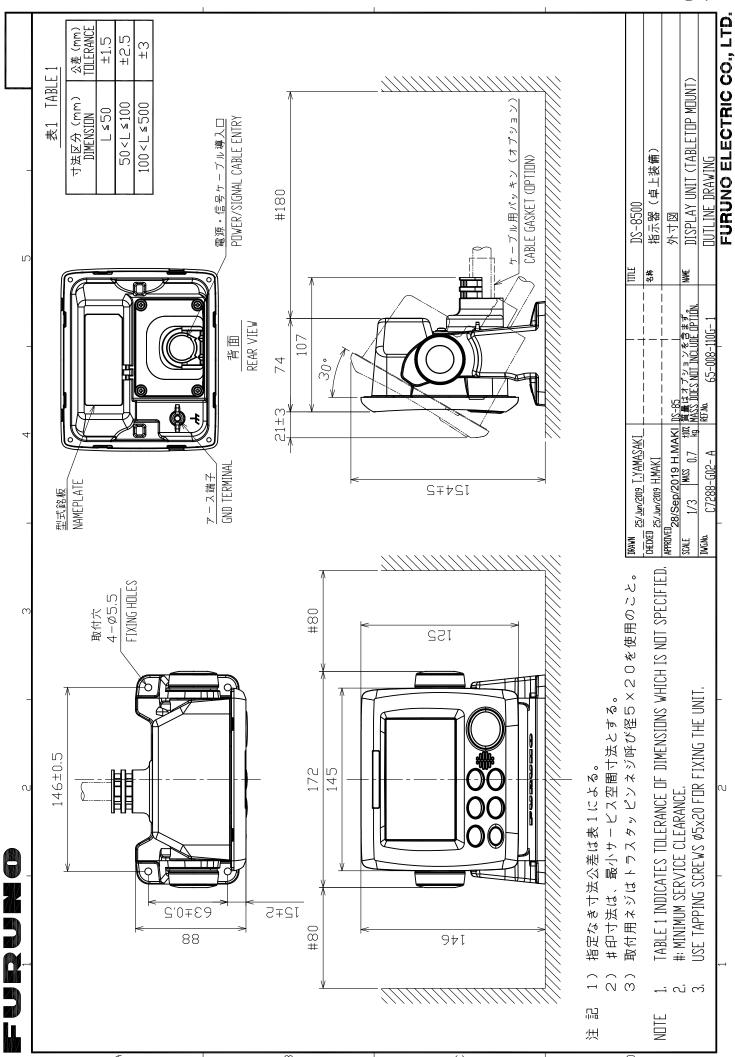
	URUI		CODE NO.	001-679-450-00	)	65AE-X-9405 -0
			TYPE	CP65-01701		1/1
I	事材料表					
INST	ALLATION MATERIALS					
番号 NO.	名 称 NAME	略 図 OUTLINE		名/規格 RIPTIONS	数量 0' TY	用途/備考 REMARKS
1	マキスへ・一サ SPACER	3	CODE NO.	C FEZN5-3CM	4	

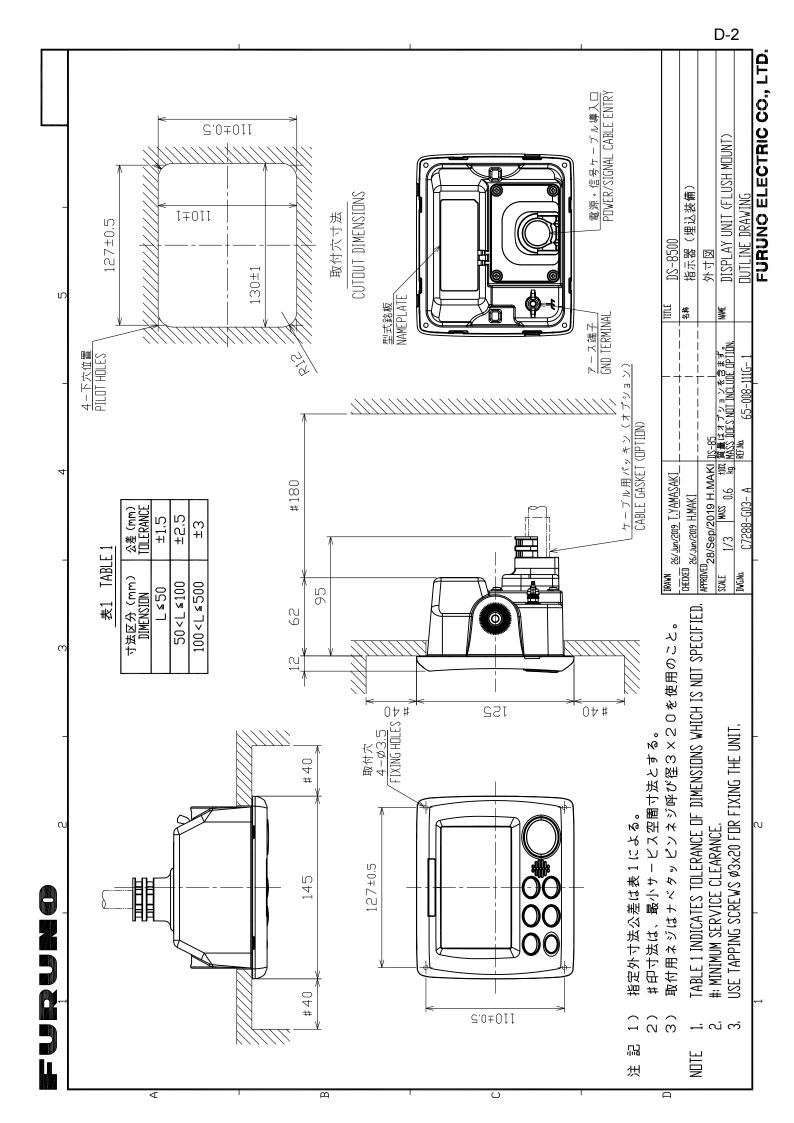
(略図の寸法は、参考値です。 DIMENSIONS IN DRAWING FOR REFERENCE ONLY.)

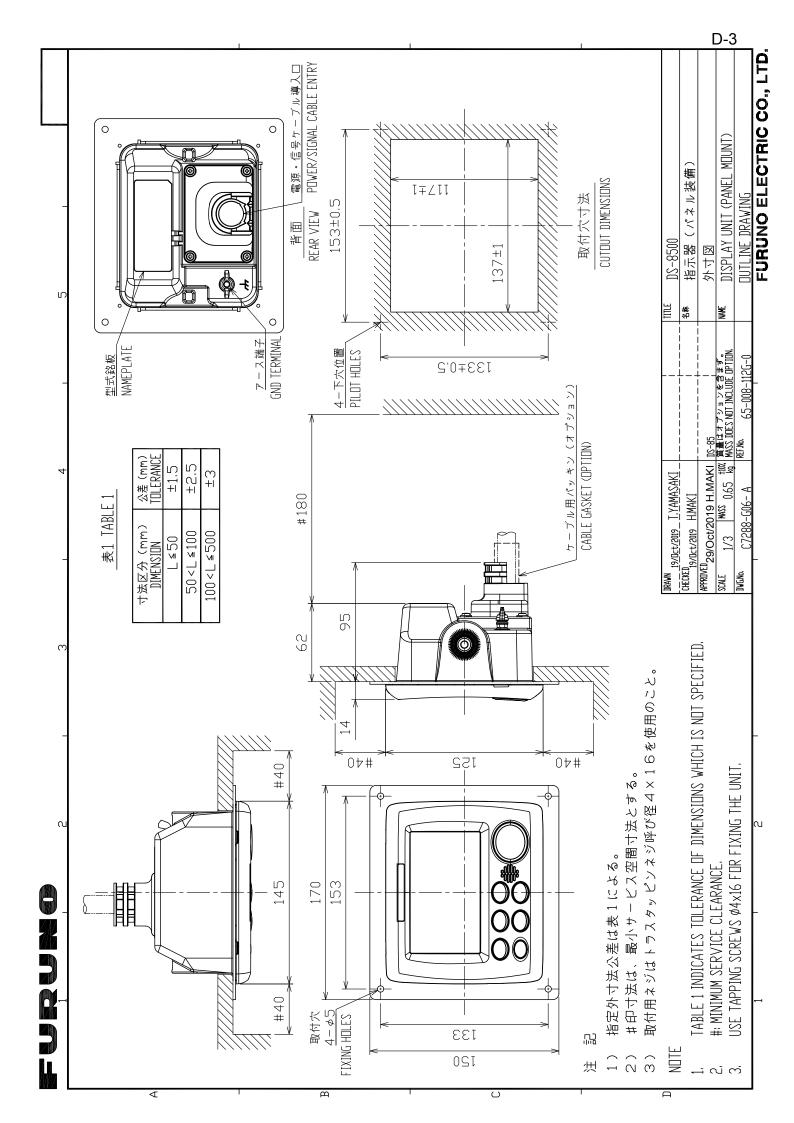
FURUNO ELECTRIC CO . , LTD.

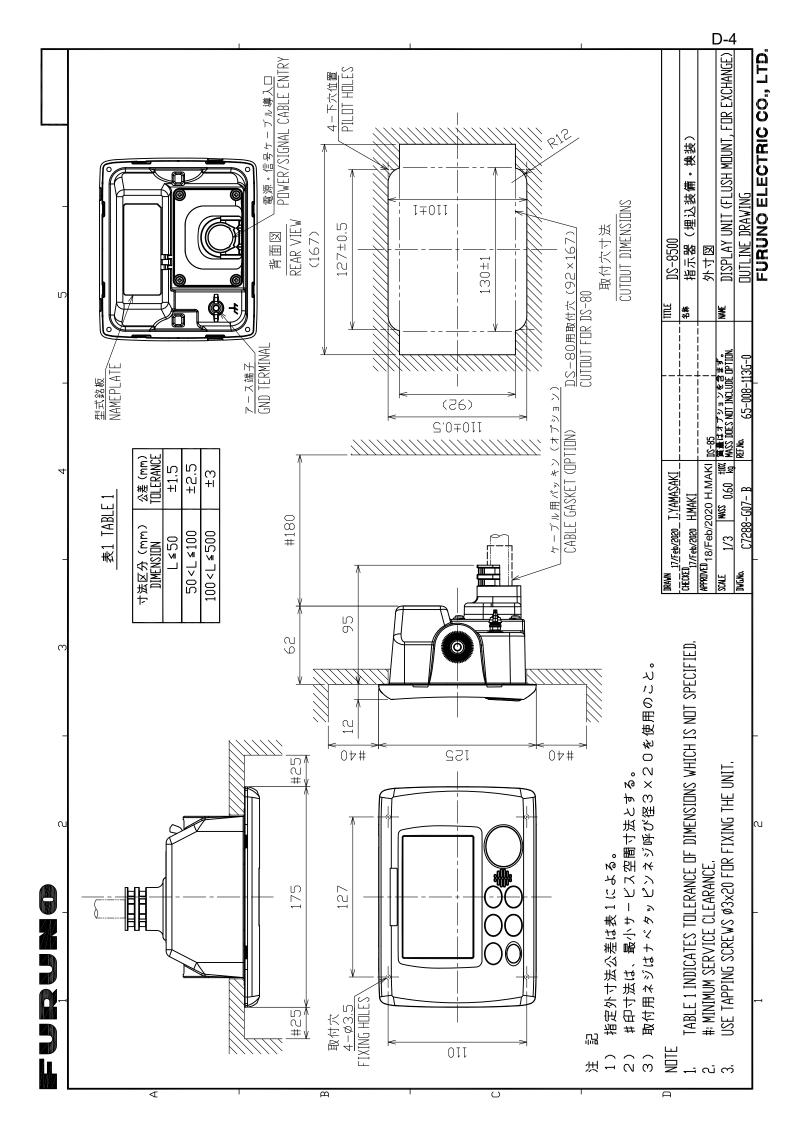
C7288-M05-A

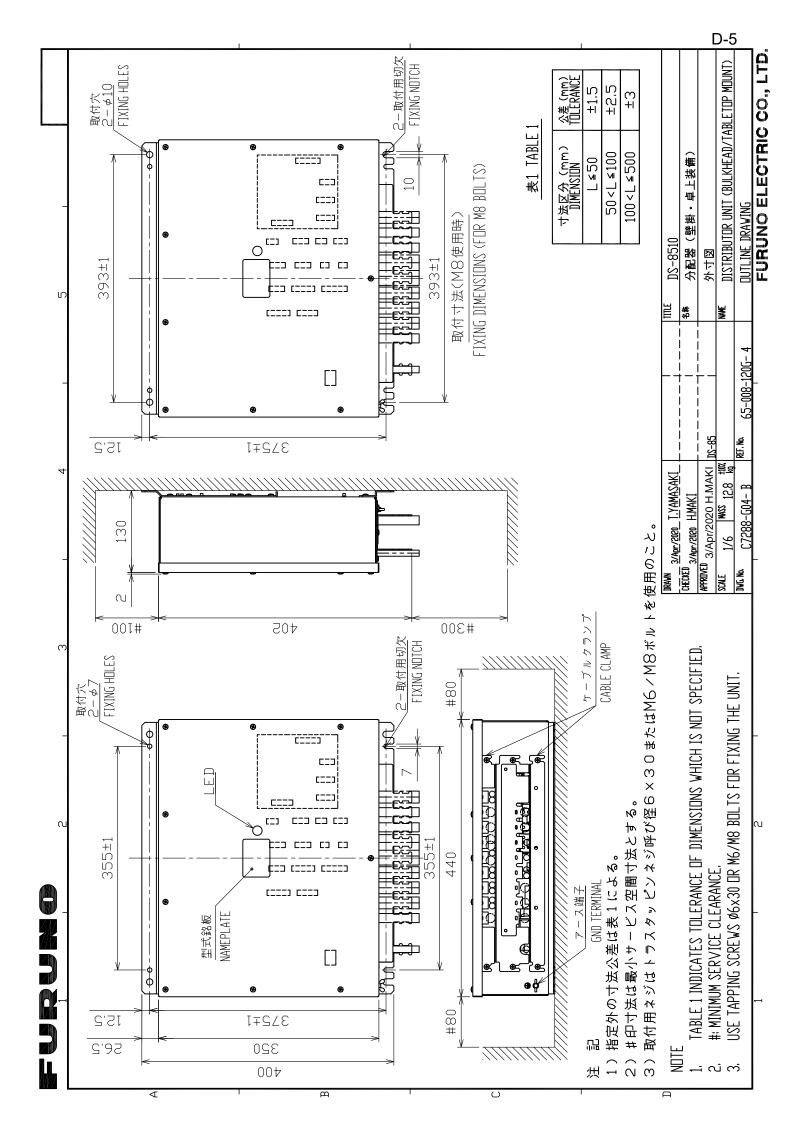


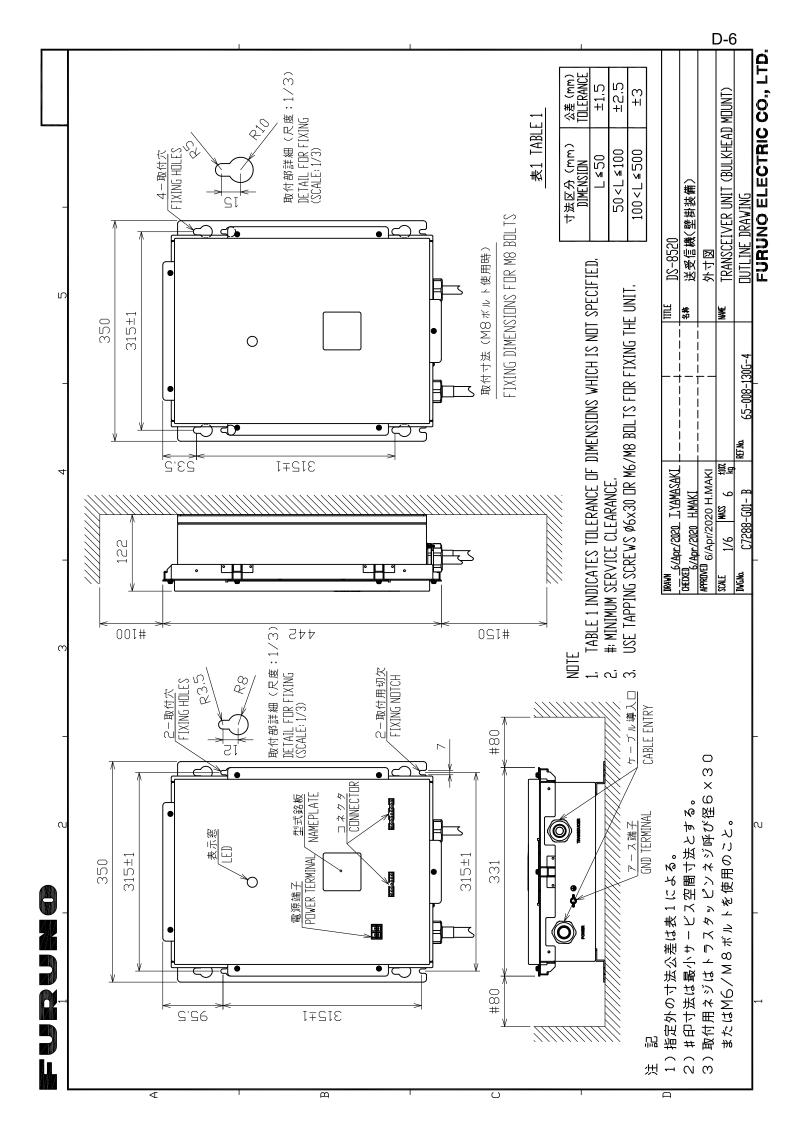


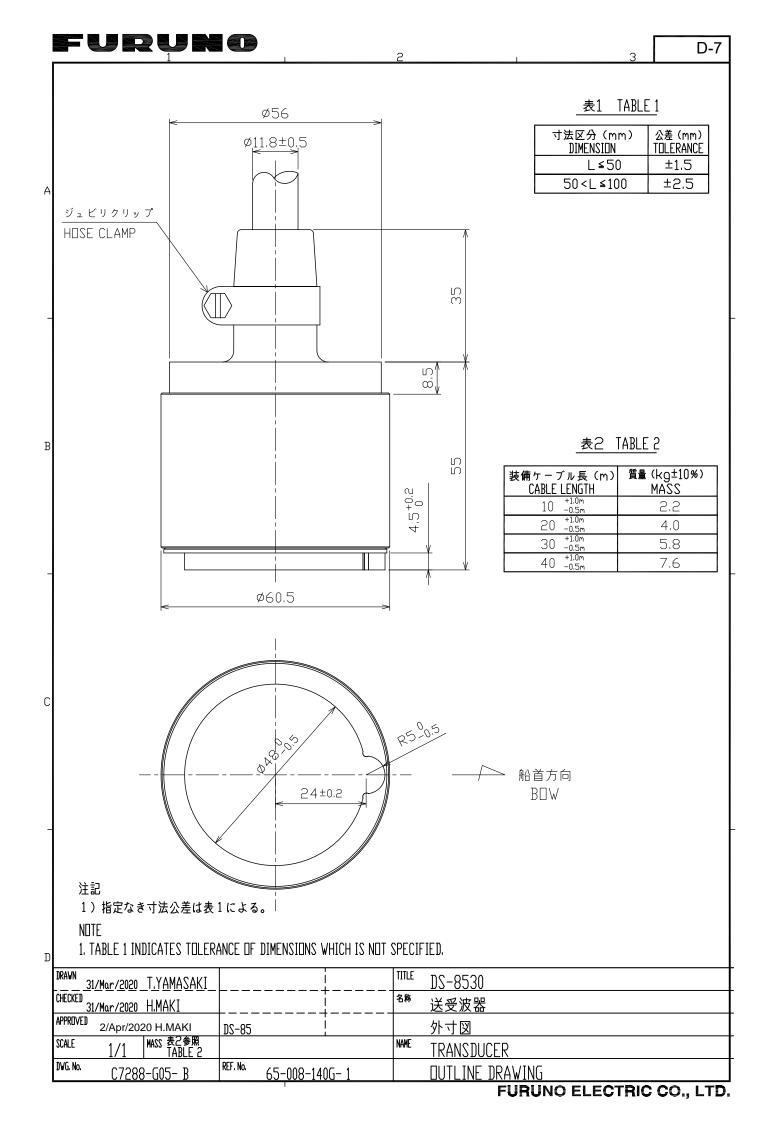


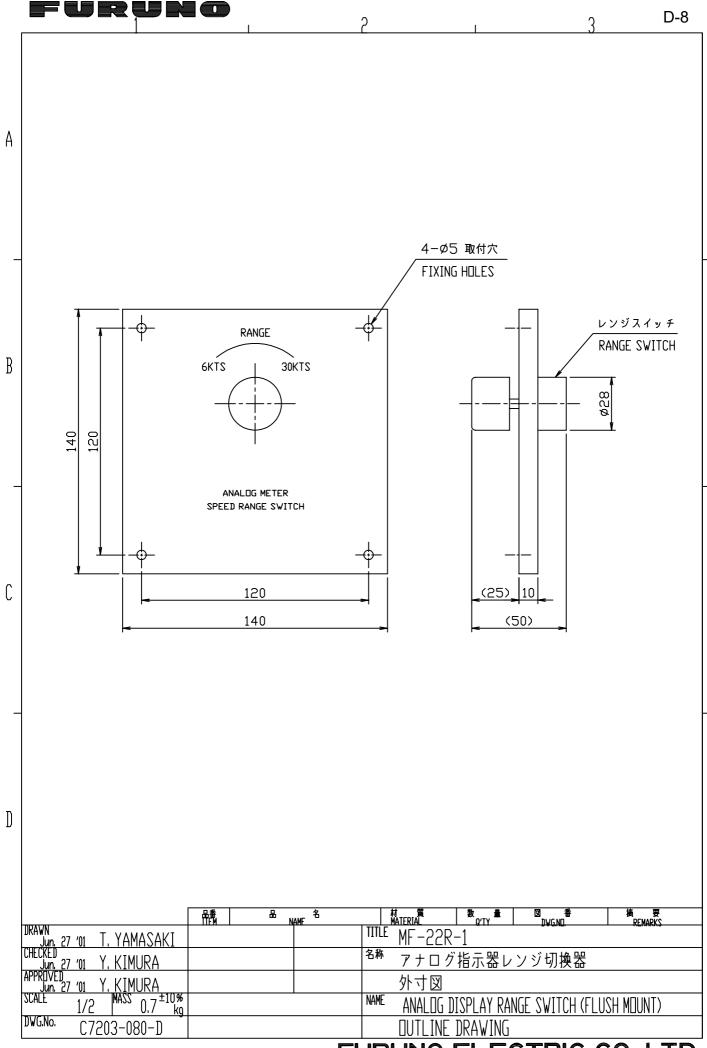




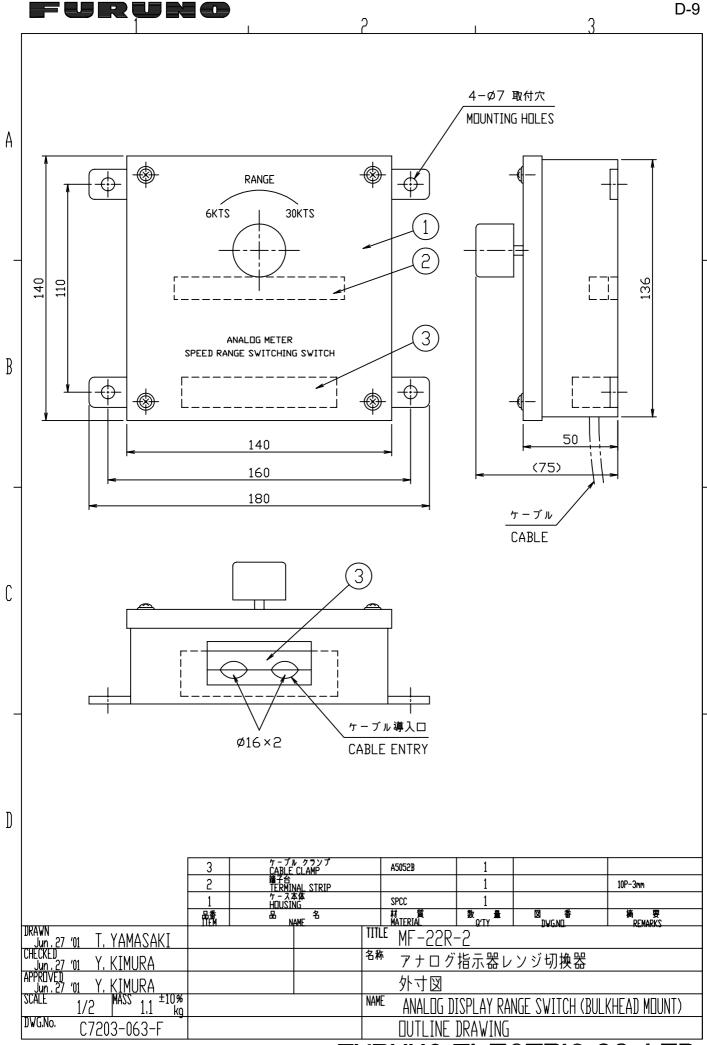








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