IMPORTANT NOTICES

General

• This manual has been authored with simplified grammar, to meet the needs of international users.
• The operator of this equipment must read and follow the instructions in this manual. Wrong operation or maintenance can void the warranty or cause injury.
• Do not copy any part of this manual without written permission from FURUNO.
• If this manual is lost or worn, contact your dealer about replacement.
• The contents of this manual and the equipment specifications can change without notice.
• The example screens (or illustrations) shown in this manual can be different from the screens you see on your display. The screens you see depend on your system configuration and equipment settings.
• Save this manual for future reference.
• Any modification of the equipment (including software) by persons not authorized by FURUNO will void the warranty.
• The following concern acts as our importer in Europe, as defined in DECISION No 768/2008/EC.
  - Name: FURUNO EUROPE B.V.
  - Address: Ridderhaven 19B, 2984 BT Ridderkerk, The Netherlands
• All brand, product names, trademarks, registered trademarks, and service marks belong to their respective holders.

How to discard this product

Discard this product according to local regulations for the disposal of industrial waste. For disposal in the USA, see the homepage of the Electronics Industries Alliance (http://www.eiae.org/) for the correct method of disposal.

How to discard a used battery

Some FURUNO products have a battery(ies). To see if your product has a battery, see the chapter on Maintenance. If a battery is used, tape the + and - terminals of the battery before disposal to prevent fire, heat generation caused by short circuit.

In the European Union

The crossed-out trash can symbol indicates that all types of batteries must not be discarded in standard trash, or at a trash site. Take the used batteries to a battery collection site according to your national legislation and the Batteries Directive 2006/66/EU.

In the USA

The Mobius loop symbol (three chasing arrows) indicates that Ni-Cd and lead-acid rechargeable batteries must be recycled. Take the used batteries to a battery collection site according to local laws.

In the other countries

There are no international standards for the battery recycle symbol. The number of symbols can increase when the other countries make their own recycle symbols in the future.
SAFETY INSTRUCTIONS

The user and installer must read the appropriate safety instructions before attempting to install or operate the equipment.

[WARNING]
Indicates a potentially hazardous situation which, if not avoided, could result in death or serious injury.

[CAUTION]
Indicates a potentially hazardous situation which, if not avoided, may result in minor or moderate injury.

Warning, Caution  Prohibitive Action  Mandatory Action

Safety instructions for the operator

[WARNING]
Do not open the equipment.
Only qualified personnel should work inside the equipment.

Do not disassemble or modify the equipment.
Fire, electrical shock or serious injury can result.

Turn off the equipment immediately if it is emitting smoke or fire.
Fire or electrical shock can result if the power is left on.

Turn off the power immediately if water leaks into the equipment or an object is dropped inside the equipment.
Continued use can cause fire or electrical shock.

Turn off the power immediately if you feel the equipment is acting abnormally.
If the equipment is very warm or is emitting strange noises turn off the power immediately and contact your dealer for advice.

[WARNING]
Do not operate the equipment with wet hands.
Electrical shock can result.

Do not place liquid-filled containers on the top of the equipment.
Electrical shock can result.

Do not install the network sounder unit where it may be subjected to rain or water splash.
Fire or electrical shock can result if water gets inside the equipment.

Use the proper fuse.
Use of a wrong fuse can damage the equipment and may cause fire.

A warning label is attached to the equipment.
Do not remove these labels. If a label is missing or illegible, contact a FURUNO agent or dealer about replacement.

Name: Warning Label (1)
Type: 86-003-1011-2
Code No.: 100-236-232
Safety instructions for the installer

<table>
<thead>
<tr>
<th>WARNING</th>
</tr>
</thead>
<tbody>
<tr>
<td>Do not open the equipment.</td>
</tr>
<tr>
<td>Only qualified personnel should work inside the equipment.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>CAUTION</th>
</tr>
</thead>
<tbody>
<tr>
<td>The transducer cable must be handled carefully, following the guidelines below.</td>
</tr>
<tr>
<td>• Keep fuels and oils away from the cable.</td>
</tr>
<tr>
<td>• Locate the cable away from chemicals.</td>
</tr>
<tr>
<td>• Locate the cable away from locations where it might be damaged.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>WARNING</th>
</tr>
</thead>
<tbody>
<tr>
<td>Turn off the power before beginning the installation.</td>
</tr>
<tr>
<td>Fire or electrical shock can result if the power is left on.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>CAUTION</th>
</tr>
</thead>
<tbody>
<tr>
<td>Do not turn on the power with the transducer exposed to air.</td>
</tr>
<tr>
<td>Damage to the transducer may result.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>WARNING</th>
</tr>
</thead>
<tbody>
<tr>
<td>Confirm that is no water leakage at the transducer and temperature sensor.</td>
</tr>
<tr>
<td>Water leakage can sink the vessel. Also, confirm that neither the transducer or sensor will loosen by vibration. The installer is solely responsible for the installation.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>WARNING</th>
</tr>
</thead>
<tbody>
<tr>
<td>Confirm that the power supply voltage is within the rating of this equipment.</td>
</tr>
<tr>
<td>Incorrect voltage will damage the equipment and may cause fire.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>WARNING</th>
</tr>
</thead>
<tbody>
<tr>
<td>Confirm the following compass safe distances to prevent interference to a magnetic compass:</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Standard compass</th>
<th>Steering compass</th>
</tr>
</thead>
<tbody>
<tr>
<td>0.30 m</td>
<td>0.30 m</td>
</tr>
</tbody>
</table>
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This sounder can be connected to NavNet/NavNet vx2*, NavNet 3D (MFD8/12/BB) and NavNet TZtouch (TZT9/14).

* Model 17x2 Series, Model 17x2C Series, Model 17x4 Series, Model 17x4C Series, GD-1720, GD-1720C, Model 18x3C(-BB) Series, Model 18x4C(-BB) Series, Model 19x3C(-BB) Series, Model 19x4C(-BB) Series, GD-1900C(-BB), GD-1920C(-BB)

**CE declaration**
With regards to CE declarations, please refer to our website (www.furuno.com), for further information about RoHS conformity declarations.
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1. MOUNTING

1.1 Equipment Lists

### Standard supply

<table>
<thead>
<tr>
<th>Name</th>
<th>Type</th>
<th>Code No.</th>
<th>Qty</th>
<th>Remarks</th>
</tr>
</thead>
<tbody>
<tr>
<td>Network Sounder</td>
<td>DFF1</td>
<td></td>
<td>1</td>
<td></td>
</tr>
<tr>
<td>Spare Parts</td>
<td>SP02-05201</td>
<td>001-007-860</td>
<td>1 set</td>
<td>Fuse</td>
</tr>
<tr>
<td>Installation Materials</td>
<td>CP02-08100</td>
<td>000-010-153</td>
<td>1 set</td>
<td>Power cable, LAN cable, Self-tapping screws</td>
</tr>
</tbody>
</table>

### Optional supply

<table>
<thead>
<tr>
<th>Name</th>
<th>Type</th>
<th>Code No.</th>
<th>Qty</th>
<th>Remarks</th>
</tr>
</thead>
<tbody>
<tr>
<td>Matching Box</td>
<td>MB-1100</td>
<td>000-041-353</td>
<td></td>
<td>For 1 kW</td>
</tr>
<tr>
<td>Cable Assy.</td>
<td>MJ-A6SPF0017-010C</td>
<td>000-159-704-11</td>
<td>1 m</td>
<td>for NavNet</td>
</tr>
<tr>
<td></td>
<td>MJ-A6SPF0017-100C</td>
<td>000-159-706-11</td>
<td>10 m</td>
<td>for NavNet</td>
</tr>
<tr>
<td></td>
<td>MJ-A6SPF0017-200C</td>
<td>000-159-707-11</td>
<td>20 m</td>
<td>for NavNet</td>
</tr>
<tr>
<td></td>
<td>MJ-A6SPF0017-300C</td>
<td>000-159-708-11</td>
<td>30 m</td>
<td>for NavNet</td>
</tr>
<tr>
<td></td>
<td>MJ-A6SRMD/TM11AP8-005</td>
<td>000-144-463</td>
<td></td>
<td>For HUB</td>
</tr>
<tr>
<td></td>
<td>MOD-Z072-020+</td>
<td>000-167-175-10</td>
<td>2 m</td>
<td>HUB-101</td>
</tr>
<tr>
<td></td>
<td>MOD-Z072-100+</td>
<td>000-167-177-10</td>
<td>10 m</td>
<td>HUB-101</td>
</tr>
<tr>
<td></td>
<td>MOD-Z072-050+</td>
<td>000-167-176-10</td>
<td>50 m</td>
<td>HUB-101</td>
</tr>
<tr>
<td>Inner Hull Kit S</td>
<td>22S0191-2</td>
<td>000-802-598</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Triducer</td>
<td>525STID-MSD</td>
<td>000-011-783</td>
<td></td>
<td>Thru-hull mount, metallic</td>
</tr>
<tr>
<td></td>
<td>525STID-PWD</td>
<td>000-011-784</td>
<td></td>
<td>Transom mount, plastic</td>
</tr>
<tr>
<td>Transducer</td>
<td>520-5PSD</td>
<td>000-015-204</td>
<td>10 m</td>
<td>Thru-hull mount, plastic</td>
</tr>
<tr>
<td></td>
<td>520-5PWD</td>
<td>000-015-126</td>
<td>15 m</td>
<td>Transom mount, plastic</td>
</tr>
<tr>
<td></td>
<td>520-5MSD</td>
<td>000-015-212</td>
<td>15 m</td>
<td>Thru-hull mount, metallic</td>
</tr>
<tr>
<td></td>
<td>50B-6</td>
<td>000-015-042</td>
<td>10 m</td>
<td>1 kW</td>
</tr>
<tr>
<td></td>
<td>50B-6B</td>
<td>000-015-043</td>
<td>15 m</td>
<td>1 kW</td>
</tr>
<tr>
<td></td>
<td>50B-9B</td>
<td>000-015-065</td>
<td>15 m</td>
<td>1 kW</td>
</tr>
<tr>
<td></td>
<td>200B-5</td>
<td>000-015-027</td>
<td>10 m</td>
<td>1 kW</td>
</tr>
<tr>
<td></td>
<td>200B-5S</td>
<td>000-015-029</td>
<td>10 m</td>
<td>1 kW</td>
</tr>
<tr>
<td></td>
<td>50/200-1T</td>
<td>000-015-170</td>
<td>10 m</td>
<td>1 kW</td>
</tr>
<tr>
<td>Speed/Temperature Sensor</td>
<td>ST-02MSB</td>
<td>000-137-986</td>
<td></td>
<td>Thru-hull mount, metallic</td>
</tr>
<tr>
<td></td>
<td>ST-02PSB</td>
<td>000-137-987</td>
<td></td>
<td>Thru-hull mount, plastic</td>
</tr>
<tr>
<td>Temperature Sensor</td>
<td>T-04MSB</td>
<td>000-026-893</td>
<td></td>
<td>Thru-hull mount</td>
</tr>
<tr>
<td></td>
<td>T-04MTB</td>
<td>000-026-894</td>
<td></td>
<td>Transom mount</td>
</tr>
<tr>
<td>Cable Assy.</td>
<td>02S4147</td>
<td>000-141-082</td>
<td></td>
<td>For Speed/Temp sensor, Temp. sensor</td>
</tr>
<tr>
<td>Extension Cable *</td>
<td>C332 10M</td>
<td>000-192-786-10</td>
<td></td>
<td>10m, for transducer</td>
</tr>
<tr>
<td>Rectifier</td>
<td>PR-62</td>
<td>000-013-484</td>
<td></td>
<td>100 VAC</td>
</tr>
<tr>
<td></td>
<td></td>
<td>000-013-485</td>
<td></td>
<td>110 VAC</td>
</tr>
<tr>
<td></td>
<td></td>
<td>000-013-486</td>
<td></td>
<td>220 VAC</td>
</tr>
<tr>
<td></td>
<td></td>
<td>000-013-487</td>
<td></td>
<td>230 VAC</td>
</tr>
</tbody>
</table>

**Note:** Use only 600 W/1 kW transducer. Use of other types will damage the transducer.

*: Use of the extension cable may cause the following problems:
- Reduced detection ability
Wrong ACCU-FISH™ information (fish length smaller than actual length, fewer fish detections, error in individual fish detection).
Wrong speed data
No TD-ID recognition

1.2 Network Sounder

The network sounder can be installed on a desktop, deck or on a bulkhead. When selecting a mounting location for the network sounder, keep the following in mind:

- The temperature and humidity should be moderate and stable.
- Locate the unit away from exhaust pipes and vents.
- The mounting location should be well ventilated.
- Mount the unit where shock and vibration are minimal.
- Keep the unit away from electromagnetic field-generating equipment such as motors and generators.
- Leave slack in cables for maintenance and servicing ease.
- A magnetic compass will be affected if the network sounder is placed too close to it. Observe the compass safe distances noted in the safety instructions to prevent disturbance to the magnetic compass.
- Fasten the network sounder to the mounting location with four self-tapping screws (4×20).
1.3 Transducer 520-5PSD, 520-5MSD

1.3.1 Mounting location

The performance of this sounder is directly related to the mounting location of the transducer, especially for high-speed cruising. The installation should be planned in advance, keeping the standard cable length and the following factors in mind:

- When the boat has a keel, the transducer should be at least 15-30 cm away from it. Typical thru-hull mountings are shown in the figure on the next page.
- Air bubbles and turbulence caused by movement of the boat can seriously degrade the sounding capability of the transducer. The transducer should, therefore, be located in a position where water flow is the smoothest. Noise from the propellers also adversely affects performance and the transducer should not be mounted nearby. The lifting strakes are notorious for creating acoustic noise, and these must be avoided by keeping the transducer inboard of them.
- The transducer must always remain submerged, even when the boat is rolling, pitching or up on a plane at high speed.
- A practical choice would be somewhere between 1/3 and 1/2 of the boat's length from the stern. For planing hulls, a practical location is generally rather far astern, so that the transducer is always in water regardless of the planing attitude.

Dimensions of transducers 520-5PSD, 520-5MSD
1.3.2 Acceptable mounting locations

Deep-V hull

* Position 1/2 to 1/3 length of the hull from stern.
* 15-30 cm from center line (inside first lifting strakes).

* Transducer mounting location on deep-V hull

High speed V-planing hull

* Within the submerged bottom area
* Deadrise angle within 15°

* Transducer mounting location on high speed V-planing hull
1.3.3 **Installation procedure**

1. With the boat hauled out of the water, mark the location selected for mounting the transducer on the bottom of the hull. If the hull is not level within $15^\circ$ in any direction, fairing blocks made out of teak should be used between the transducer and hull, both inside and outside, to keep the transducer face parallel with the water line. Fabricate the fairing block as shown below and make the entire surface as smooth as possible to provide an undisturbed flow of water around the transducer.

The fairing block should be smaller than the transducer itself to provide a channel to divert turbulent water around the sides of the transducer rather than over its face.

![Construction of fairing block](image)

2. Drill a hole just large enough to pass the threaded stuffing tube of the transducer through the hull, making sure it is drilled vertically.

3. Apply a sufficient amount of high quality caulking compound to the top surface of the transducer, around the threads of the stuffing tube and inside the mounting hole (and fairing blocks if used) to ensure watertight mounting.

4. Mount the transducer and fairing blocks and tighten the locking nuts. Be sure that the transducer is properly oriented and its working face is parallel to the water line.

![Deep-V Hull and Flat Hull](image)

**Note:** Do not over-stress the stuffing tube and locking nuts through excessive tightening, since the wood block will swell when the boat is placed in the water. It is suggested that the nut be tightened lightly at installation and retightened several days after the boat has been launched.
1.4 Transducer 525-5PWD (transom mount)

This type of mounting is very commonly employed for outboard motor boats. Do not use this method on an inboard motor boat because turbulence is created by the propeller ahead of the transducer.

There are two methods of installation: flush with hull (for flat hulls) and projecting from hull (for deep V-hulls).

1.4.1 Installation for flat hulls

A suitable mounting location is at least 50 cm away from the engine and where the water flow is smooth.

1. Drill four pilot holes in the mounting location.
2. Attach the transducer to the bracket with self-tapping screws (supplied).
3. Adjust the transducer position so the transducer faces right to the seabed.
   
   **Note:** If necessary, to improve water flow and minimize air bubbles staying on the transducer face, incline the transducer about 5° at the rear. This may require a certain amount of experimentation for fine tuning at high cruising speeds.

4. Fill the gap between the wedge front of the transducer and transom with epoxy material to eliminate any air spaces.
1.4.2 *Installation for deep-V hulls*

This method is employed on deep-V hulls and provides good performance because the effects of air bubbles are minimal. Install the transducer parallel with water surface; not flush with hull. If the boat is placed on a trailer care must be taken not to damage the transducer when the boat is hauled out of the water and put on the trailer.

![Transom mount transducer, projecting from hull](image)

1.4.3 *Transducer preparation*

Before putting the boat in water, wipe the face of the transducer thoroughly with a detergent liquid soap. This will lessen the time necessary for the transducer to have good contact with the water. Otherwise the time required for complete "saturation" will be lengthened and performance will be reduced.

*Note:* Do not paint the transducer. Performance will be affected.
1.5 **Inside Hull Mount**

This mounting method is available for FRP boats.

1.5.1 **Necessary tools**

You will need the following tools:

- Sandpaper (#100)
- Marine sealant
- Silicone grease

1.5.2 **Remarks on installation**

- Turn off the engine and anchor the boat while installing the equipment.
- Install the transducer in the engine room.

1.5.3 **Mounting location**

Keep the following points in mind when selecting a mounting location:

- The mounting location should be where the hull is of single-hull thickness and is void of air or flotation materials other than solid fiberglass between the transducer face and the water.
- Do not place the transducer over hull struts or ribs which run under the hull.
- Avoid a location where the rising angle of the hull exceeds 15°, to minimize the effect of the boat's rolling.
- You will finalize the mounting location through some trial and error. The procedure for this is shown later.
1.5.4 Installation procedure

1. Clean the transducer face to remove any foreign material. Lightly roughen the transducer face with #100 sandpaper. Also, roughen the inside of the hull where the transducer is to be mounted.

2. Warm the marine sealant to 40°C before usage to soften it. Coat the transducer face and mounting location with marine sealant.

3. Press the transducer firmly down on the hull and gently twist it back and forth to remove any air which may be trapped in the marine sealant.

4. Connect this unit to NavNet equipment and turn on the NavNet equipment.

5. Set up the NavNet equipment to show “single frequency display”.

6. Set the gain to “50”.

7. Set the range to “10”.

   **Case 1**

   The installation is proper if the bottom echo is displayed in red and the depth indication is shown. Go to step 9.

   **Case 2**

   The bottom echo is not displayed in red when ultrasound attenuation is great. Re-locate the transducer as shown in step 8

8. Re-locating the transducer.

   1) Turn off the power.
   2) Detach the transducer. Insert a knife or wooden stick under transducer to remove it
   3) Repeat steps 1 thru 7.

9. Fix the transducer.
1.6 Optional Speed/Temperature Sensor ST-02MSB, ST-02PSB

Select a suitable mounting location considering the following points:

- Select a mid-boat flat position. The sensor does not have to be installed perfectly perpendicular. The sensor must not be damaged in dry-docking operation.
- Select a place apart from equipment generating heat.
- Select a place in the forward direction viewing from the drain hole, to allow for circulation of cooling water.
- Select a place free from vibration.

Procedure

1. Dry-dock the boat.
2. Make a hole of approx. 51 mm in diameter in the mounting location.
3. Unfasten locknut and remove the sensor section.
4. Apply high-grade sealant to the flange of the sensor.
5. Pass the sensor casing through the hole.
6. Face the notch on the sensor toward boat's bow and tighten the flange.
7. Set the sensor section to the sensor casing and tighten the locknut.
8. Launch the boat and check for water leakage around the sensor.
1.7 Optional Triducers

1.7.1 Thru-hull triducer 525STID-MSD

See section 1.2 for how to install the 525STID-MSD.

1.7.2 Transom mount triducer 525STID-PWD

Pre-test for speed and temperature

Connect the sensor to the instrument and spin the paddlewheel. Check for a speed reading and the approximate air temperature. If there is no reading, return the sensor to your place of purchase.

Tools and materials needed

- Scissors
- Masking tape
- Safety goggles
- Dust mask
- Electric drill
- Screwdrivers
- Pencil
- Zip-ties

Drill bit for:
- Bracket holes: 4mm, #23, or 9/64"
- Fiberglass hull: chamfer bit (preferred), 6mm, or 1/4"
- Transom hole: 19mm or 3/4" (optional)
- Cable clamp holes: 3mm or 1/8"

Straight edge

Marine sealant

Water-based antifouling paint (mandatory in salt water).

Scissors
**Mounting location**

To ensure the best performance, the sensor must be submerged in aeration-free and turbulence-free water. Mount the sensor close to the centerline of the boat. On slower heavier displacement hulls, positioning it farther from the centerline is acceptable.

Allow adequate space above the bracket for it to release and rotate the sensor upward.

![Diagram of mounting location]

**Height required at mounting location**

**Note 1:** Do not mount the sensor in an area of turbulence or bubbles: near water intake or discharge openings; behind strakes, struts, fittings, or hull irregularities; behind eroding paint (an indication of turbulence).

**Note 2:** Avoid mounting the sensor where the boat may be supported during trailering, launching, hauling, and storage.

**Note 3:** For single drive boat, mount on the starboard side at least 75 mm (3") beyond the swing radius of the propeller.

![Diagram of mounting location on single drive boat]

**Note 4:** For twin drive boat, mount between the drives.
Installation of bracket

1. Cut out the installation template (enclosed with transducer) along the dotted line.

2. At the selected location, position the template, so the arrow at the bottom is aligned with the bottom edge of the transom. Being sure the template is parallel to the waterline, tape it in place.

Positioning the template

Warning: Always wear safety goggles and a dust mask.

3. Using a 4 mm, #23, or 9/64" bit, drill three holes 22 mm (7/8") deep at the locations indicated. To prevent drilling too deeply, wrap masking tape around the bit 22 mm (7/8") from the point.

Fiberglass hull: Minimize surface cracking by chamfering the gelcoat. If a chamfer bit or countersink bit is not available, start drilling with a 6mm or 1/4" bit to a depth of 1 mm (1/16").

4. If you know your transom angle, the bracket is designed for a standard 13° transom angle.
   11° -18° angle: No shim is required. Skip to step 3 in "Adjusting".
   Other angles: The shim is required. Skip to step 2 of "Adjusting".
   If you do not know the transom angle, temporarily attach the bracket and sensor to the transom to determine if the plastic shim is needed.

5. Using the three #10 x 1-1/4" self-tapping screws, temporarily screw the bracket to the hull. DO NOT tighten the screws completely at this time. Follow the step 1-4 in "Attaching the sensor to the bracket", before proceeding with "Adjusting".
**Attaching the sensor to the bracket**

1. If the retaining cover near the top of the bracket is closed, open it by depressing the latch and rotating the cover downward.

2. Insert the sensor’s pivot arms into the slots near the top of the bracket.

3. Maintain pressure until the pivot arms click into place.

4. Rotate the sensor downward until the bottom snaps into the bracket.

5. Close the retaining cover to prevent the accidental release of the sensor when the boat is underway.

**Adjusting**

1. Using a straight edge, sight the underside of the sensor relative to the underside of the hull. The stern of the sensor should be 1-3 mm (1/16-1/8”) below the bow of the sensor or parallel to the bottom of the hull.

   **Note:** Do not position the bow of the sensor lower than the stern because aeration will occur.

2. To adjust the sensor’s angle relative to the hull, use the tapered plastic shim provided. If the bracket has been temporarily fastened to the transom, remove it. Key the shim in place on the back of the bracket.

   *2° -10° transom angle (stepped transom and jet boats):* Position the shim with the tapered end down.
**19°-22° transom angle (small aluminum and fiberglass boats):** Position the shim with the tapered end up.

$$\begin{align*}
2°-10° & \text{ transom angle} \\
11° & \text{ transom angle} \\
19°-22° & \text{ transom angle}
\end{align*}$$

<table>
<thead>
<tr>
<th>Shim Position</th>
<th>Transom Angle</th>
</tr>
</thead>
<tbody>
<tr>
<td>sh. with taper down</td>
<td>NO SHIM</td>
</tr>
<tr>
<td>parallel</td>
<td>12°-18° transom angle</td>
</tr>
<tr>
<td>NO</td>
<td>NO SHIM</td>
</tr>
<tr>
<td>angle reversed</td>
<td>slight angle</td>
</tr>
<tr>
<td>YES</td>
<td>angle too steep</td>
</tr>
</tbody>
</table>

**Sensor position and transom angle**

3. If the bracket has been temporarily fastened to the transom, remove it. Apply a marine sealant to the threads of the three #10 x 1-1/4" self-tapping screws to prevent water seeping into the transom. Screw the bracket to the hull. Do not tighten the screws completely at this time.

4. Repeat step 1 to ensure that the angle of the sensor is correct.

**Note:** Do not position the sensor farther into the water than necessary to avoid increasing drag, spray, and water noise and reducing boat speed.

5. Using the vertical adjustment space on the bracket slots, slide the sensor up or down to provide a projection of 3 mm (1/8”). Tighten the screws.

**Vertical adjustment and cable routing**
**Cable routing**

Route the sensor cable over the transom, through a drain hole, or thorough a new hole drilled in the transom above the waterline.

Never cut the cable or remote the connector; this will void the warranty. Always wear safety goggles and a dust mask.

1. If a hole must be drilled, choose a location well above the waterline. Check for obstructions such as trim tabs, pumps, or wiring inside the hull. Mark the location with a pencil. Drill a hole through the transom using a 19 mm or 3/4" bit (to accommodate the connector).

2. Route the cable over or through the transom.

3. On the outside of the hull secure the cable against the transom using the cable clamps. Position a cable clamp 50 mm (2") above the bracket and mark the mounting hole with a pencil.

4. Position the second cable clamp halfway between the first clamp and the cable hole. Mark this mounting hole.

5. If a hole has been drilled in the transom, open the appropriate slot in the transom cable cover. Position the cover over the cable where it enters the hull. Mark the two mounting holes.

6. At each of the marked locations, use a 3 mm or 1/8" bit to drill a hole 10 mm (3/8") deep. The prevent drilling too deeply, wrap masking tape around the bit 10 mm (3/8") from the point.

7. Apply marine sealant to the threads of the #6 x 1/2" self-tapping screw to prevent water from seeping into the transom. If you have drilled a hole through the transom, apply marine sealant to the space around the cable where it passes through the transom.

8. Position the two cable clamps and fasten them in place. If used, push the cable cover over the cable and screw it in place.

9. Route the cable to the instrument being careful not to tear the cable jacket when passing it through the bulkhead(s) and other parts of the boat. To reduce electrical interference, separate the sensor cable from other electrical wiring and "noise" sources. Coil any excess cable and secure it in place with zip-ties to prevent damage.
2. **WIRING**

Connect the power cable, transducer cable, external equipment and ground wire as shown in the figure below.

**Ground**

Connect the ground wire (1.25sq) to ship's ground to prevent interference to the picture. Shorten the ground wire as much as possible. For FRP vessels, install a ground plate that measures about 20 cm by 30 cm on the outside of the hull bottom to provide a ground point.

**Note:** Use a "closed-type" lug ( ) to make the ground connection at the network sounder. Do not use an "open-type" lug ( ).

**External KP**

Consult with your dealer if connection of an external KP is required to reduce interference from another transducer.
2.1 Optional Temperature/Speed Sensor, Temperature Sensor

Connect the temperature/speed sensor or temperature sensor to the XDR port with the converter connector (Type: 02S4147, Code No.: 000-141-082, option).

**Connection of temperature/speed sensor**

Connect to XDR port at network sounder

**Connection of transducer, temperature sensor, speed/temperature sensor**

Tape connector with self-vulcanizing tape and then vinyl tape to waterproof connector. Bind tape end with cable tie.
2.2 Wiring Optional 1 kW Transducer

To connect optional transducer 50B-6, 50B-6B, 50B-9B, 200B-5, 200B-5S, 50/200-1T, the optional Matching Box MB-1100 is required.

Matching Box MB-1100

Matching Box Kit (Type: MB-1100, Code No.: 000-041-353)

<table>
<thead>
<tr>
<th>Name</th>
<th>Type</th>
<th>Code No.</th>
<th>Qty</th>
<th>Remarks</th>
</tr>
</thead>
<tbody>
<tr>
<td>Matching Box</td>
<td>MB-1100</td>
<td>000-041-000</td>
<td>1</td>
<td>Cable w/10P connector supplied for connection to network sounder</td>
</tr>
<tr>
<td>Crimp-on Lug</td>
<td>FV1.25-3 Red</td>
<td>000-538-113</td>
<td>6</td>
<td></td>
</tr>
<tr>
<td>Cord Lock</td>
<td>NC-1</td>
<td>000-516-650</td>
<td>1</td>
<td>For use with separate transducer</td>
</tr>
</tbody>
</table>

Fabrication of transducer cable

Fabricate the transducer cable as illustrated below to connect it to the Distribution Box.
3. INITIAL SETTINGS, OPERATION

3.1 Selecting the Transmission Power

The default transmission power is 600 W. If the 1 kW transducer is installed, turn on the #1 segment of DIP SW S2 on the pcb 02P6353 inside the network sounder.

For NavNet/NavNet vx2
1. Detach the power cable.
2. Detach the cover of the DFF1; grasp the cover at opposing sides with hands, pull outward slightly and lift up to detach.
3. Loosen three screws fixing the inside cover, and slide cover forward to detach it.
4. Set the #1 segment of DIP SW S2 according to transducer connected.
5. Reattach the inside and outside covers and reconnect the power cable.

For NavNet 3D/TZtouch: Set the transducer type at the NavNet 3D/TZtouch. See respective installation manual for the procedure.

WARNING
Do not open the equipment unless totally familiar with electrical circuits and service manual.

Only qualified personnel should work inside the equipment.

PCB 02P6353
3.2 MODE SW

The MODE switch provides the functions described in the table below. Remove the rubber cap to access the switch and set switches with a plastic screwdriver or the like.

<table>
<thead>
<tr>
<th>SW No.</th>
<th>Function, description</th>
<th>Setting content</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Power from NavNet</td>
<td>OFF: Sounder powered on/off by NavNet</td>
</tr>
<tr>
<td></td>
<td></td>
<td>ON: Sounder not powered on/off by NavNet</td>
</tr>
<tr>
<td>2</td>
<td>IP number</td>
<td>OFF: IP0</td>
</tr>
<tr>
<td></td>
<td></td>
<td>ON: IP1</td>
</tr>
<tr>
<td></td>
<td><strong>Note:</strong> When installing the below-mentioned units to a NavNet network other than the NavNet 3D network, turn the 1st unit OFF and the 2nd unit ON.</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>- DFF1, 2 units</td>
</tr>
<tr>
<td></td>
<td></td>
<td>- BBDS1, 2 units</td>
</tr>
<tr>
<td></td>
<td></td>
<td>- DFF1, 1 unit, BBDS1, 1 unit (total of 2 units)</td>
</tr>
<tr>
<td>3</td>
<td>Factory testing</td>
<td>OFF: Testing OFF</td>
</tr>
<tr>
<td></td>
<td></td>
<td>ON: Testing ON</td>
</tr>
<tr>
<td>4</td>
<td>Automatic IP setting</td>
<td>OFF: Automatic IP enabled</td>
</tr>
<tr>
<td></td>
<td>(Currently no use)</td>
<td>ON: Automatic IP disabled</td>
</tr>
</tbody>
</table>

For NavNet 3D, turn off all switches.
3.3 Operation Check (LED)

The network sounder is powered on/off from ship’s switchboard. The LED on the network sounder lights or flashes according to equipment state, as described in the table below.

<table>
<thead>
<tr>
<th>LED state</th>
<th>Meaning</th>
</tr>
</thead>
<tbody>
<tr>
<td>Lit continuously*</td>
<td>NavNet is not showing the sounder display, or sounder is not connected to NavNet</td>
</tr>
<tr>
<td>Flashing every two seconds</td>
<td>Normal operation</td>
</tr>
<tr>
<td>Flashing every four seconds</td>
<td>Factory test mode</td>
</tr>
</tbody>
</table>

* The LED lights for approximately 20 seconds after turning on the power while the equipment is being initialized.

---

DFF1, top view
4. MAINTENANCE

4.1 Maintenance

Regular maintenance is essential for good performance. Check the items listed in the table below monthly to help keep your equipment in good shape for years to come.

<table>
<thead>
<tr>
<th>Item</th>
<th>Action</th>
</tr>
</thead>
<tbody>
<tr>
<td>Transducer cable</td>
<td>Check that cable is tightly fastened and is not damaged. Replace if damaged.</td>
</tr>
<tr>
<td>Power cable, transducer cable plug</td>
<td>Check that they are tightly fastened and not damaged. Refasten if necessary. Replace if damaged.</td>
</tr>
<tr>
<td>Ground</td>
<td>Check for corrosion. Clean if necessary.</td>
</tr>
<tr>
<td>Power supply voltage</td>
<td>Check voltage. If out of rating correct problem.</td>
</tr>
<tr>
<td>Cleaning the network sounder’s cabinet</td>
<td>Dust or dirt on the cabinet may be removed with a dry cloth. Do not use chemical-based cleaners to clean the cabinet; they can remove paint and markings.</td>
</tr>
<tr>
<td>Transducer</td>
<td>Marine life on the transducer face will result in a gradual decrease in sensitivity. Check the transducer face for cleanliness each time the boat is dry-docked. Carefully remove any marine life with a piece of wood or fine-grade sandpaper.</td>
</tr>
</tbody>
</table>

4.2 Replacing the Fuse

The two 3 A fuses (Type: FGBO-A 125V 3A PBF, Code No. 000-155-850-10) in the snap-in fuse holder on the power cable protect the equipment from equipment fault and reverse polarity of the ship’s mains. If the equipment cannot be powered, a fuse may have blown. Find out the cause for blown fuse before replacing a fuse. If a fuse blows again after replacement, contact a FURUNO agent or dealer for advice.

WARNING

Do not open the equipment unless totally familiar with electrical circuits and service manual.

Only qualified personnel should work inside the equipment.

WARNING

Use the proper fuse.

Use of a wrong fuse can result in damage to the equipment or cause fire.
APPENDIX 1 INSTALLATION OF TEMPERATURE SENSORS

The installation instructions in this chapter are copied from the manufacturer’s (AIRMAR Technology Corporation) installation guide, which is included with your sensor.

The model numbers mentioned within the documentation should be read as follows:
T42 => T-04MSB
T80 => T-04MTB

OWNER’S GUIDE & INSTALLATION INSTRUCTIONS

Thru-Hull, Analog
High-Precision Temperature Sensor
Model T42

Follow the precautions below for optimal product performance and to reduce the risk of property damage, personal injury, and/or death.

WARNING: Always wear safety goggles and a dust mask when installing.

WARNING: Immediately check for leaks when the boat is placed in the water. Do not leave the boat unchecked for more than three hours. Even a small leak can allow considerable water to accumulate.

CAUTION: Never install a bronze sensor in a metal hull because electrolytic corrosion will occur.

CAUTION: Never install a metal sensor on a vessel with a positive ground system.

CAUTION: Never pull, carry, or hold the sensor by its cable; this may sever internal connections.

CAUTION: Never use solvents. Cleaner, fuel, sealant, paint, and other products may contain solvents that can damage plastic parts, especially the sensor’s face.

IMPORTANT: Read the instructions completely before proceeding with the installation. These instructions supersede any other instructions in your instrument manual if they differ.

Tools & Materials
Safety goggles
Dust mask
Electric drill
Drill bit/hole saw/spade bit:
- Pilot hole: T42
- Hole saw: 3mm or 1/8”
- 22mm or 7/8”
Sandpaper
Mild household detergent or weak solvent (alcohol)
Marine sealant (suitable for below waterline)
Sizable pliers
Installation in a cored fiberglass hull (see page 2)
- Drill a 3mm or 1/8” pilot hole from inside the hull. If there is a rib, strib, or other hull irregularity near the selected mounting location, drill from the outside.
- Using the appropriate drill bit, cut a hole perpendicular to the hull from outside the boat.
- Sand and clean the area around the hole, inside and outside, to ensure that the marine sealant will adhere properly to the hull. If there is any petroleum residue inside the hull, remove it with either mild household detergent or a weak solvent (alcohol) before sanding.

Sensor Installation

Hole Drilling
Core fiberglass hull — Follow separate instructions on page 2.

Applications
- Bronze sensor recommended for fiberglass or wood hull only.
- The hull must be a minimum of 8mm (5/16”) thick at the mounting location.

Mounting Location
Choose a location where the temperature sensor will be in contact with the water at all times.
APPENDIX 1 INSTALLATION OF TEMPERATURE SENSORS

Bedding

CAUTION: Be sure all surfaces to be bedded are clean and dry.

1. Remove the hull nut (see Figure 1).
2. Apply a 2 mm (1/16") thick layer of marine sealant around the flange of the sensor that will contact the hull and up the stem. The sealant must extend 6 mm (1/4") higher than the combined thickness of the hull and the hull nut. This will ensure that there is marine sealant in the threads to seal the hull and hold the hull nut securely in place.
3. Apply a 2 mm (1/16") thick layer of marine sealant to the flange of the hull nut that will contact the hull.

Installing

1. From outside the hull, thread the cable through the mounting hole.
2. Push the sensor into the mounting hole using a twisting motion to squeeze out excess marine sealant (see Figure 1).
3. From inside the hull, slide the hull nut onto the cable. Screw the hull nut in place. Tighten it with slip-joint pliers.

Cored fiberglass hull—Do not over tighten, crushing the hull.

Wood hull—Allow for the wood to swell before tightening.
4. Remove any excess marine sealant on the outside of the hull to ensure smooth water flow over the sensor.

Checking for Leaks

When the boat is placed in the water, immediately check around the thru-hull sensor for leaks. Note that very small leaks may not be readily observed. Do not to leave the boat in the water for more than 3 hours before checking it again. If there is a small leak, there may be considerable bilge water accumulation after 24 hours. If a leak is observed, repeat "Bedding" and "Installing" immediately (see page 2).

Cable Routing & Connecting

CAUTION: If the sensor came with a connector, do not remove it to ease cable routing. If the cable must be cut and spliced, use Airmar’s splash-proof Junction Box No. 33-035 and follow the instructions supplied. Removing the waterproof connector or cutting the cable, except when using a water-tight junction box, will void the sensor warranty.

1. Route the cable to the instrument being careful not to tear the cable jacket when passing it through the bulkhead(s) and other parts of the boat. Use grommet(s) to prevent chafing. To reduce electrical interference, separate the transducer cable from other electrical wiring and the engine. Coil any excess cable and secure it in place with cable ties to prevent damage.
2. Refer to the instrument owner’s manual to connect the transducer to the instrument.

Installation in a Cored Fiberglass Hull

The core (wood or foam) must be cut and sealed carefully. The core must be protected from water seepage, and the hull must be reinforced to prevent it from crushing under the hull nut allowing the sensor to become loose.

CAUTION: Completely seal the hull to prevent water seepage into the core.

1. Drill a 3 mm or 1/8" pilot hole from inside the hull. If there is a rib, strut, or other hull irregularity near the selected mounting location, drill from the outside. (If the hole is drilled in the wrong location, drill a second hole in a better location. Apply masking tape to the outside of the hull over the incorrect hole and fill it with epoxy.)
2. Using the 21 mm or 7/8" drill bit, cut a hole from outside the hull through the outer skin only (see Figure 2).
3. From inside the hull using the 30 mm or 1-1/4" hole saw, cut through the inner skin and most of the core. The core material can be very soft. Apply only light pressure to the hole saw after cutting through the inner skin to avoid accidentally cutting the outer skin.
4. Remove the plug of core material so the inside of the outer skin and the inner core of the hull is fully exposed. Clean and sand the inner skin, core, and the outer skin around the hole.
5. Coat a hollow or solid cylinder of the correct diameter with wax and tape it in place. Fill the gap between the cylinder and hull with casting epoxy. After the epoxy has set, remove the cylinder.
6. Sand and clean the area around the hole, inside and outside, to ensure that the sealant will adhere properly to the hull. If there is any petroleum residue inside the hull, remove it with either mild household detergent or a weak solvent (alcohol) before sanding.
7. Proceed with "Bedding" and "Installing" (see page 2).
Maintenance & Replacement
Aquatic growth can accumulate rapidly on the sensor’s surface reducing its performance within weeks. Clean the surface with a Scotch-Brite® scour pad and mild household detergent taking care to avoid making scratches. If the fouling is severe, lightly wet sand with fine grade wet/dry paper.

Anti-fouling Paint
Surfaces exposed to salt water must be coated with anti-fouling paint. Use water-based anti-fouling paint only. Never use ketone-based paint since ketones can attack many plastics possibly damaging the sensor. Reapply anti-fouling paint every 6 months or at the beginning of each boating season.

Replacement Sensor & Parts
The information needed to order a replacement sensor is printed on the cable tag. Do not remove this tag. When ordering, specify the part number and date. For convenient reference, record this information at the top of page one.

Lost, broken, or worn parts should be replaced immediately.

Hull nut 02-031-3

Obtain parts from your instrument manufacturer or marine dealer.

Gemeco
(USA) Tel: 803-693-0777
Fax: 803-693-0477
email: sales@gemeco.com

Airmar EMEA
(Europe, Middle East, Africa) Tel: +33,(0)2.23.52.06.48
Fax: +33,(0)2.23.52.06.49
email: sales@airmar-emea.com
Follow the precautions below for optimal product performance and to reduce the risk of property damage, personal injury, and/or death.

**WARNING:** Always wear safety goggles and a dust mask when installing.

**WARNING:** Below the waterline mount—When the boat is placed in the water, immediately check for leaks around the screws and any other holes drilled in the hull.

**CAUTION:** Installation on a metal hull—The stainless steel housing must be isolated from a metal hull to prevent electrolytic corrosion. Use marine sealant.

**CAUTION:** Never install a metal sensor on a vessel with a positive ground system.

**IMPORTANT:** Read the instructions completely before proceeding with the installation. These instructions supersede any other instructions in your instrument manual if they differ.

**Applications**

- Measures air or water temperature.
- Stainless steel sensor is compatible with all hull materials. Recommended for aluminum hulls to prevent electrolytic corrosion, provided the stainless steel sensor is isolated from the metal hull by using marine sealant.

**Mounting Location**

The sensor can be mounted anywhere that you want to know the temperature. For example, you can mount the sensor on the transom, in the live well, or in the engine compartment.

If you are measuring water temperature, choose a location where the sensor will be in contact with the water at all times.

**Tools & Materials**

- Safety goggles
- Dust mask
- Pencil
- Electric drill
- Drill bit/hole saw/spade bit:
  - Pilot holes: 3mm or 1/8"
  - Transom hole (some installations): 18mm or 3/4"
- 2 Stainless steel, self-tapping screws: 4 x 18mm or #8 x 3/4"
- Marine sealant (suitable for below waterline)
- Screwdriver(s)
- Cable clamp(s) (some installations)
- Grommet(s) (some installations)
- Cable ties

**Installation**

**Mounting on the transom**

**CAUTION:** Mount the sensor as close to the centerline (keel) of the boat as possible to ensure the sensor remains in the water when the boat is turning (see Figure 1).

**CAUTION:** Fiberglass hull—Minimize surface cracking by running the drill in reverse until the gelcoat is penetrated.

**CAUTION:** If the sensor came with a connector, do not remove it to ease cable routing. If the cable must be cut and spliced, use Airmar’s splash-proof Junction Box No. 33-035 and follow the instructions provided. Removing the waterproof connector or cutting the cable, except when using a water-tight junction box, will void the sensor warranty.

**Figure 1. Mounting on the transom**

Copyright © 2014 Airmar Technology Corp.
Mount the sensor near the centerline and close to the bottom of the transom.

Route the sensor cable over the transom, through a drain hole, or through a hole that you have drilled in the transom above the waterline.

1. Place the sensor against the hull and mark the position of the screw holes with a pencil.
2. Using a 3mm or 1/8" drill bit, drill pilot holes at the marked locations, 10mm (3/8") deep.
3. Apply marine sealant to the threads of the purchased screws to prevent water from seeping into the transom.
4. Screw the temperature sensor to the hull.
5. If a hole must be drilled through the transom, choose a location well above the waterline. Check for obstructions such as trim tabs, pumps, or wiring inside the hull. Mark the location with a pencil. Drill a hole through the transom using the appropriate size hole saw or spade bit (to accommodate the connector). Do NOT remove the connector.
6. Route the cable over or through the transom.
7. On the outside of the hull, secure the cable against the transom using a purchased cable clamp(s). Mark the position of the screw hole(s) with a pencil.
8. Using a 3mm or 1/8" drill bit, drill a pilot hole(s) at the marked locations, 10mm (3/8") deep.
9. Apply marine sealant to the threads of the screw(s) to prevent water from seeping into the transom.
10. Fasten the cable clamp(s) in place.
11. If a hole has been drilled through the transom, apply marine sealant to the space around the cable leading through the transom.

Cable Routing & Connecting

1. Route the cable to the instrument, being careful not to tear the cable jacket when passing it through the bulwark(s) and other parts of the boat. To reduce electrical interference, separate the sensor cable from other electrical wiring and sources of noise. Coil any excess cable and secure it in place with cable ties to prevent damage.
2. Refer to the instrument owner's manual to connect the sensor to the instrument.

Replacement Sensor & Parts

The information needed to order a replacement sensor is printed on the cable tag. Do not remove this tag. When ordering, specify the part number and date. For convenient reference, record this information at the top of page one.

Obtain parts from your instrument manufacturer or marine dealer.

Gemeco
Tel: 803-693-0777
Fax: 803-693-0477
email: sales@gemeco.com

Airmar EMEA
Tel: +33 (0)2.23.52.06.48
Fax: +33 (0)2.23.52.06.49
email: sales@airmar-emea.com
SPECIFICATIONS OF THE NETWORK SOUNDER
DFF1

1. GENERAL
1.1. Output Power  600 W/ 1 kW rms nominal, 1 kW requires optional MB-1100
1.2. TX Frequency  50 kHz or 200 kHz, 50/200 kHz exchangeable
1.3. Amplifier type  Wide dynamic linear amp (double superheterodyne)
1.4. Network protocol  Ethernet 100/10BASE-TX
1.5. Depth Range and Pulse Repetition Rate

<table>
<thead>
<tr>
<th>Range (m)</th>
<th>PRR ( /min.)</th>
</tr>
</thead>
<tbody>
<tr>
<td>2</td>
<td>3000</td>
</tr>
<tr>
<td>5</td>
<td>3000</td>
</tr>
<tr>
<td>10</td>
<td>1990</td>
</tr>
<tr>
<td>40</td>
<td>485</td>
</tr>
<tr>
<td>100</td>
<td>195</td>
</tr>
<tr>
<td>200</td>
<td>95</td>
</tr>
<tr>
<td>400</td>
<td>65</td>
</tr>
<tr>
<td>1200</td>
<td>34</td>
</tr>
</tbody>
</table>

2. POWER SUPPLY
12-24 VDC: 1.1-0.4 A (at 1 kW output)

3. ENVIRONMENTAL CONDITION
3.1. Ambient Temperature  -15°C to +55°C
3.2. Relative Humidity  93% at 40°C
3.3. Dustproofing, waterproofing  IP20 (not waterproof)
3.4. Vibration (IEC 60945 Ed4)  
- 2-5 Hz and up to 13.2 Hz with an excursion of ±1 mm ±10 %  (7 m/s² maximum acceleration at 13.2 Hz)
- 13.2-100 Hz with a constant maximum acceleration of 7 m/s²

4. COATING COLOR
4.1. Main Unit  N3.0
<table>
<thead>
<tr>
<th>NAME</th>
<th>OUTLINE</th>
<th>DESCRIPTION/ CODE No.</th>
<th>Q'TY</th>
</tr>
</thead>
</table>
| （ユニット）ネットワーク魚探 | | DFF1  
| NETWORK SOUNDER | 219 x 90 x 255 mm | 000-010-154-00 | 1 |
| 予備品ヒューズ | | GLASS TUBE FUSE  
| SPARE PARTS | 30 mm | F6B0-A 125V 3A PBF | 2 |
| 工事材料ケーブル（組品）LAN | | INSTALLATION MATERIALS  
| CP02-08100 | | MOD-Z072-050+ | 1 |
| LAN CABLE ASSEMBLY | L=5M | 001-167-890-10 |
| ケーブル組品MJ | | POWER CABLE ASSY. | 1 |
| POWER CABLE ASSY. | L=3.5M | MJ-A3SP0028-035G | 1 |
| トランスステージ 1個 | | SELF-TAPPING SCREW | 4 |
| SELF-TAPPING SCREW | 20 x 4 mm | 4X20 SUS304 | 4 |
| 図書 取扱説明書 | | DOCUMENT | 1 |
| OPERATOR’S MANUAL | | | 1 |

コード番号末尾の[**]は、選択品の代表コードを表します。
CODE NUMBER ENDING WITH "**" INDICATES THE CODE NUMBER OF REPRESENTATIVE MATERIAL.

型式/コード番号が2段の場合、下段より上段に代わる通達用品であり、どちらかが入っています。なお、品質は変わりません。
TWO TYPES AND CODES MAY BE LISTED FOR AN ITEM. THE LOWER PRODUCT MAY BE SHIPPED IN PLACE OF THE UPPER PRODUCT. QUALITY IS THE SAME.

（略図の寸法は、参考値です。DIMENSIONS IN DRAWING FOR REFERENCE ONLY.）
### 表 1 TABLE 1

<table>
<thead>
<tr>
<th>寸法区分 (mm)</th>
<th>公差 (mm)</th>
</tr>
</thead>
<tbody>
<tr>
<td>L ≤ 50</td>
<td>±1.5</td>
</tr>
<tr>
<td>50 &lt; L ≤ 100</td>
<td>±2.5</td>
</tr>
<tr>
<td>100 &lt; L ≤ 500</td>
<td>±3</td>
</tr>
</tbody>
</table>

注記 1) 取付穴は最小サービス空間寸法をもとする。
2) 指定外の寸法公差は表1による。
3) 取付用ネジはトランスステインネジ呼び径4×20を使用のこと。

NOTE 1. MINIMUM SERVICE CLEARANCE.
2. TABLE 1 INDICATES TOLERANCE OF DIMENSIONS WHICH IS NOT SPECIFIED.
3. USE SELF-TAPPING SCREWS 4x20 FOR FIXING THE UNIT.

<table>
<thead>
<tr>
<th>DRAM</th>
<th>E. MIYOSHI</th>
</tr>
</thead>
<tbody>
<tr>
<td>DATED</td>
<td>9/07</td>
</tr>
<tr>
<td>DESIGNED</td>
<td>TAKAHASHI, T</td>
</tr>
<tr>
<td>APPROVED</td>
<td>Y. Hatai</td>
</tr>
<tr>
<td>SCALE</td>
<td>1/3</td>
</tr>
<tr>
<td>MASS</td>
<td>1.2 ±10kg</td>
</tr>
<tr>
<td>NAME</td>
<td>NETWORK SOUNDER</td>
</tr>
<tr>
<td>NO.</td>
<td>C2036-G01-B</td>
</tr>
</tbody>
</table>

FURUNO ELECTRIC CO., LTD.
注記
1) 指定外の寸法公差は表1による。
2) く印寸法は最小サービス空間寸法とする。
3) 取付にはタップネジ呼び4を使用のこと。

NOTE
1. TABLE 1 INDICATES TOLERANCE OF DIMENSIONS WHICH IS NOT SPECIFIED.
2. #: MINIMUM SERVICE CLEARANCE.
3. USE TAPPING SCREWS Ø4 FOR FIXING THE UNIT.
注記
* 1) 造船所手配。
* 2) オプション。
* 3) 工場にて取付済み。
* 4) DFF1のジャンバー設定変更が必要。
* 5) DFF1のDIPスイッチ設定変更が必要。

NOTE
*1: SHIPYARD SUPPLY.
*2: OPTION.
*3: FITTED AT FACTORY.
*4: CHANGE JUMPER SETTING OF DFF1.
*5: CHANGE DIP SWITCH SETTING OF DFF1.

DRAWN: 13/Dec/2016 T. YAMASAKI
CHECKED: 13/Dec/2016 H. MAKI
APPROVED: 14/Dec/2016 H. MAKI

NAME: NETWORK SOUNDER
NAME: NETWORK SOUNDER

REF. NO.: 02-158-1001-3
FURUNO Worldwide Warranty for Pleasure Boats (Except North America)

This warranty is valid for products manufactured by Furuno Electric Co. (hereafter FURUNO) and installed on a pleasure boat. Any web based purchases that are imported into other countries by anyone other than a FURUNO certified dealer may not comply with local standards. FURUNO strongly recommends against importing these products from international websites as the imported product may not work correctly and may interfere with other electronic devices. The imported product may also be in breach of the local laws and mandated technical requirements. Products imported into other countries as described previously shall not be eligible for local warranty service.

For products purchased outside of your country please contact the national distributor of Furuno products in the country where purchased.

This warranty is in addition to the customer’s statutory legal rights.

1. Terms and Conditions of Warranty

FURUNO guarantees that each new FURUNO product is the result of quality materials and workmanship. The warranty is valid for a period of 2 years (24 months) from the date of the invoice, or the date of commissioning of the product by the installing certified dealer.

2. FURUNO Standard Warranty

The FURUNO standard warranty covers spare parts and labour costs associated with a warranty claim, provided that the product is returned to a FURUNO national distributor by prepaid carrier.

The FURUNO standard warranty includes:

- Repair at a FURUNO national distributor
- All spare parts for the repair
- Cost for economical shipment to customer

3. FURUNO Onboard Warranty

If the product was installed/commissioned and registered by a certified FURUNO dealer, the customer has the right to the onboard warranty.

The FURUNO onboard warranty includes

- Free shipping of the necessary parts
- Labour: Normal working hours only
- Travel time: Up to a maximum of two (2) hours
- Travel distance: Up to a maximum of one hundred and sixty (160) KM by car for the complete journey

4. Warranty Registration

For the Standard Warranty - presentation of product with serial number (8 digits serial number, 1234-5678) is sufficient. Otherwise, the invoice with serial number, name and stamp of the dealer and date of purchase is shown.

For the Onboard Warranty your FURUNO certified dealer will take care of all registrations.

5. Warranty Claims

For the Standard Warranty - simply send the defective product together with the invoice to a FURUNO national distributor. For the Onboard Warranty – contact a FURUNO national distributor or a certified dealer. Give the product’s serial number and describe the problem as accurately as possible.

Warranty repairs carried out by companies/persons other than a FURUNO national distributor or a certified dealer is not covered by this warranty.

6. Warranty Limitations

When a claim is made, FURUNO has a right to choose whether to repair the product or replace it.

The FURUNO warranty is only valid if the product was correctly installed and used. Therefore, it is necessary for the customer to comply with the instructions in the handbook. Problems which result from not complying with the instruction manual are not covered by the warranty.

FURUNO is not liable for any damage caused to the vessel by using a FURUNO product.

The following are excluded from this warranty:

a. Second-hand product
b. Underwater unit such as transducer and hull unit
c. Routine maintenance, alignment and calibration services.
d. Replacement of consumable parts such as fuses, lamps, recording papers, drive belts, cables, protective covers and batteries.
e. Magnetron and MIC with more than 1000 transmitting hours or older than 12 months, whichever comes first.
f. Costs associated with the replacement of a transducer (e.g. Crane, docking or diver etc.).
g. Sea trial, test and evaluation or other demonstrations.
h. Products repaired or altered by anyone other than the FURUNO national distributor or an authorized dealer.
i. Products on which the serial number is altered, defaced or removed.
j. Problems resulting from an accident, negligence, misuse, improper installation, vandalism or water penetration.
k. Damage resulting from a force majeure or other natural catastrophe or calamity.
l. Damage from shipping or transit.
m. Software updates, except when deemed necessary and warrantable by FURUNO.
n. Overtime, extra labour outside of normal hours such as weekend/holiday, and travel costs above the 160 KM allowance

FURUNO Electric Company, March 1, 2011
FURUNO Warranty for North America

FURUNO U.S.A., Limited Warranty provides a twenty-four (24) months LABOR and twenty-four (24) months PARTS warranty on products from the date of installation or purchase by the original owner. Products or components that are represented as being waterproof are guaranteed to be waterproof only for, and within the limits, of the warranty period stated above. The warranty start date may not exceed eighteen (18) months from the original date of purchase by dealer from Furuno USA and applies to new equipment installed and operated in accordance with Furuno USA’s published instructions.

Magnetrons and Microwave devices will be warranted for a period of 12 months from date of original equipment installation.

Furuno U.S.A., Inc. warrants each new product to be of sound material and workmanship and through its authorized dealer will exchange any parts proven to be defective in material or workmanship under normal use at no charge for a period of 24 months from the date of installation or purchase.

Furuno U.S.A., Inc., through an authorized Furuno dealer will provide labor at no cost to replace defective parts, exclusive of routine maintenance or normal adjustments, for a period of 24 months from installation date provided the work is done by Furuno U.S.A., Inc. or an AUTHORIZED Furuno dealer during normal shop hours and within a radius of 50 miles of the shop location.

A suitable proof of purchase showing date of purchase, or installation certification must be available to Furuno U.S.A., Inc., or its authorized dealer at the time of request for warranty service.

This warranty is valid for installation of products manufactured by Furuno Electric Co. (hereafter FURUNO). Any purchases from brick and mortar or web-based resellers that are imported into other countries by anyone other than a FURUNO certified dealer, agent or subsidiary may not comply with local standards. FURUNO strongly recommends against importing these products from international websites or other resellers, as the imported product may not work correctly and may interfere with other electronic devices. The imported product may also be in breach of the local laws and mandated technical requirements. Products imported into other countries, as described previously, shall not be eligible for local warranty service.

For products purchased outside of your country please contact the national distributor of Furuno products in the country where purchased.

WARRANTY REGISTRATION AND INFORMATION
To register your product for warranty, as well as see the complete warranty guidelines and limitations, please visit www.furunousa.com and click on “Support”. In order to expedite repairs, warranty service on Furuno equipment is provided through its authorized dealer network. If this is not possible or practical, please contact Furuno U.S.A., Inc. to arrange warranty service.

FURUNO U.S.A., INC.
Attention: Service Coordinator
4400 N.W. Pacific Rim Boulevard
Camas, WA 98607-9408
Telephone: (360) 834-9300
FAX: (360) 834-9400

Furuno U.S.A., Inc. is proud to supply you with the highest quality in Marine Electronics. We know you had several choices when making your selection of equipment, and from everyone at Furuno we thank you. Furuno takes great pride in customer service.
EC Declaration of Conformity

We, FURUNO ELECTRIC CO., LTD.

(Manufacturer)

9-52 Ashihara-Cho, Nishinomiya City, 662-8580, Hyogo, Japan

(Address)

declare under our sole responsibility that the product

NETWORK SOUNDER DFF1

(Model name, type number)

to which this declaration relates is in conformity with the following standard(s) or other normative document(s)

IEC 60945 Ed.4.0: 2002, clauses 9.2, 9.3, 10.3, 10.4, 10.5, 10.8 and 10.9
IEC 60945 Ed.3.0: 1996, clauses 10.2 and 10.3

(title and/or number and date of issue of the standard(s) or other normative document(s))

For assessment, see

• EMC Test Report FLI 12-06-062, December 11, 2006 prepared by Furuno Labotech International Co., Ltd.

This declaration is issued according to the Directive 2014/30/EU of the European Parliament and of the Council of 26 February 2014 on the harmonisation of the laws of the Member States relating to electromagnetic compatibility.

On behalf of Furuno Electric Co., Ltd.

Yoshitaka Shogaki
Department General Manager
Quality Assurance Department

Nishinomiya City, Japan
April 20, 2016

(Place and date of issue)

(name and signature or equivalent marking of authorized person)
FURUNO ELECTRIC CO., LTD.
9-52, Ashihara-cho,
Nishinomiya, 662-8580, JAPAN

<table>
<thead>
<tr>
<th>All rights reserved</th>
<th>Printed in Japan</th>
</tr>
</thead>
</table>

Pub. No. OME-20360-K4
(YOSH) DFF1

FURUNO Authorized Distributor/Dealer

A: FEB. 2007
K4: DEC. 17, 2019

Printed in Japan

Pub. No. OME-20360-K4
(YOSH) DFF1

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K4: DEC. 17, 2019

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